# Phasor

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## Phase Lags and Leads

$$\frac{d}{dx} f(x) = \cos(x) \qquad leads \qquad f(x) = \sin(x)$$

$$\frac{d}{dx} f(x) = -\sin(x) \qquad leads \qquad f(x) = \cos(x)$$

$$\int f(x) dx = -\cos(x) + C \quad lags \quad f(x) = \sin(x)$$

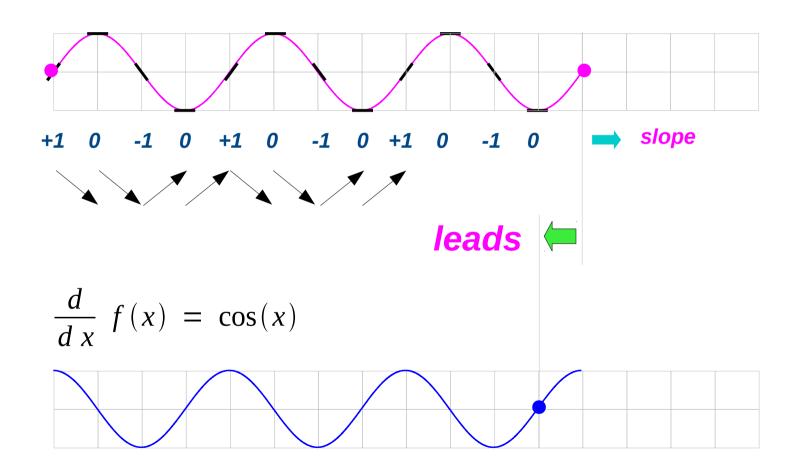
$$\int f(x) dx = \sin(x) + C \qquad lags \qquad f(x) = \cos(x)$$

$$\frac{d}{dx} f(x) \quad \text{leads} \quad f(x) \quad \text{by} \quad \frac{\pi}{2}$$

$$\int f(x) dx \quad \text{lags} \quad f(x) \quad \text{by} \quad \frac{\pi}{2}$$

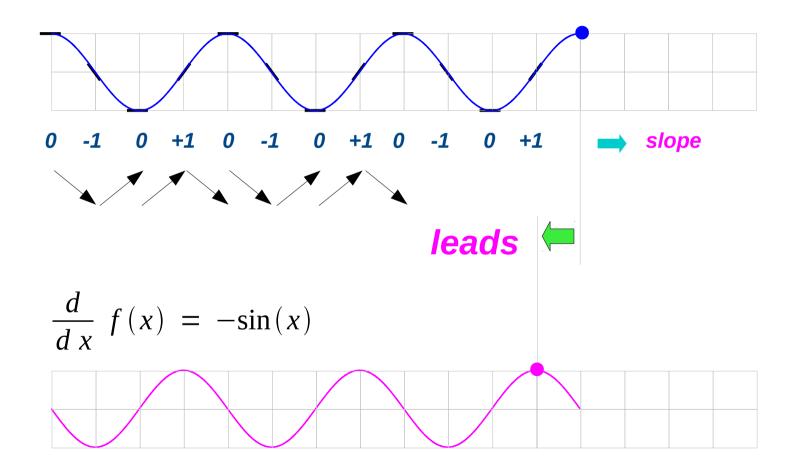
# Derivative of sin(x)

$$f(x) = \sin(x)$$



## Derivative of cos(x)

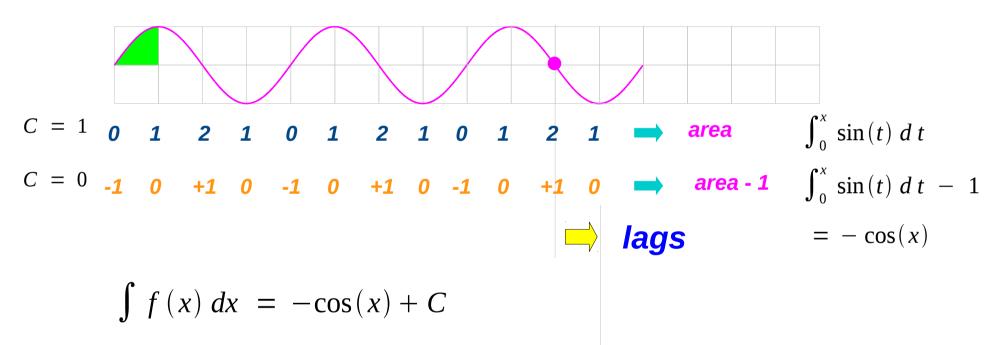
$$f(x) = \cos(x)$$

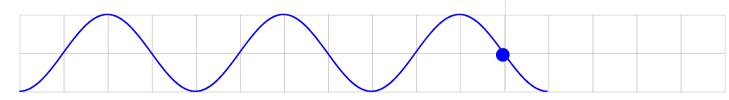


# Integral of sin(x)

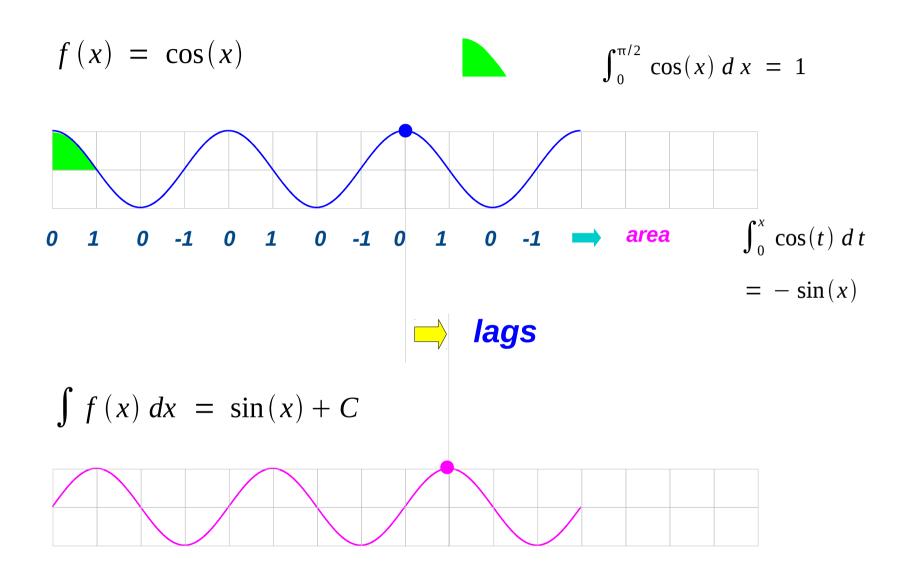
$$f(x) = \sin(x)$$

$$\int_0^{\pi/2} \sin(t) dt = 1$$

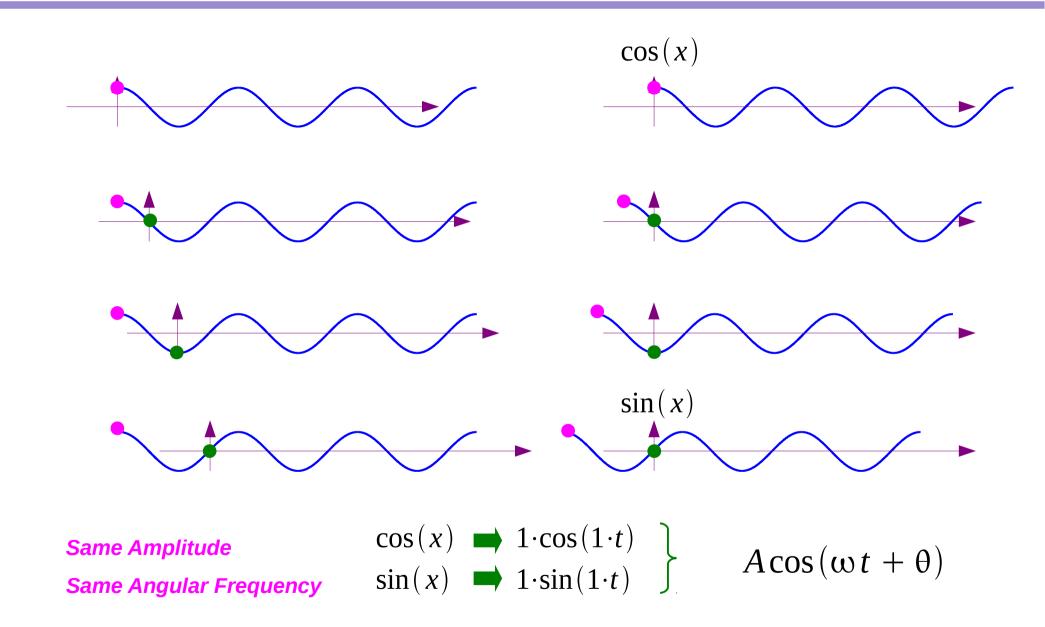




# Integral of cos(x)



## Sinusoid



### Phasor

### Sinusoid (Sine Waves)

$$A\cos(\omega t + \theta)$$

$$\begin{cases} Amplitude & A \\ Angular Frequency & \omega \\ Angle at t = 0 & \theta \end{cases}$$

### 1. Representation using Euler's Formula

$$A\cos(\omega t + \theta) = \frac{A}{2} \cdot e^{+i(\omega t + \theta)} + \frac{A}{2} \cdot e^{-i(\omega t + \theta)}$$

### 2. Representation using Real Part

$$A\cos(\omega t + \theta) = Re\{Ae^{i(\omega t + \theta)}\} = Re\{Ae^{i\theta} \cdot e^{i\omega t}\}$$

$$\Rightarrow Ae^{i\theta} \cdot e^{i\omega t}$$

$$\Rightarrow Ae^{i\theta}$$

$$\Rightarrow A \angle \theta$$

## Phasor

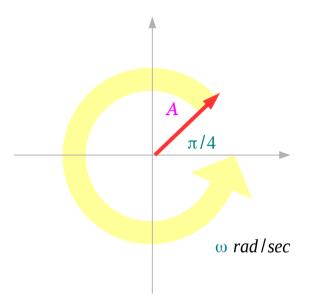
$$A\cos(\omega t + \theta)$$

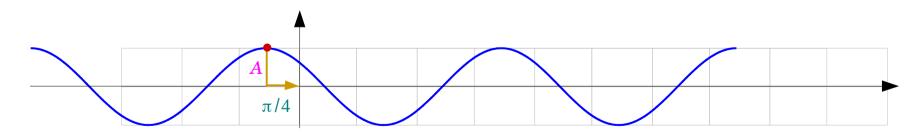
$$A\cos(\omega t + \theta) = \Re\{Ae^{i(\omega t + \theta)}\}\$$

$$= \Re\{e^{i\omega t} \cdot Ae^{i\theta}\}$$

$$\rightarrow Ae^{i\theta} = A\cos\theta + jA\sin\theta$$

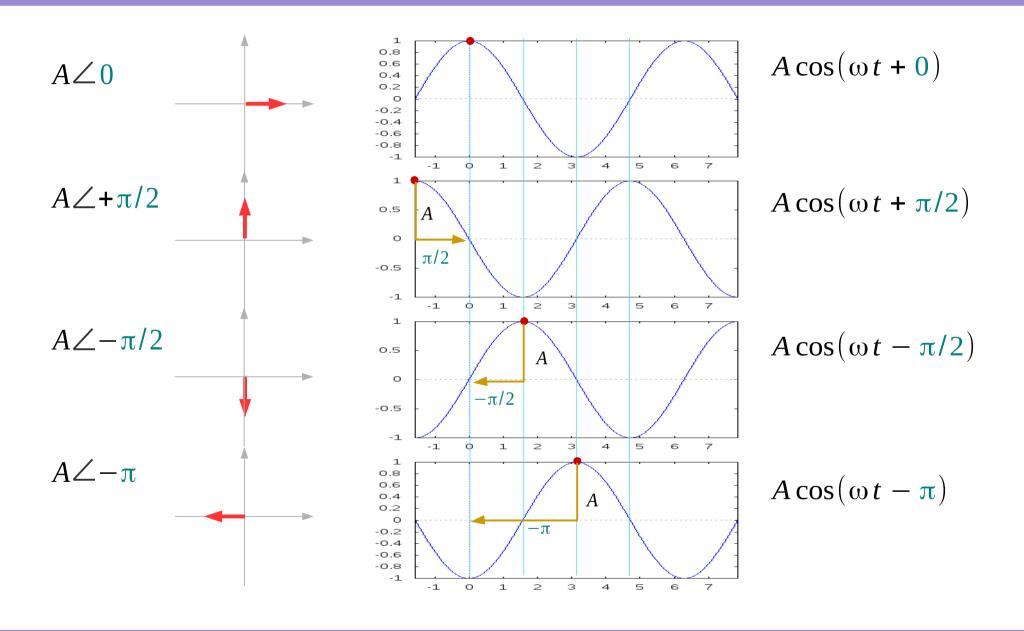
 $\rightarrow$   $A \angle \theta$ 



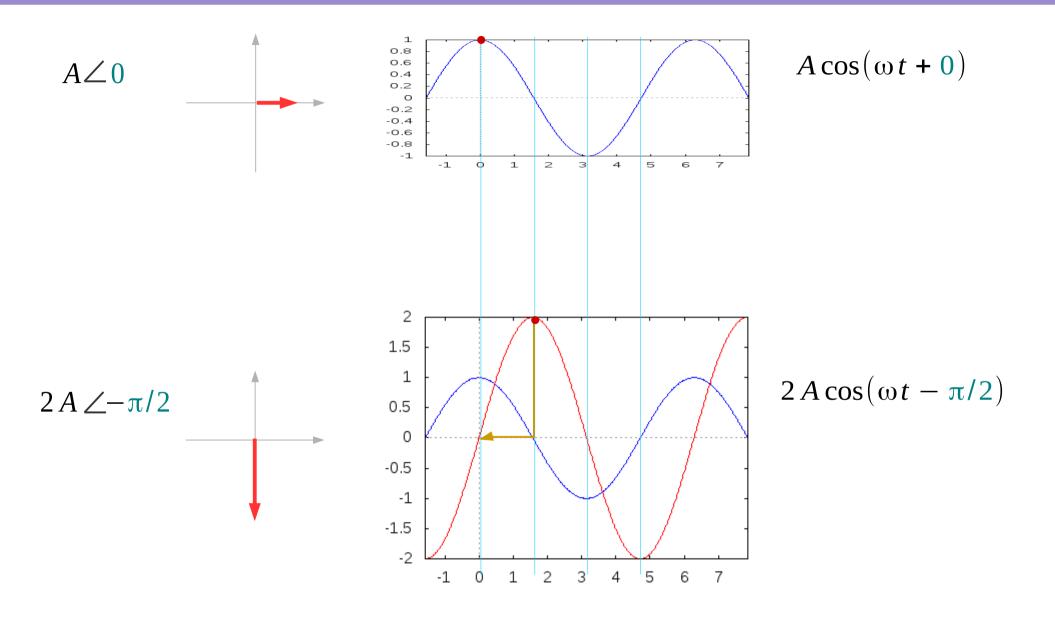


 $\boldsymbol{A}$ 

# Phasor Example (1)



# Phasor Example (2)



### Phasor

$$A\cos(\omega t + \theta)$$

$$= A\cos(\omega t)\cos(\theta) - A\sin(\omega t)\sin(\theta)$$

$$= A\cos(\theta)\cos(\omega t) - A\sin(\theta)\sin(\omega t)$$

$$= X\cos(\omega t) - Y\sin(\omega t)$$

$$A\cos(\theta) = X$$

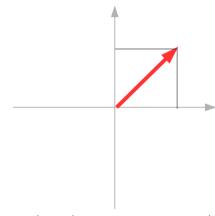
$$A\sin(\theta) = Y$$

$$A = \sqrt{X^2 + Y^2}$$
$$\tan \theta = \frac{Y}{X}$$

$$\theta > 0$$
 leading

$$\theta < 0$$
 lagging

$$A \angle \theta$$



$$(X, Y) = (A\cos\theta, A\sin\theta)$$

$$X + jY = A\cos\theta + jA\sin\theta$$

# Linear Combination of $cos(\omega t)$ & $sin(\omega t)$

### $X\cos(\omega t) + Y\sin(\omega t)$

$$\begin{split} &X\cos(\omega t) + Y\sin(\omega t) \\ &= \sqrt{X^2 + Y^2} \Big[ \frac{x}{\sqrt{X^2 + Y^2}} \cos(\omega t) + \frac{Y}{\sqrt{X^2 + Y^2}} \sin(\omega t) \Big] \\ &= \sqrt{X^2 + Y^2} \Big[ \cos(\theta) \cos(\omega t) + \sin(\theta) \sin(\omega t) \Big] \\ &= \sqrt{X^2 + Y^2} \cos(\theta - \omega t) \\ &= \sqrt{X^2 + Y^2} \cos(\omega t - \theta) \end{split}$$

$$X\cos(\omega t) - Y\sin(\omega t)$$

$$\sqrt{X^2+Y^2}\cos(\omega t-\theta)$$

$$X\cos(\omega t) + Y\sin(\omega t)$$

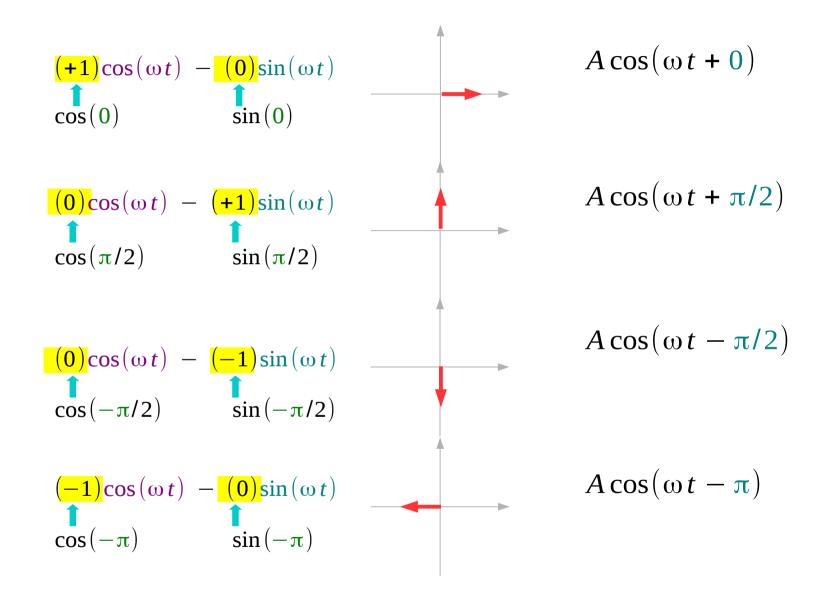
$$= \sqrt{X^2 + Y^2}\cos(\omega t - \theta)$$

$$\cos(\theta) = \frac{X}{\sqrt{X^2 + Y^2}}$$

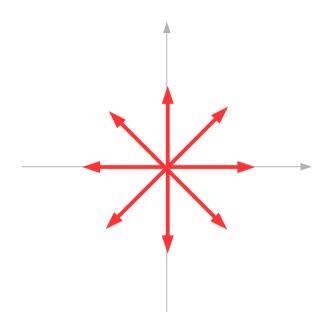
$$\sin(\theta) = \frac{Y}{\sqrt{X^2 + Y^2}}$$

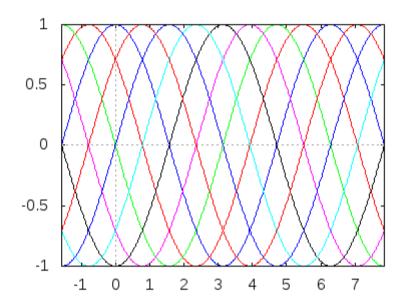
$$\sqrt{X^2+Y^2}\cos(\omega t+\theta)$$

# Phasor as a starting point

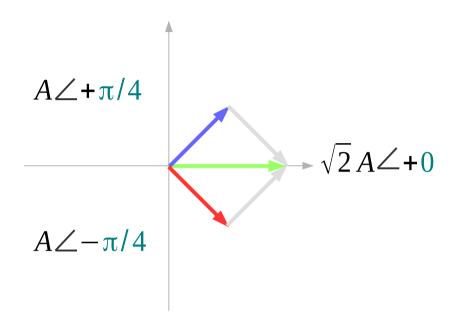


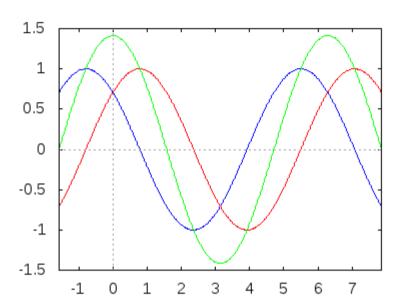
# Phase Angles



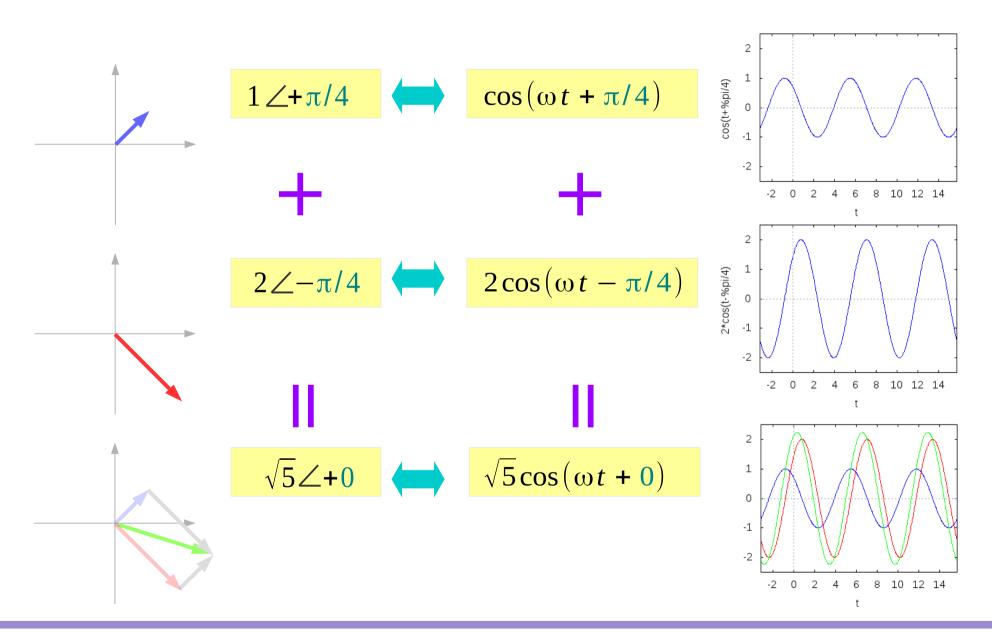


## **Phasor Arithmetic**





## **Phasor Addition**



### Phasor Addition Rule

$$x(t) = \sum_{k=1}^{N} A_k \cos(\omega t + \theta_k)$$
$$= A \cos(\omega t + \theta)$$

### adding complex numbers

$$\sum_{k=1}^{N} A_k e^{j(\theta_k)} = A e^{j\theta}$$

a complex number

$$= \sum_{k=1}^{N} \Re \{A_{k}e^{j(\omega t + \theta_{k})}\}$$

$$= \Re \{\sum_{k=1}^{N} A_{k}e^{j(\omega t)}e^{j(\theta_{k})}\}$$

$$= \Re \{\sum_{k=1}^{N} A_{k}e^{j\theta_{k}}e^{j(\omega t)}\}$$

$$= \Re \{\sum_{k=1}^{N} A_{k}e^{j\theta_{k}}e^{j(\omega t)}\}$$

$$= \Re \{\sum_{k=1}^{N} Ae^{j\theta}e^{j(\omega t)}\}$$

$$= \Re \{\sum_{k=1}^{N} Ae^{j(\omega t + \theta)}\}$$

$$= A\cos(\omega t + \theta)$$

# Phasor Multiplication & Division

$$x(t) = A_1 \cos(\omega t + \theta_1) = \Re\{A_1 e^{j(\omega t + \theta_1)}\}$$
$$y(t) = A_2 \cos(\omega t + \theta_2) = \Re\{A_2 e^{j(\omega t + \theta_2)}\}$$

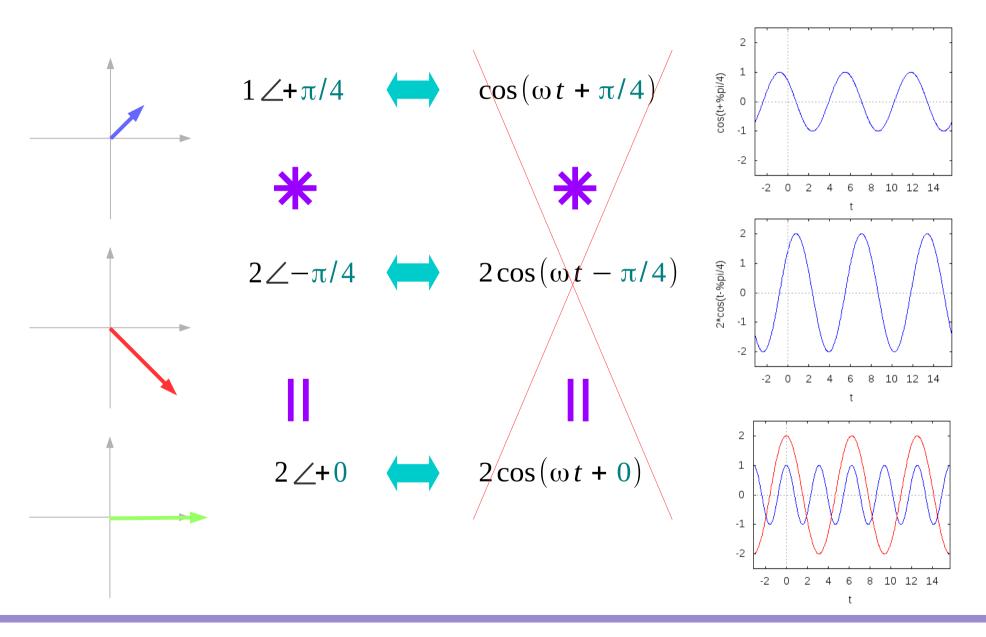
$$x(t)*y(t) = A_1 A_2 \cos(\omega t + \theta_1) \cos(\omega t + \theta_2)$$

$$= \Re\{A_1 A_2 e^{j(2\omega t + \theta_1 + \theta_2)}\}$$
 different angular frequency!

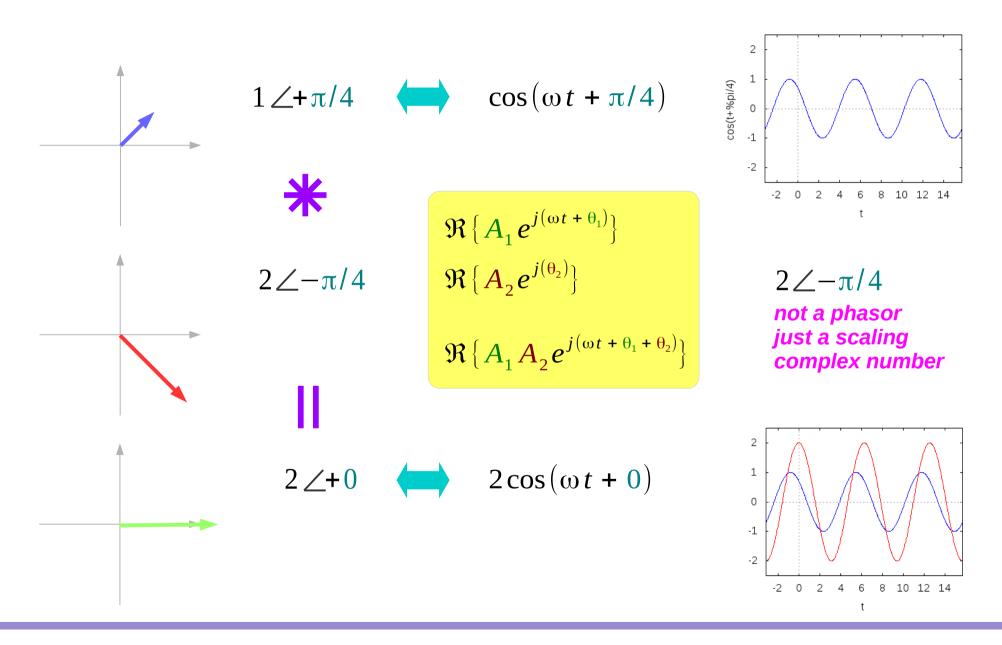
$$\frac{x(t)}{y(t)} = \frac{A_1}{A_2} \frac{\cos(\omega t + \theta_1)}{\cos(\omega t + \theta_2)}$$

$$= \Re\left\{\frac{A_1}{A_2} e^{j(\theta_1 - \theta_2)}\right\}$$
no more rotating!

# **Phasor Multiplication**



# **Phasor Scaling**



# **Vector Space**

#### V: non-empty <u>set</u> of objects

defined operations: addition  $\mathbf{u} + \mathbf{v}$ 

scalar multiplication  $k \mathbf{u}$ 

if the following axioms are satisfied for all object  $\mathbf{u}$ ,  $\mathbf{v}$ ,  $\mathbf{w}$  and all scalar k, m

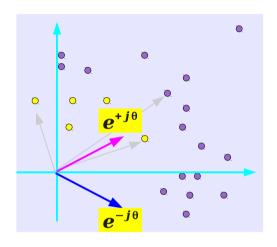


V: vector space

objects in V: vectors

- 1. if  $\mathbf{u}$  and  $\mathbf{v}$  are objects in  $\mathbf{V}$ , then  $\mathbf{u} + \mathbf{v}$  is in  $\mathbf{V}$
- 2. u + v = v + u
- 3. u + (v + w) = (u + v) + w
- 4. 0 + u = u + 0 = u (zero vector)
- 5.  $\mathbf{u} + (-\mathbf{u}) = (-\mathbf{u}) + (\mathbf{u}) = \mathbf{0}$
- 6. if k is any scalar and  $\mathbf{u}$  is objects in  $\mathbf{V}$ , then  $k\mathbf{u}$  is in  $\mathbf{V}$
- 7. k(u + v) = ku + kv
- 8. (k + m)u = ku + mu
- 9. k(mu) = (km)u
- 10. 1(u) = u

### **Basis**: a set of linear independent spanning vectors



 $j\sin\theta$ 

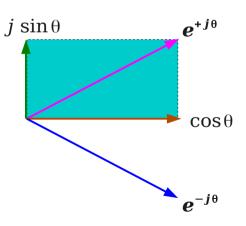
every complex number can be represented by

$$\begin{bmatrix} k_1 \end{bmatrix} e^{+j\theta} + \begin{bmatrix} k_2 \end{bmatrix} e^{+j\theta}$$

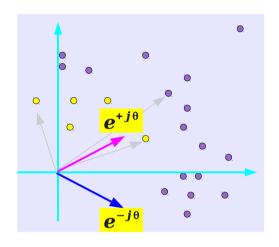
linear combination of  $e^{+j\theta}$  and  $e^{+j\theta}$  which are one set of linear independent two vectors

every complex number can also be represented by

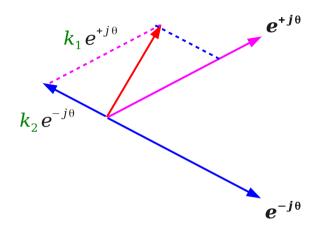
$$\boxed{l_1 \cos\theta + l_2 j \sin\theta}$$

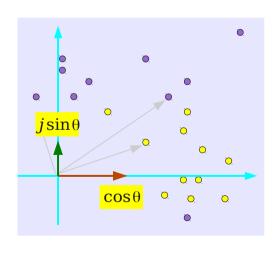


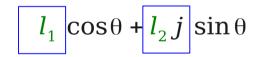
### **Basis**: a set of linear independent spanning vectors

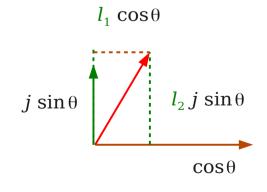


$$\begin{bmatrix} k_1 \end{bmatrix} e^{+j\theta} + \begin{bmatrix} k_2 \end{bmatrix} e^{+j\theta}$$









# C<sup>1</sup> and R<sup>2</sup> Spaces

$$c_1 e^{+i\omega t} + c_2 e^{-i\omega t}$$



$$c_3 \cos(\omega t) + c_4 i \sin(\omega t)$$

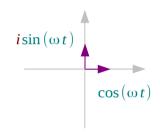
$$c_1 = (c_3 + c_4)/2$$
  
 $c_2 = (c_3 - c_4)/2$ 

real number real number

$$c_3 = (c_1 + c_2)$$
  
 $c_4 = (c_1 - c_2)$ 

real number real number

 $C^1$ 



$$c_1 e^{+i\omega t} + c_2 e^{-i\omega t}$$

$$c_1 = (c_3 - c_4 i)/2$$
  
 $c_2 = (c_3 + c_4 i)/2$ 

conjugate complex number



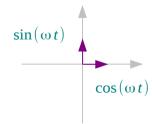
 $c_3 \cos(\omega t) + c_4 \sin(\omega t)$ 

+2\*real part

$$c_3 = (c_1 + c_2)$$
  
 $c_4 = i(c_1 - c_2)$ 

real number





## Linear Combination of cos(ωt) & sin(ωt)

$$X\cos(\omega t) + Y\sin(\omega t)$$

$$X\cos(\omega t) - Y\sin(\omega t)$$

$$\sqrt{X^2+Y^2}\cos(\omega t-\theta)$$

$$\sqrt{X^2+Y^2}\cos(\omega t+\theta)$$

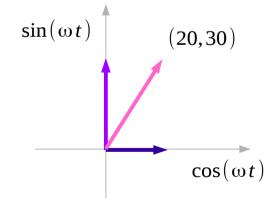
$$20\cos(\omega t) + 30\sin(\omega t)$$

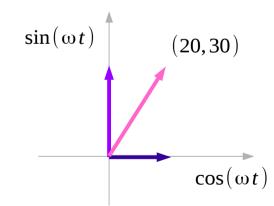
$$20\cos(\omega t) - 30\sin(\omega t)$$

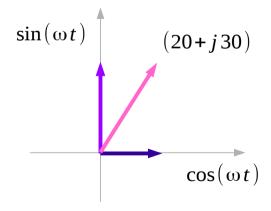
$$36.06\cos(\omega t - 0.588)$$

$$36.06\cos(\omega t + 0.588)$$

 $36.06 \angle 0.588$ 







### References

- [1] http://en.wikipedia.org/
- [2] J.H. McClellan, et al., Signal Processing First, Pearson Prentice Hall, 2003