

Planar Graph (7A)

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Planar Graph




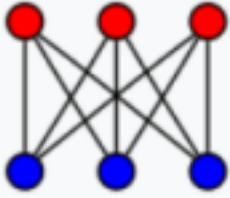
a planar graph is a graph that can be embedded in the plane, i.e., it can be drawn on the plane in such a way that its edges intersect only at their endpoints.

it can be drawn in such a way that no edges cross each other. Such a drawing is called a **plane graph** or **planar embedding** of the graph. (**planar representation**)

A **plane graph** can be defined as a planar graph with a mapping from every node to a point on a plane, and from every edge to a plane curve on that plane, such that the extreme points of each curve are the points mapped from its end nodes, and all curves are disjoint except on their extreme points.

https://en.wikipedia.org/wiki/Planar_graph

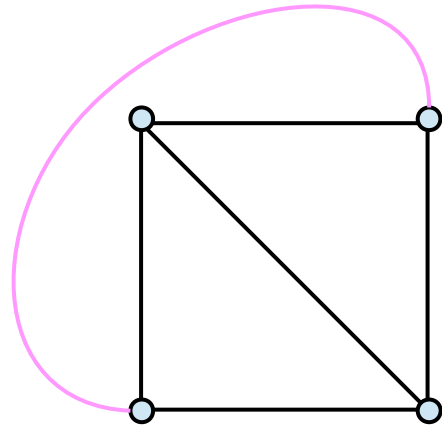
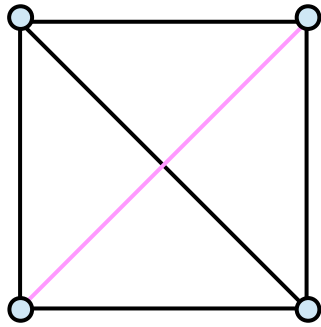
Planar Graph Examples

Example graphs	
Planar	Nonplanar
 <p>Butterfly graph</p>	 <p>Complete graph K_5</p>
 <p>Complete graph K_4</p>	 <p>Utility graph $K_{3,3}$</p>

https://en.wikipedia.org/wiki/Planar_graph

Planar Representation

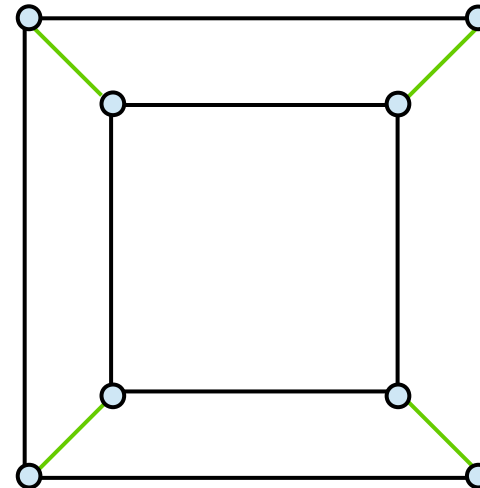
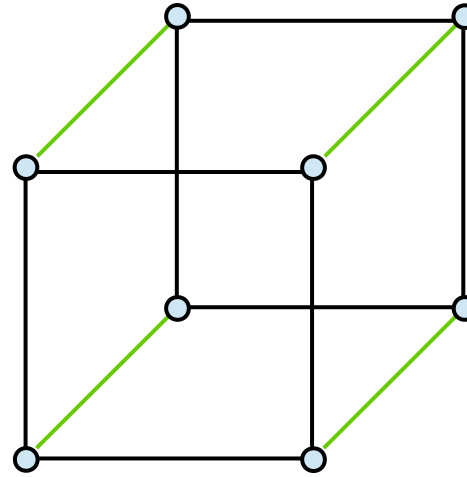
K_4



No crossing
 K_4 Planar

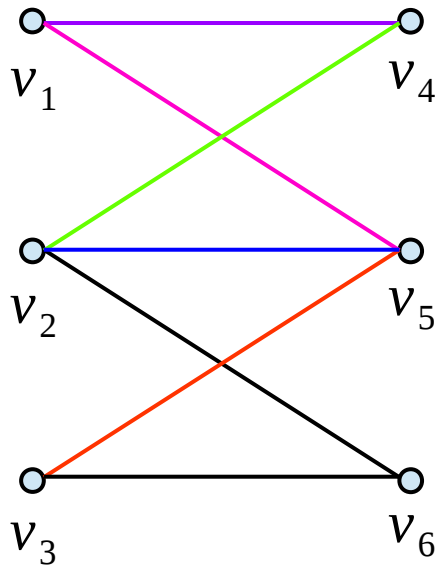
Discrete Mathematics, Rosen

Q_3

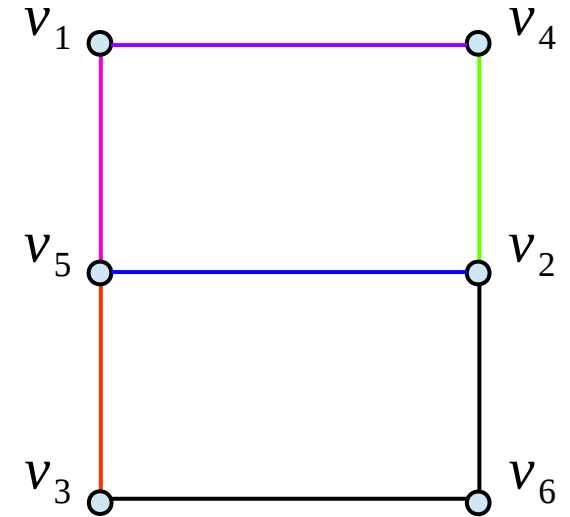
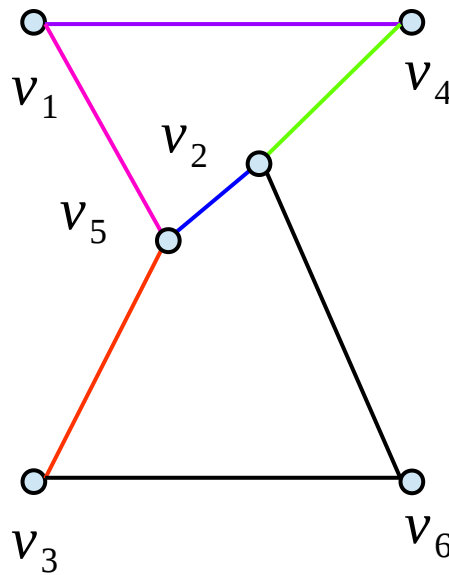


No crossing
 Q_3 Planar

A planar bipartite graph

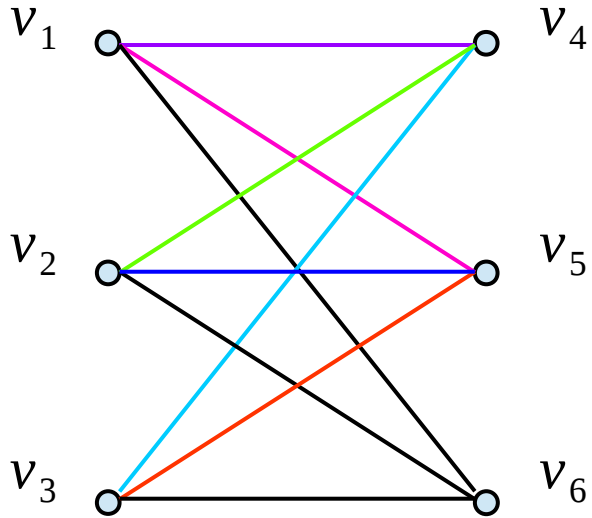


Bipartite graph
but not complete
bipartite graph
 $K_{3,3}$

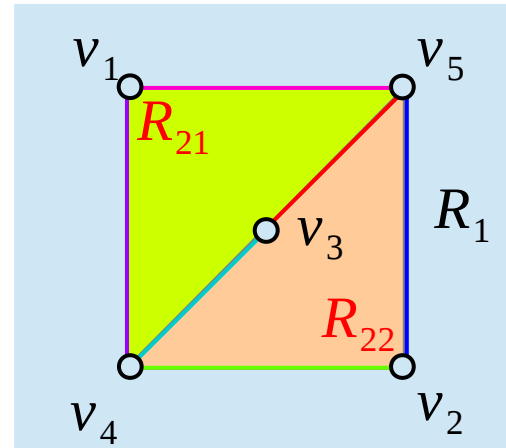
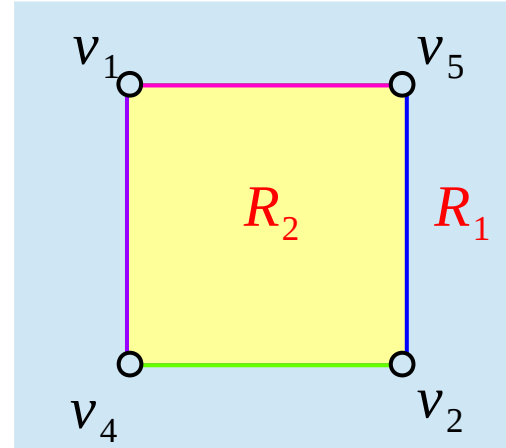


Planar Graph

Non-planar Graph $K_{3,3}$

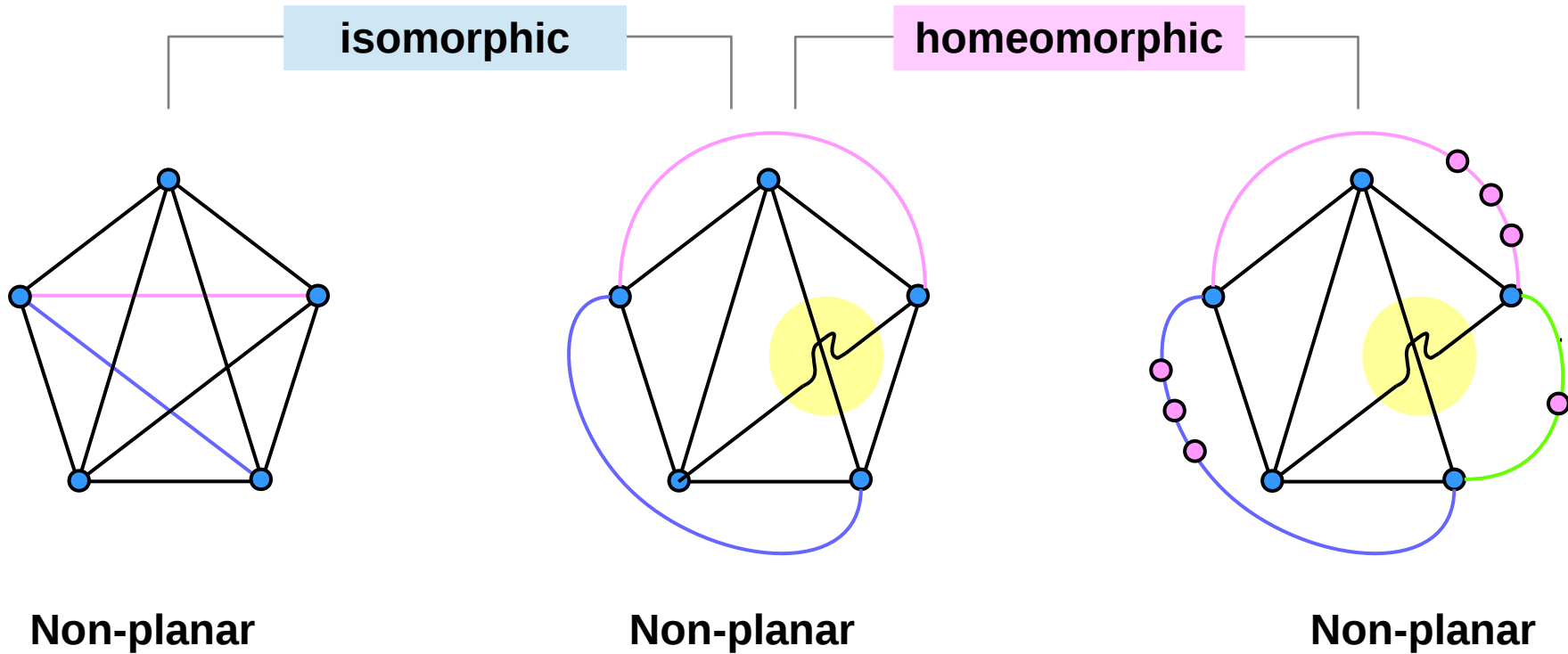


no where v_6



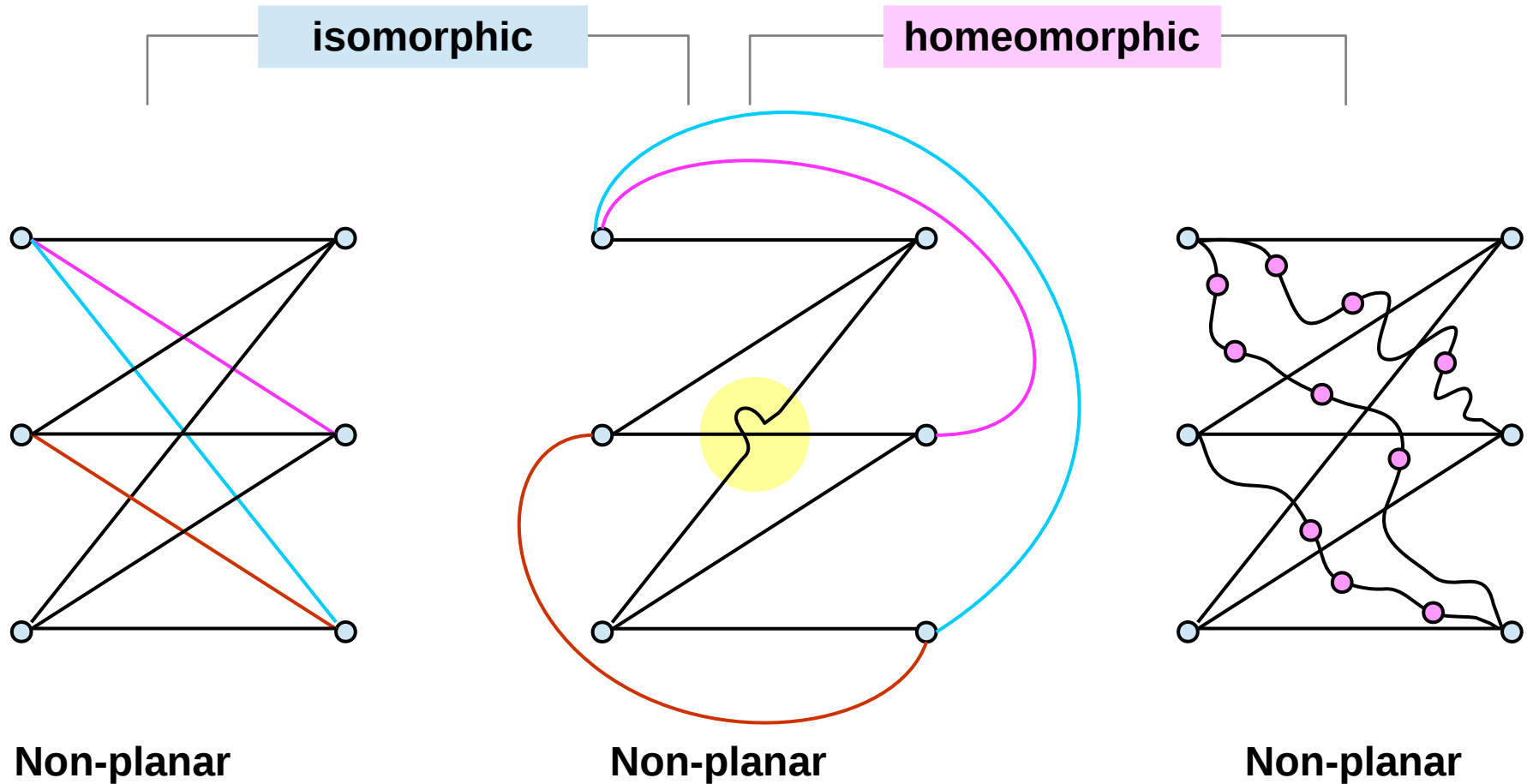
Non-planar

Non-planar graph examples – K_5



All these graphs are similar in determining whether they are planar or not

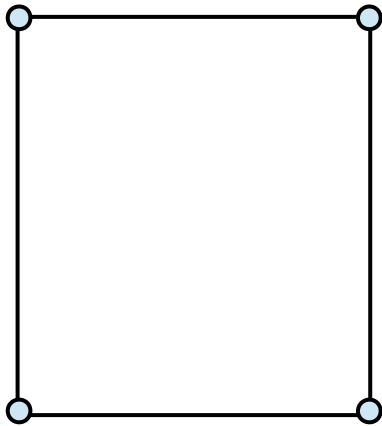
Non-planar graph examples – $K_{3,3}$



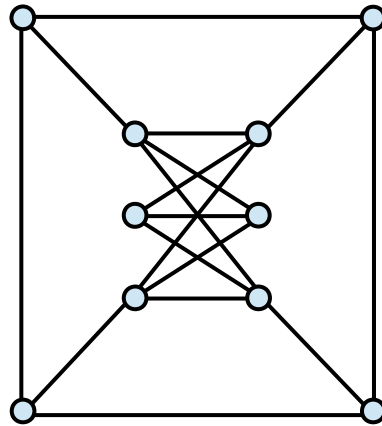
All these graphs are similar in determining whether they are planar or not

Non-planar graph examples – embedding $K_{3,3}$

Planar



Non-planar

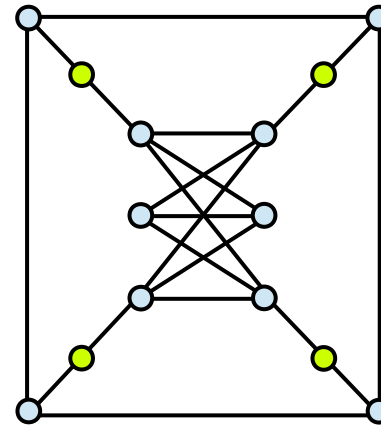


contains $K_{3,3}$



non-planar
subgraph

Non-planar

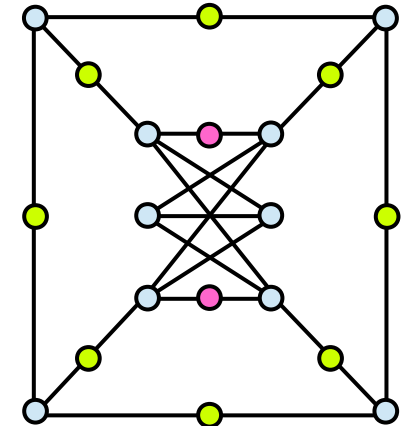


contains $K_{3,3}$



non-planar
subgraph

Non-planar

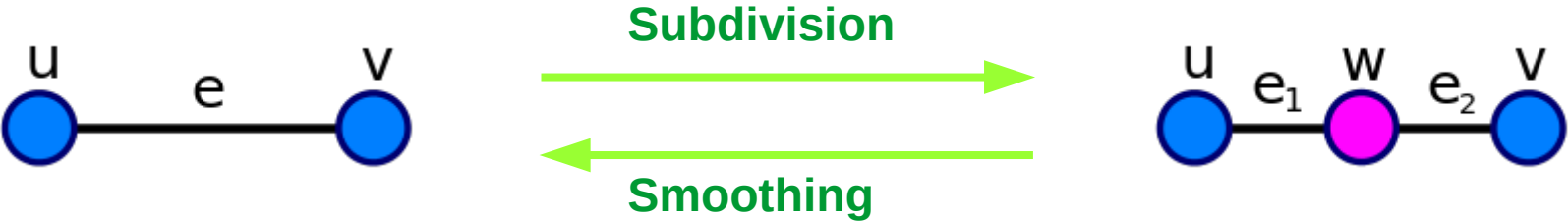


contains a
subdivision of $K_{3,3}$



non-planar
subgraph

Subdivision and Smoothing



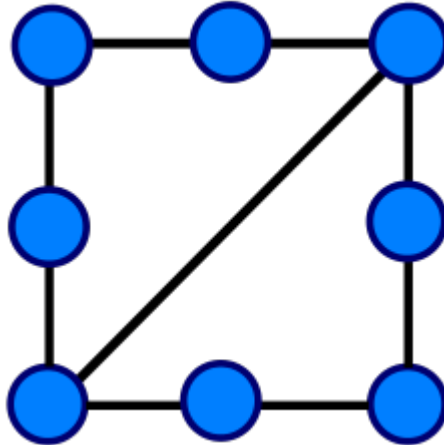
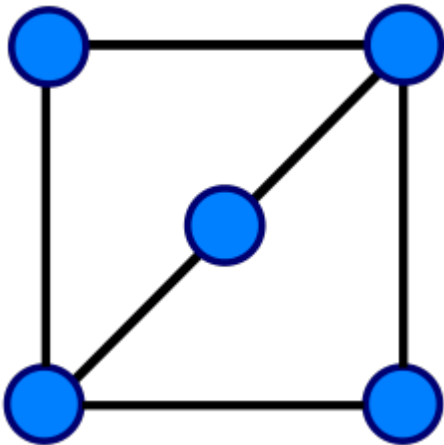
https://en.wikipedia.org/wiki/Planar_graph

Homeomorphism

two graphs G_1 and G_2 are **homeomorphic** if there is a graph **isomorphism** from some **subdivision** of G_1 to some **subdivision** of G_2

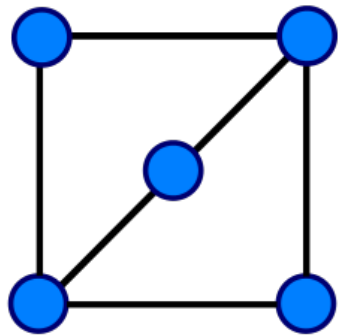
homeo (identity, sameness)

iso (equal)

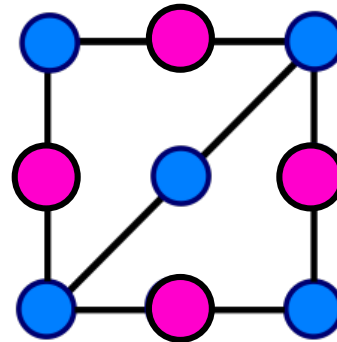
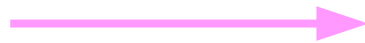


https://en.wikipedia.org/wiki/Planar_graph

Homeomorphism Examples

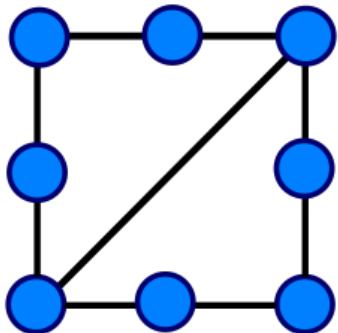


Subdivision

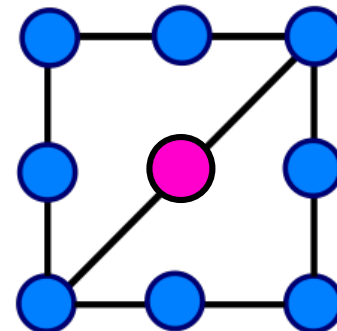
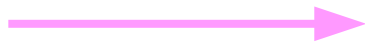


||

||



Subdivision



homeomorphic

Subdivision



isomorphic

homeomorphic

isomorphic

https://en.wikipedia.org/wiki/Planar_graph

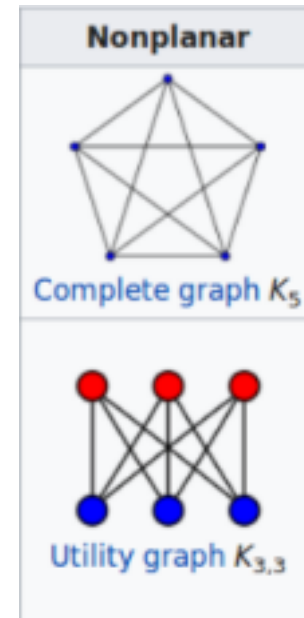
Embedding on a surface

subdividing a graph preserves planarity.

Kuratowski's theorem states that

a finite graph is **planar** if and only if it contains **no** subgraph **homeomorphic** to K_5 (**complete graph** on five vertices) or $K_{3,3}$ (**complete bipartite graph** on six vertices, three of which connect to each of the other three).

In fact, a graph **homeomorphic** to K_5 or $K_{3,3}$ is called a **Kuratowski subgraph**.

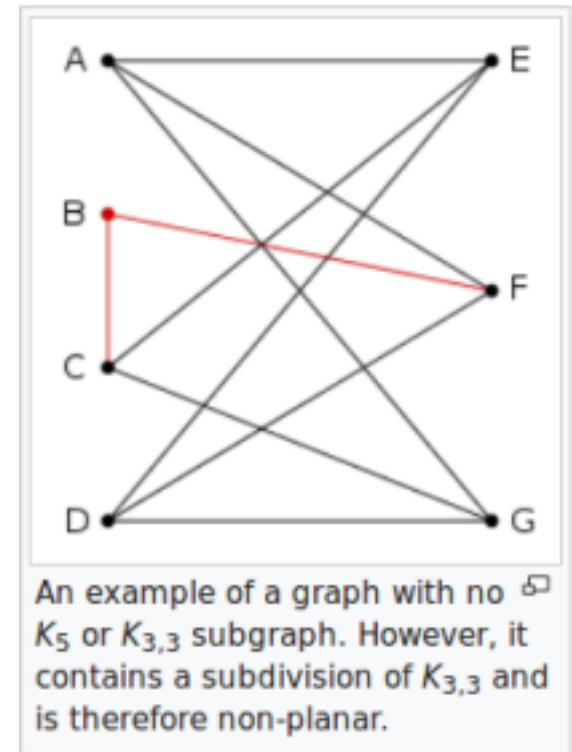


https://en.wikipedia.org/wiki/Planar_graph

Kuratowski's Theorem

A finite graph is **planar** if and only if it does not contain a **subgraph** that is a **subdivision** of the **complete graph** K_5 or the **complete bipartite graph** $K_{3,3}$ (utility graph).

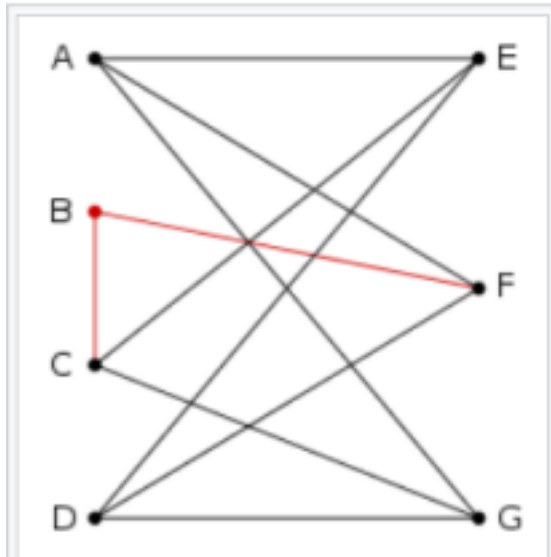
A **subdivision** of a graph results from **inserting vertices** into **edges** (changing an edge $\bullet\text{---}\bullet$ to $\bullet\text{---}\bullet\text{---}\bullet$) zero or more times.



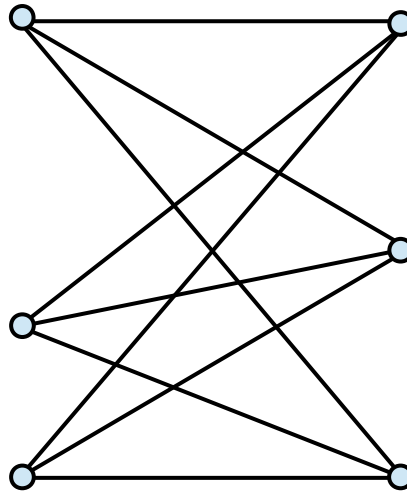
https://en.wikipedia.org/wiki/Planar_graph

Kuratowski's Theorem

homeomorphic



An example of a graph with no K_5 or $K_{3,3}$ subgraph. However, it contains a subdivision of $K_{3,3}$ and is therefore non-planar.



planar



no subgraph homeomorphic to K_5 or $K_{3,3}$

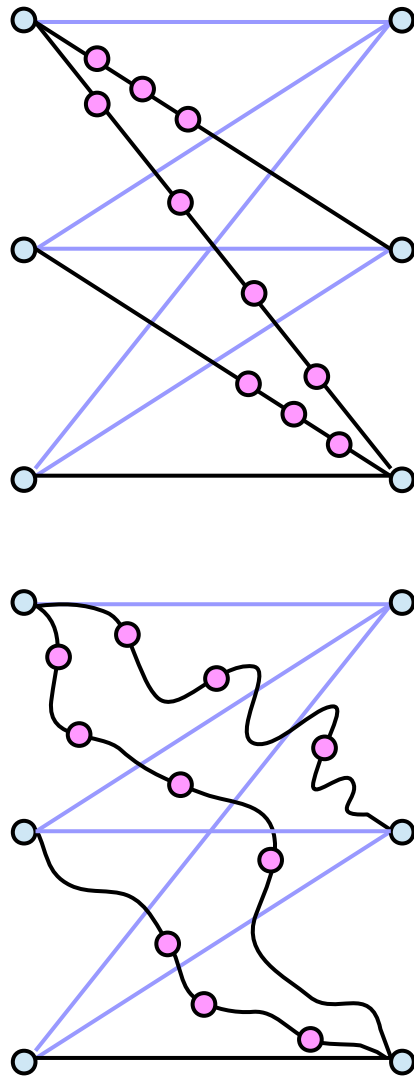
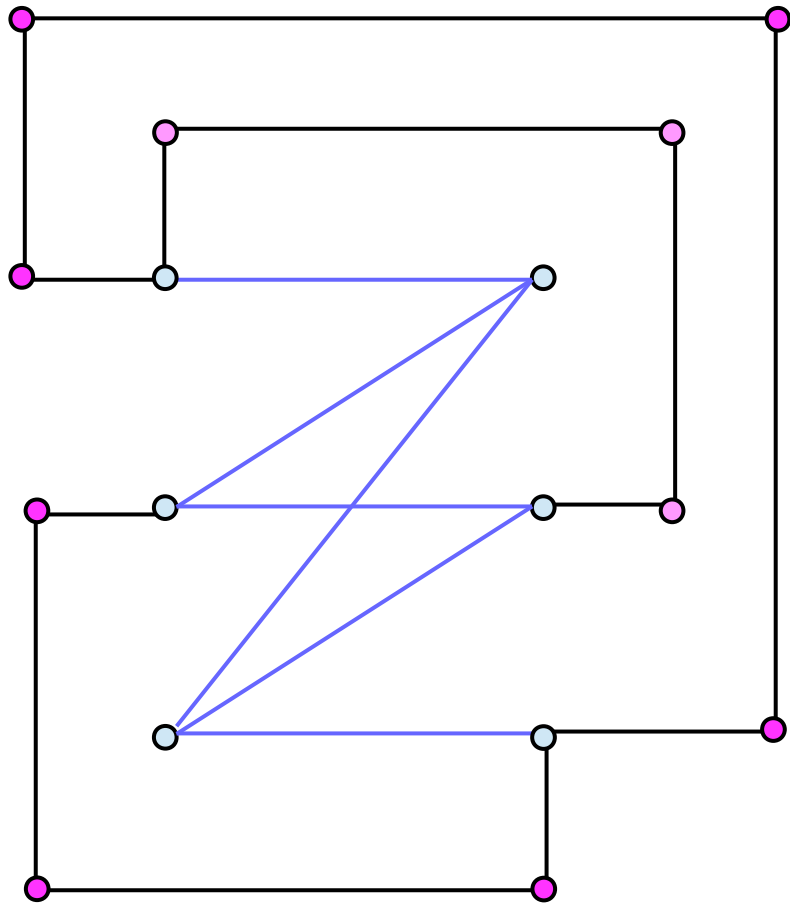
Non-planar



subgraph homeomorphic to K_5 or $K_{3,3}$

https://en.wikipedia.org/wiki/Planar_graph

Homeomorphic to $K_{3,3}$



References

- [1] <http://en.wikipedia.org/>
- [2]

Tree Overview (1A)

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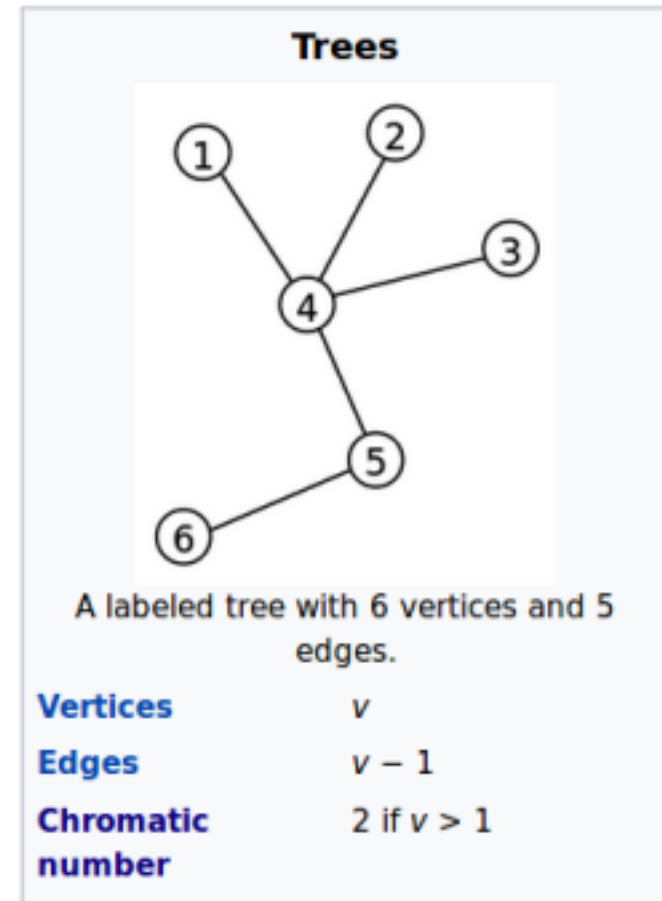
Tree

a tree is an **undirected** graph in which any two vertices are **connected** by exactly **one path**.

any **acyclic connected** graph is a **tree**.

A **forest** is a disjoint union of trees.

connect
acyclic



[https://en.wikipedia.org/wiki/Tree_\(graph_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory))

Tree Condition (1)

A **tree** is an **undirected** graph G that satisfies any of the following equivalent conditions:

G is **connected** and has no **cycles**.

G is **acyclic**, and a **simple cycle** is formed if any **edge** is added to G .

G is **connected**, but is not connected if any single **edge** is removed from G .

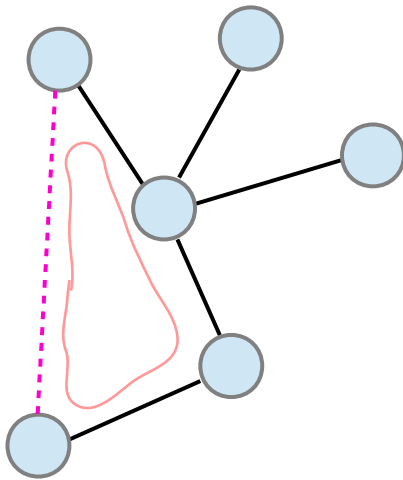
G is **connected** and the 3-vertex complete graph K_3 is not a **minor** of G .

Any **two vertices** in G can be **connected** by a unique **simple path**.

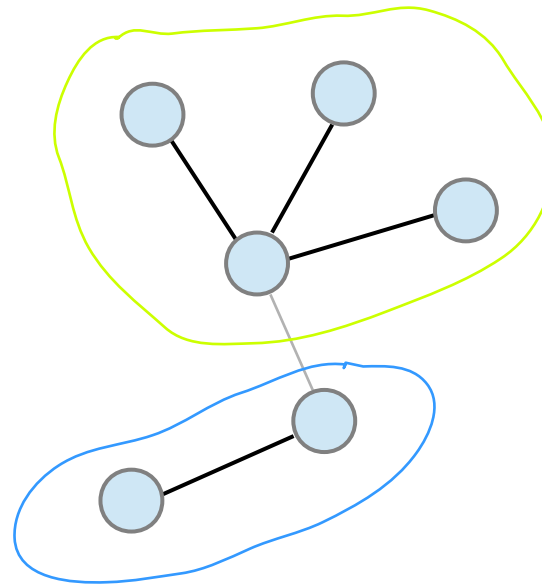
[https://en.wikipedia.org/wiki/Tree_\(graph_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory))

Tree Condition (2)

G is **acyclic**, and a **simple cycle** is formed if any **edge** is added to G.



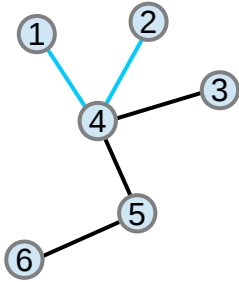
G is **connected**, but is not connected if any single **edge** is removed from G.



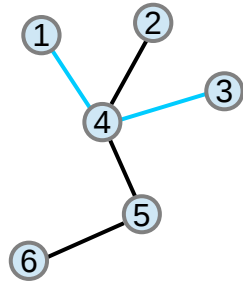
[https://en.wikipedia.org/wiki/Tree_\(graph_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory))

Tree Condition (3)

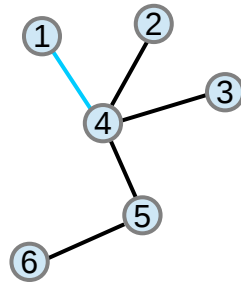
$p_{1,2}$



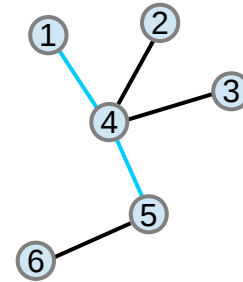
$p_{1,3}$



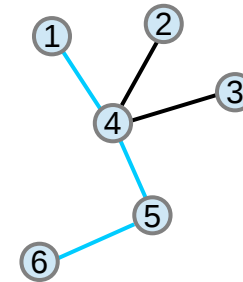
$p_{1,4}$



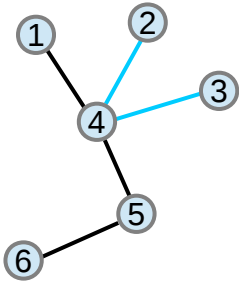
$p_{1,5}$



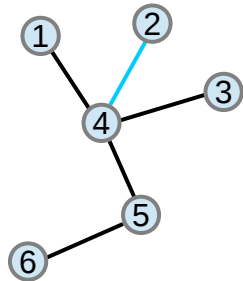
$p_{1,6}$



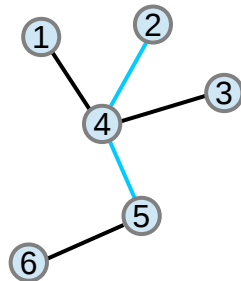
$p_{2,3}$



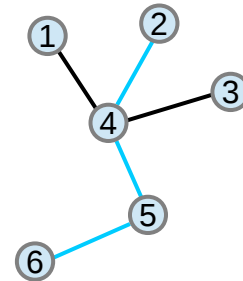
$p_{2,4}$



$p_{2,5}$



$p_{2,6}$

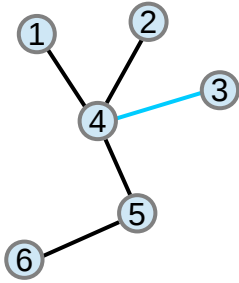


Any **two vertices** in G can be **connected** by a **unique simple path**.

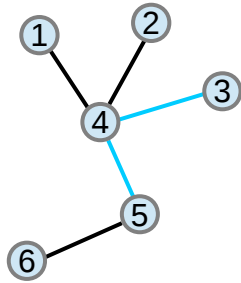
[https://en.wikipedia.org/wiki/Tree_\(graph_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory))

Tree Condition (4)

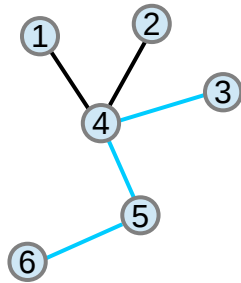
$p_{3,4}$



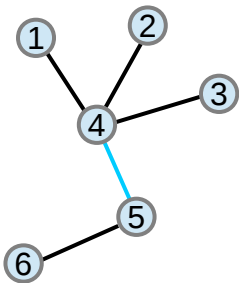
$p_{3,5}$



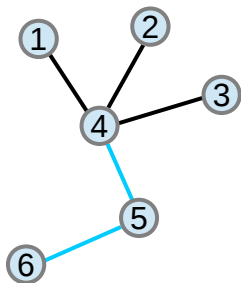
$p_{3,6}$



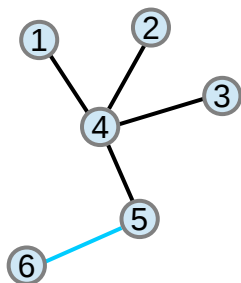
$p_{4,5}$



$p_{4,6}$



$p_{5,6}$



Any **two vertices** in G can be **connected** by a unique simple path.

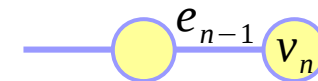
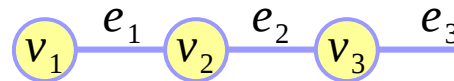
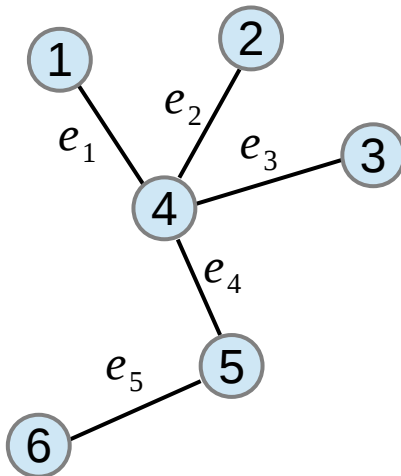
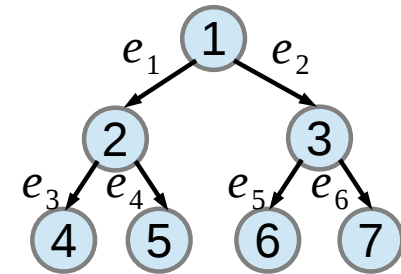
[https://en.wikipedia.org/wiki/Tree_\(graph_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory))

Tree Condition (5)

If G has finitely many **vertices**, say **n vertices**, then the above statements are also equivalent to any of the following conditions:



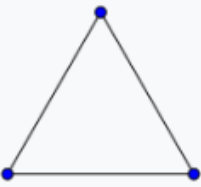
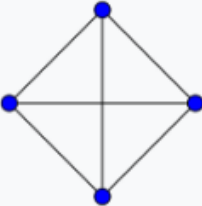
G is **connected** and has **$n - 1$ edges**.

G has **no simple cycles** and has **$n - 1$ edges**.

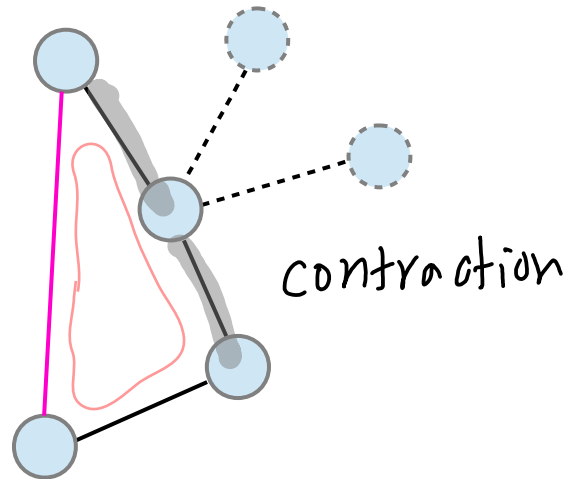
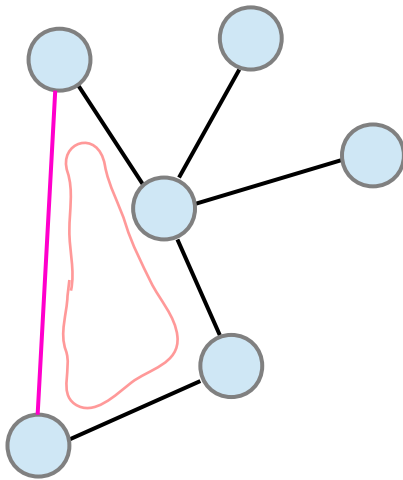


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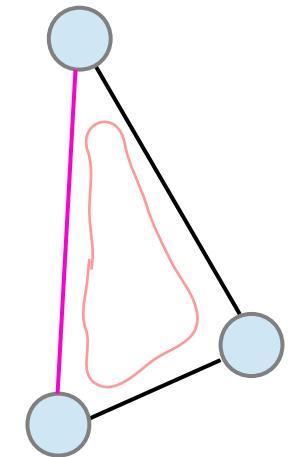
Tree Condition (6)

$K_1: 0$	$K_2: 1$	$K_3: 3$	$K_4: 6$
			

G is **connected** and the 3-vertex complete graph K_3 is not a **minor** of G .



deleting edges
deleting vertices

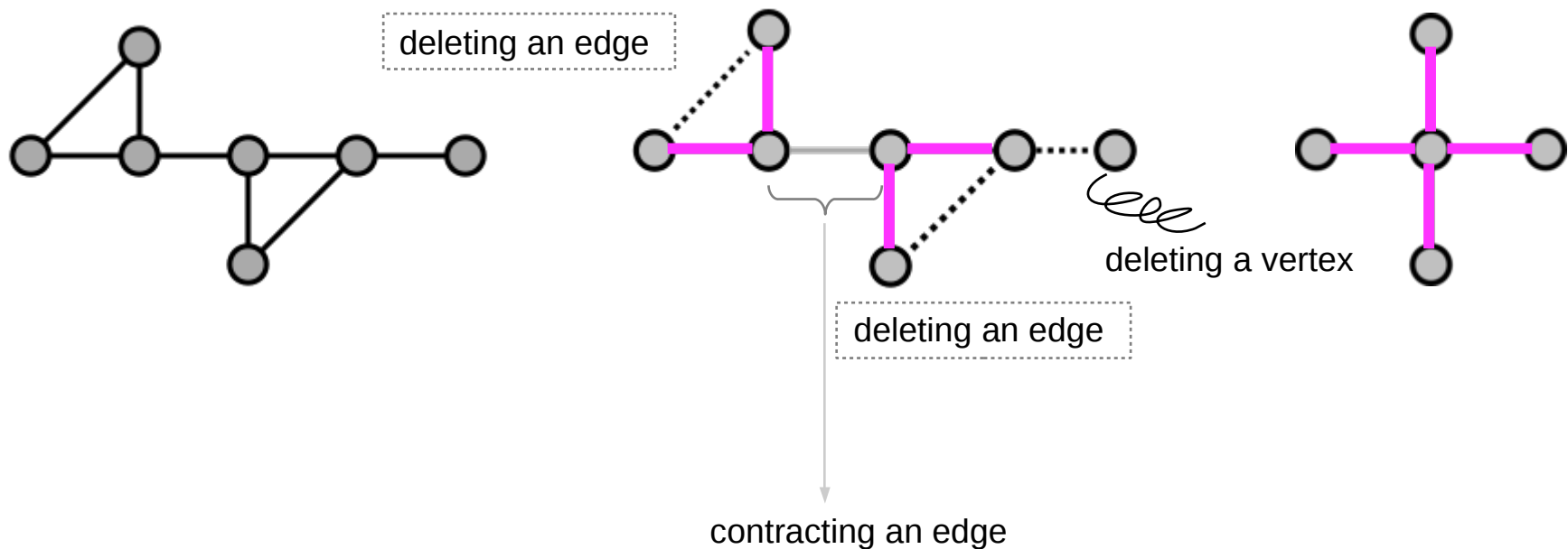


contracting edges

[https://en.wikipedia.org/wiki/Tree_\(graph_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory))

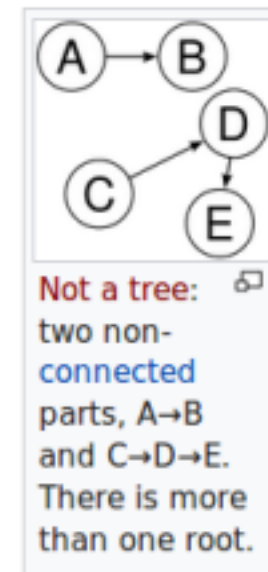
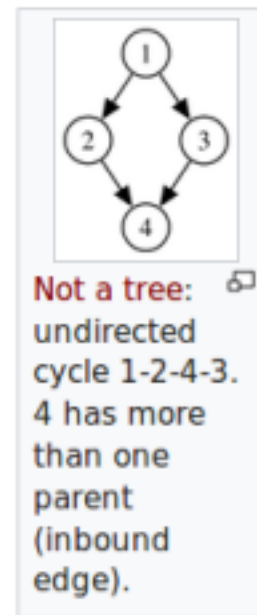
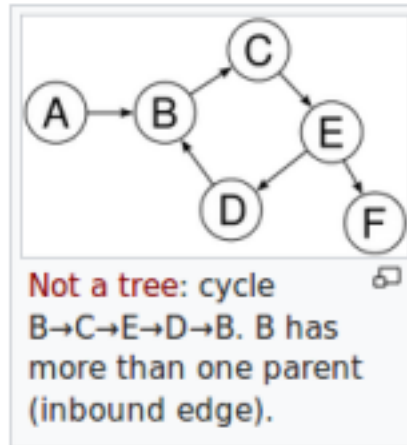
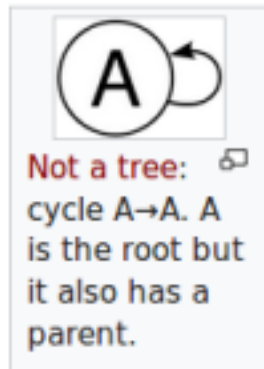
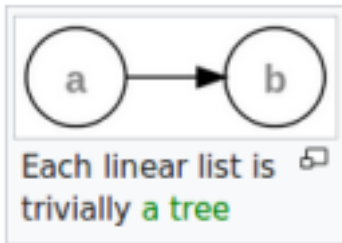
Graph Minor

In graph theory, an undirected graph H is called a minor of the graph G if H can be formed from G by **deleting edges** and **vertices** and by **contracting edges**.



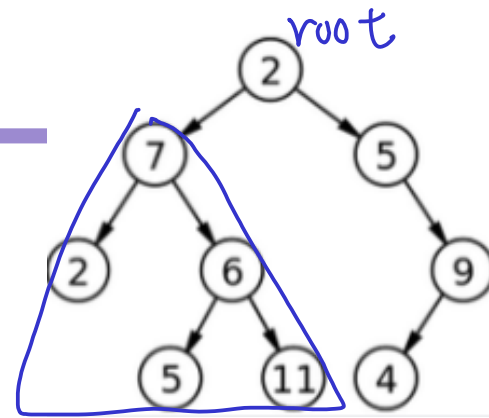
https://en.wikipedia.org/wiki/Graph_minor

Tree Examples



[https://en.wikipedia.org/wiki/Tree_\(data_structure\)](https://en.wikipedia.org/wiki/Tree_(data_structure))

Terminology used in trees (1)



Root

The top node in a tree.

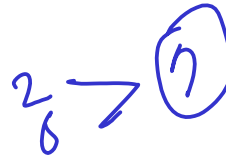
Child



A node directly connected to another node when moving away from the Root.

Parent

The converse notion of a child.



Siblings

A group of nodes with the same parent.



Descendant

A node reachable by repeated proceeding from parent to child.



Ancestor

A node reachable by repeated proceeding from child to parent.



Terminology used in trees (2)

Leaf (less commonly called **External node**)

A node with no children.

Branch (**Internal node**)

A node with at least one child.

Degree

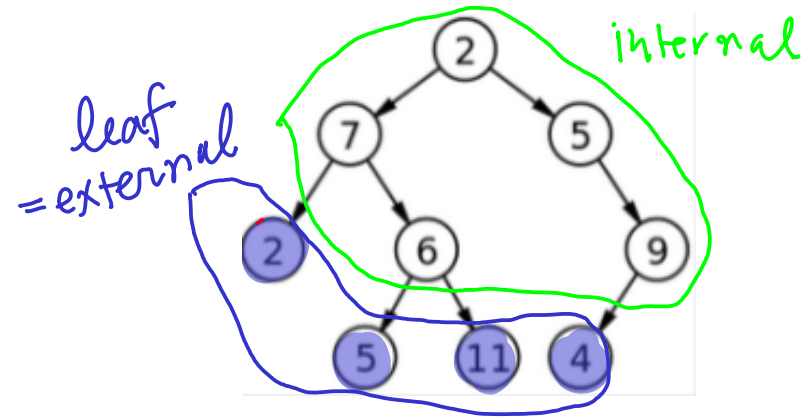
The number of subtrees of a node.

Edge

The connection between one node and another.

Path

A sequence of nodes and edges connecting a node with a descendant.



[https://en.wikipedia.org/wiki/Tree_\(data_structure\)](https://en.wikipedia.org/wiki/Tree_(data_structure))

Terminology used in trees (3)

Level

The level of a node is defined by $1 +$ (the number of connections between the node and the root).

Height of node

The height of a node is the number of edges on the longest path between that node and a leaf.

Height of tree

The height of a tree is the height of its root node.

Depth

The depth of a node is the number of edges from the tree's root node to the node.

Forest

A forest is a set of $n \geq 0$ disjoint trees.

Depth

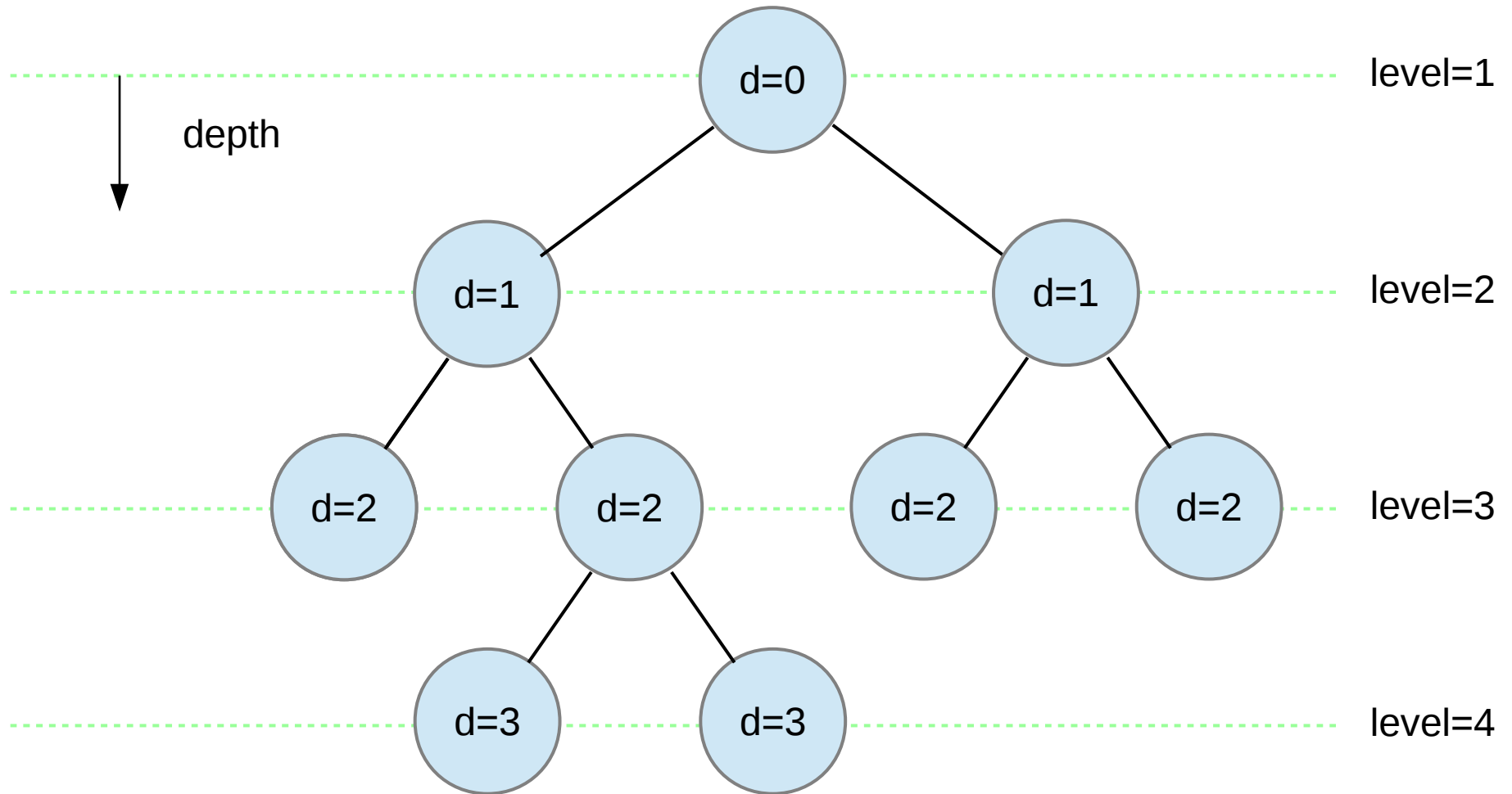
Depth

Height

Some literatures have the reversed definitions of height and depth

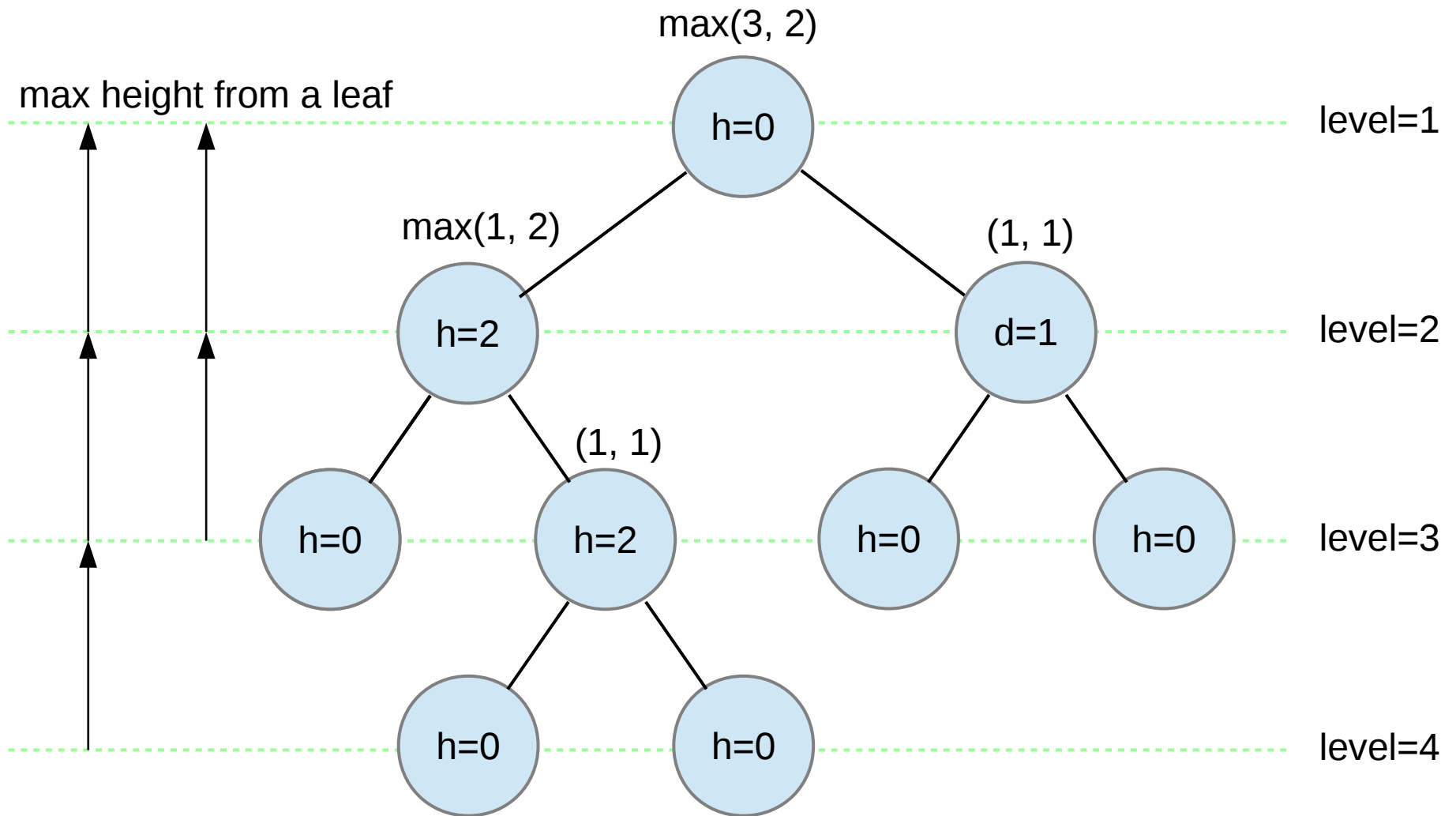
[https://en.wikipedia.org/wiki/Tree_\(data_structure\)](https://en.wikipedia.org/wiki/Tree_(data_structure))

Depth



[https://en.wikipedia.org/wiki/Tree_\(data_structure\)](https://en.wikipedia.org/wiki/Tree_(data_structure))

Height



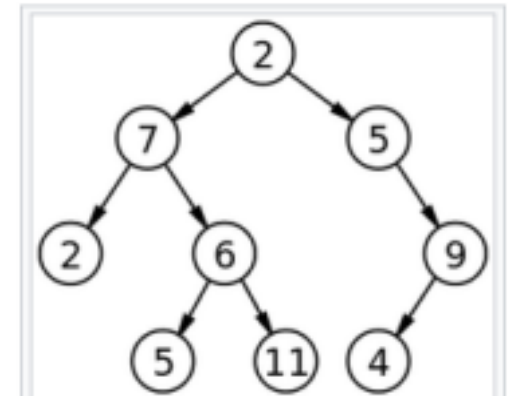
[https://en.wikipedia.org/wiki/Tree_\(data_structure\)](https://en.wikipedia.org/wiki/Tree_(data_structure))

Binary Tree

a **binary tree** is a tree data structure in which each **node** has at most two children, (the **left child**, the **right child**)

A **recursive definition** using just set theory notions is that a (non-empty) binary tree is a tuple **(L, S, R)**, where **L** and **R** are **binary trees** or the **empty set** and **S** is a **singleton set**.

Some authors allow the binary tree to be the empty set as well.

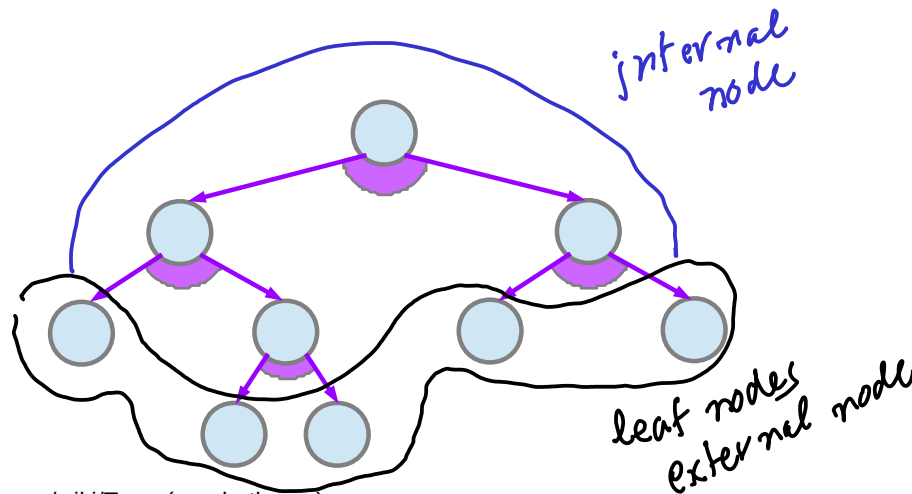
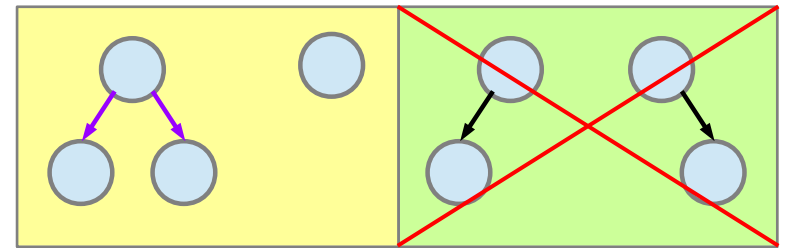


A labeled binary tree of size 9 and height 3, with a root node whose value is 2. The above tree is unbalanced and not sorted.

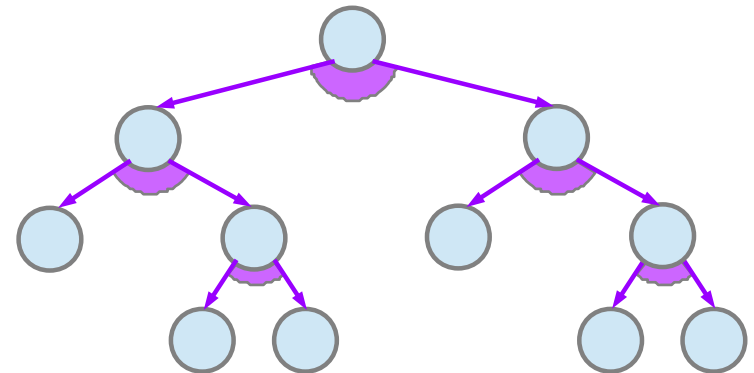
Full Binary Tree

A **rooted binary tree** has a **root node** and every **node** has at most two children.

A **full binary tree** is (proper, plane binary tree) a tree in which every node has either **0** or **2** children.



[https://en.wikipedia.org/wiki/Tree_\(graph_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory))



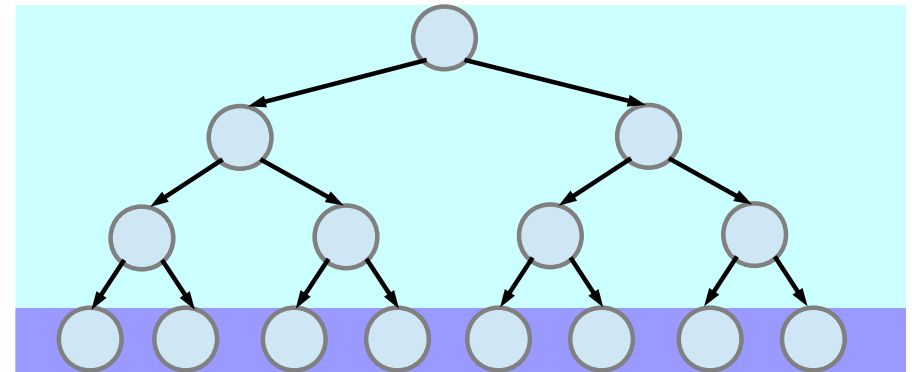
Perfect Binary Trees

A **perfect binary tree** is a binary tree in which all **interior nodes** have two children and all **leaves** have the same depth or same level.

also called a **complete binary tree**

two children

the same depth (level).

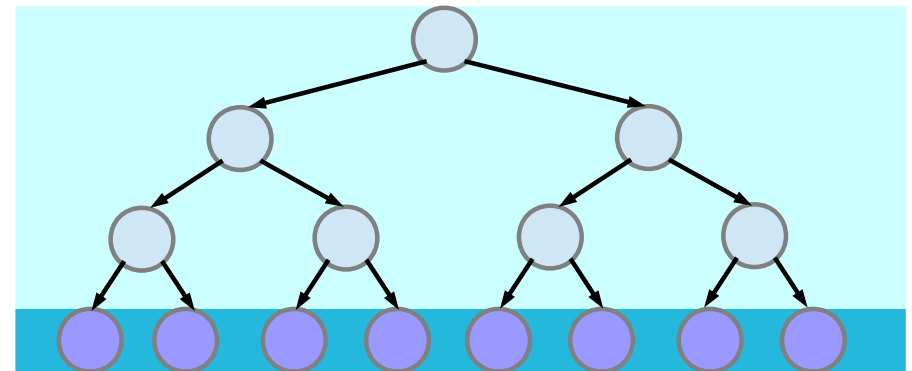
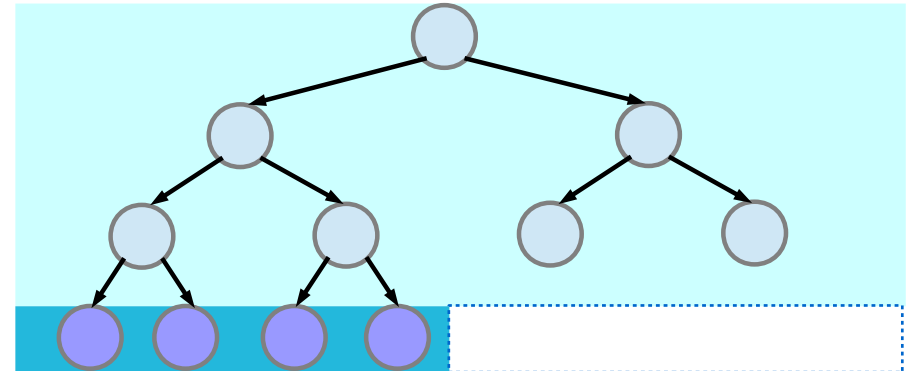


[https://en.wikipedia.org/wiki/Tree_\(graph_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory))

Complete Binary Trees

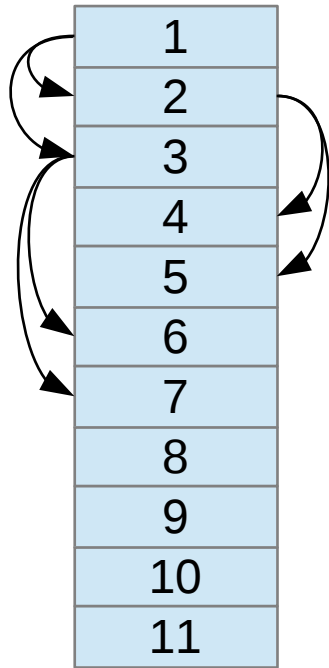
In a **complete** binary tree every level, except possibly the last, is completely filled, and all nodes in the last level are as far left as possible.

An alternative definition is a **perfect** tree whose rightmost leaves (perhaps all) have been removed.



[https://en.wikipedia.org/wiki/Tree_\(graph_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory))

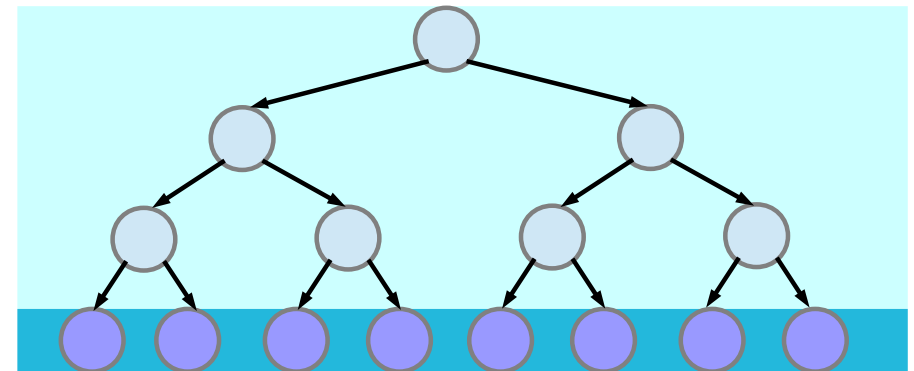
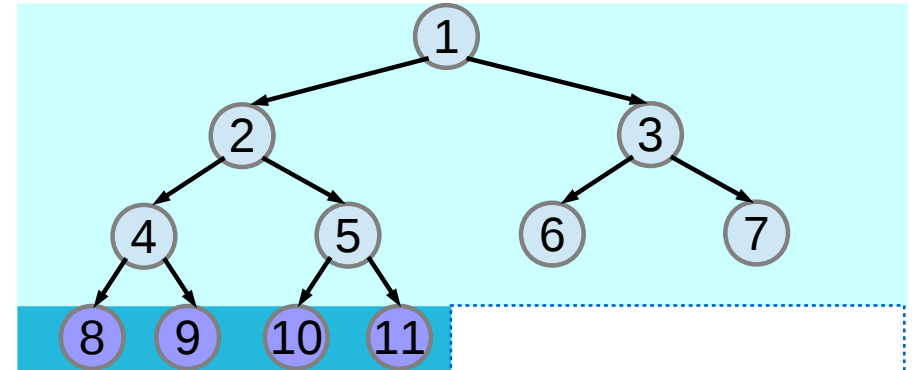
Complete Binary Trees and Linear Arrays



$2 \cdot i$ Left child
 $2 \cdot i + 1$ Right child

A complete binary tree can be efficiently represented using an array.

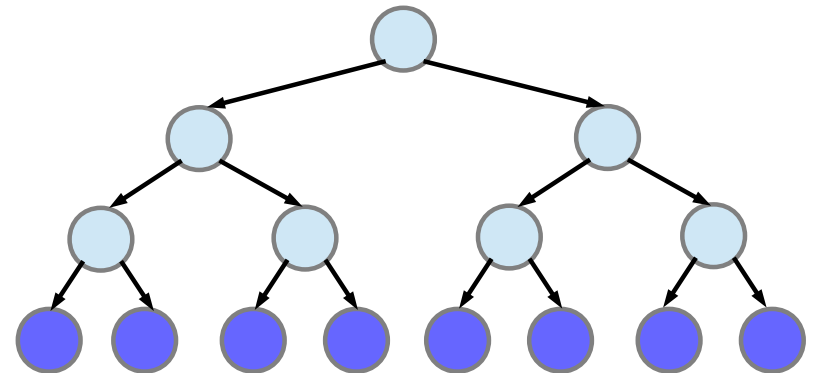
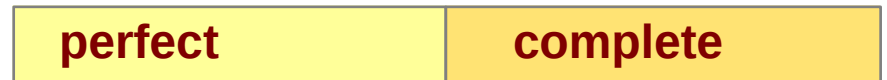
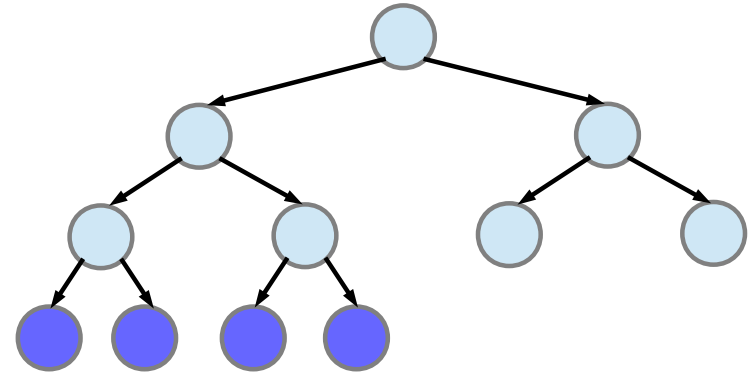
contiguous
no blanks
→ complete



[https://en.wikipedia.org/wiki/Tree_\(graph_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory))

Different use of compute binary trees

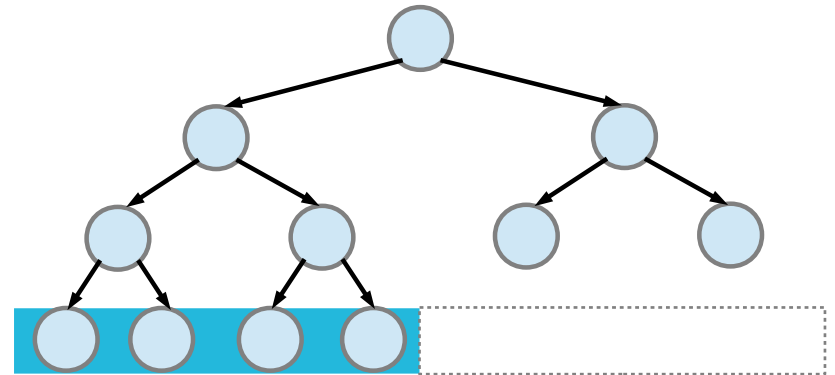
Some authors use the term **complete** to refer instead to a **perfect** binary tree as defined above, in which case they call this type of tree an **almost complete binary tree** or **nearly complete binary tree**.



[https://en.wikipedia.org/wiki/Tree_\(graph_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory))

Properties of Binary Trees (1)

A **complete** binary tree can have between **1** and 2^{m-1} nodes at the last level m .

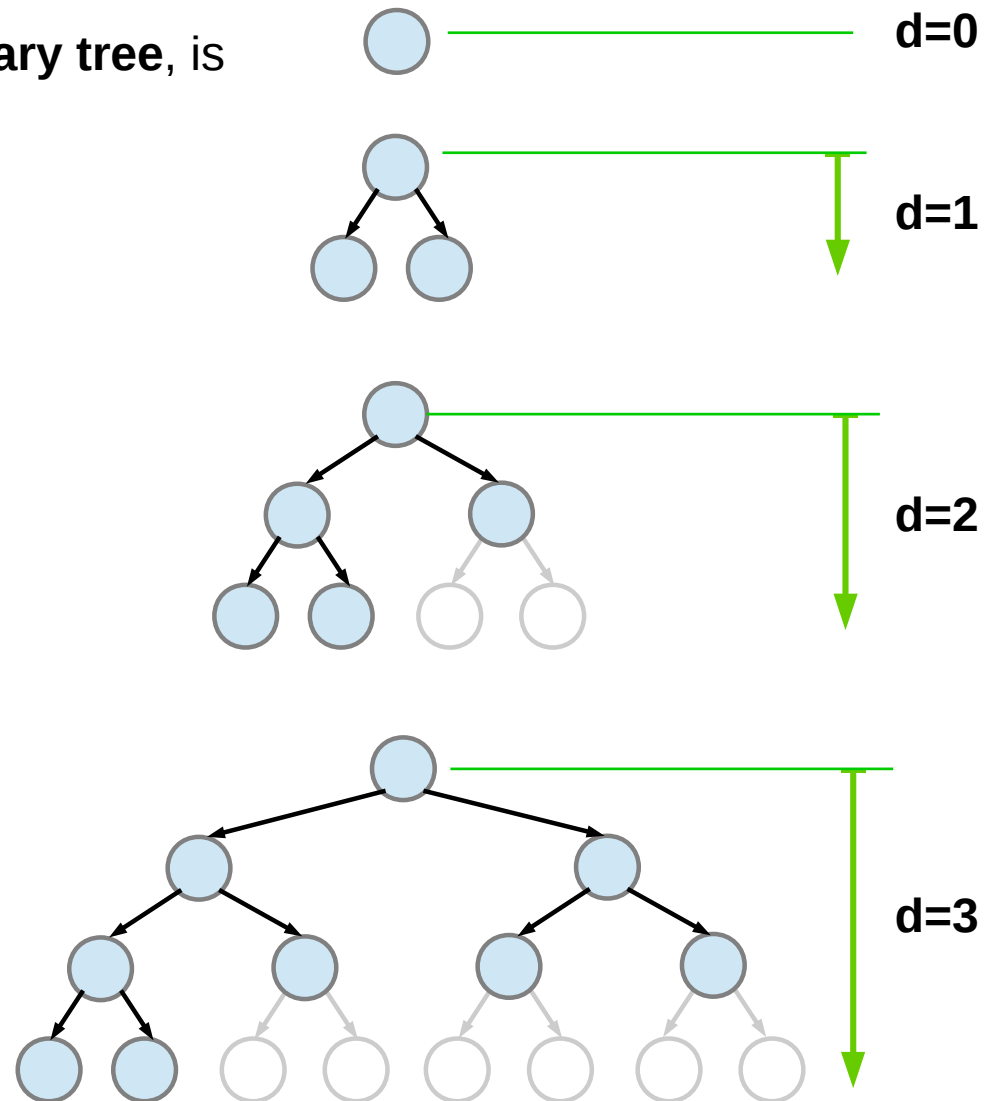


[https://en.wikipedia.org/wiki/Tree_\(graph_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory))

Properties of Binary Trees (2)

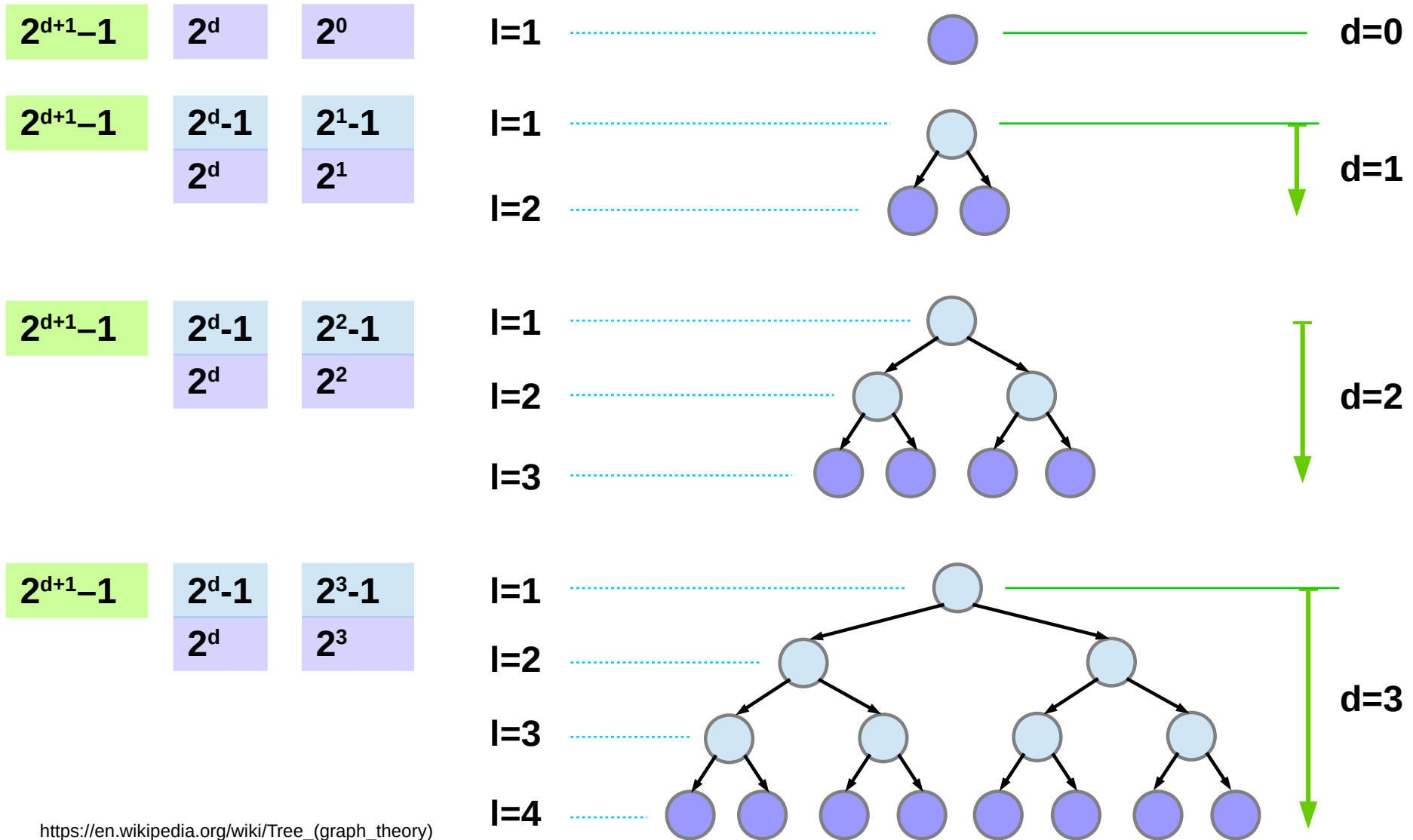
The **number of nodes** n in a **full binary tree**, is
at least $n = 2^d + 1$ and
at most $n = 2^{d+1} - 1$,
where d is the **depth** of the tree.

A tree consisting of only a **root node**
has a **depth** of **0**.



[https://en.wikipedia.org/wiki/Tree_\(graph_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory))

Properties of Binary Trees (3)



[https://en.wikipedia.org/wiki/Tree_\(graph_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory))

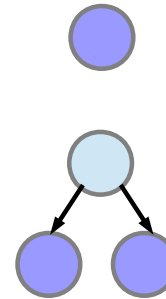
Properties of Binary Trees (4)

The number of **leaf nodes** is m
in a **perfect binary tree**,
is $m=(n+1)/2$

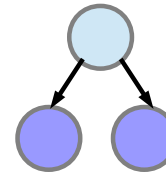
because the number of **non-leaf**
(**internal**) **nodes** is $m-1$

This means that a **perfect binary tree**
with m **leaves** has
 $n = 2m-1$ nodes.

[https://en.wikipedia.org/wiki/Tree_\(graph_theory\)](https://en.wikipedia.org/wiki/Tree_(graph_theory))

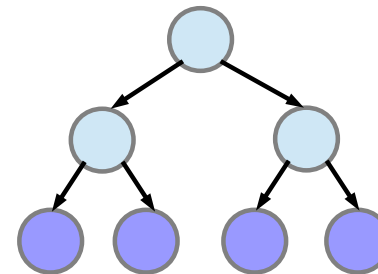


m	2^0
-----	-------



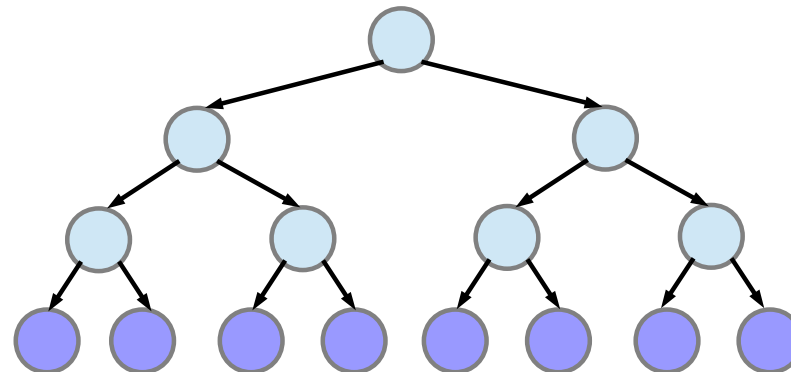
$m-1$	2^1-1
-------	---------

m	2^1
-----	-------



$m-1$	2^2-1
-------	---------

m	2^2
-----	-------



$m-1$	2^3-1
-------	---------

m	2^3
-----	-------

References

- [1] <http://en.wikipedia.org/>
- [2]

Tree Traversal (1A)

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Please send corrections (or suggestions) to youngwlim@hotmail.com.

This document was produced by using LibreOffice and Octave.

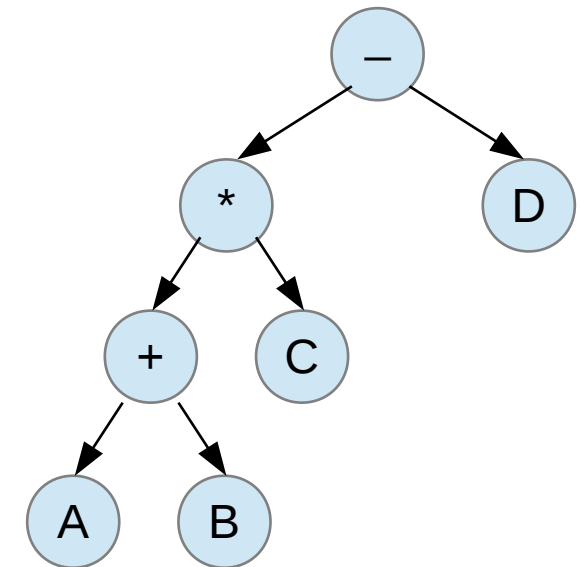
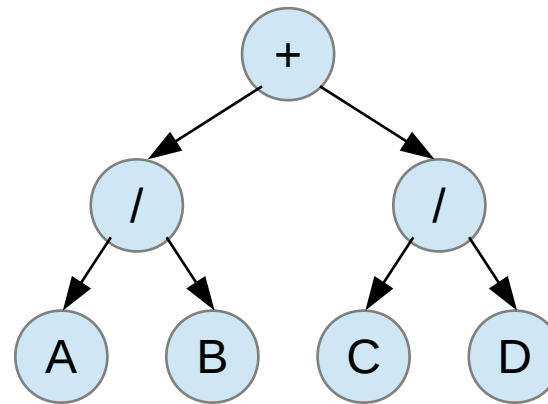
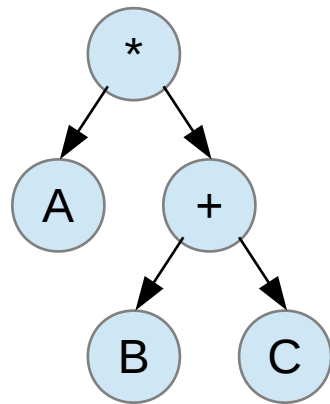
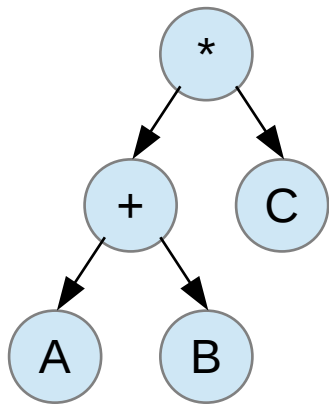
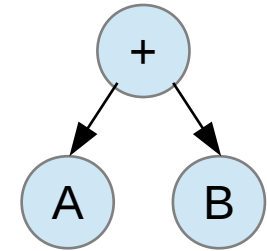
Infix, Prefix, Postfix Notations

Infix Notation	Prefix Notation	Postfix Notation
$A + B$	$+ A B$	$A B +$
$(A + B) * C$	$* + A B C$	$A B + C *$
$A * (B + C)$	$* A + B C$	$A B C + *$
$A / B + C / D$	$+ / A B / C D$	$A B / C D / +$
$((A + B) * C) - D$	$- * + A B C D$	$A B + C * D -$

https://www.tutorialspoint.com/data_structures_algorithms/expression_parsing.html

Infix, Prefix, Postfix Notations and Binary Trees

Infix Notation	Prefix Notation	Postfix Notation
$A + B$	$+ A B$	$A B +$
$(A + B) * C$	$* + A B C$	$A B + C *$
$A * (B + C)$	$* A + B C$	$A B C + *$
$A / B + C / D$	$+ / A B / C D$	$A B / C D / +$
$((A + B) * C) - D$	$- * + A B C D$	$A B + C * D -$



https://www.tutorialspoint.com/data_structures_algorithms/expression_parsing.htm

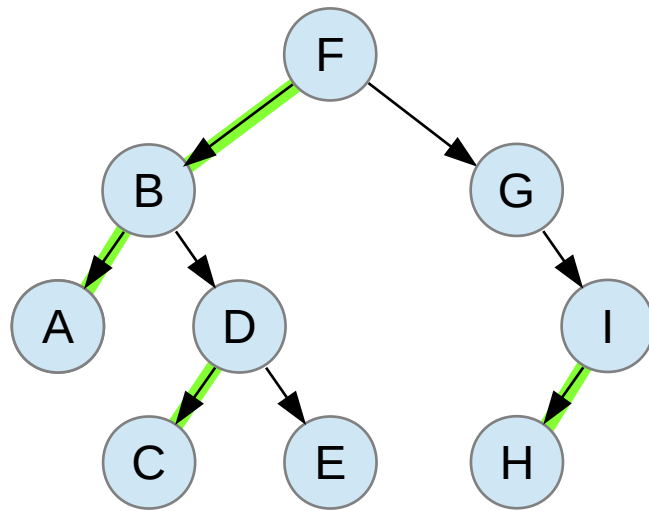
Tree Traversal

Depth First Search

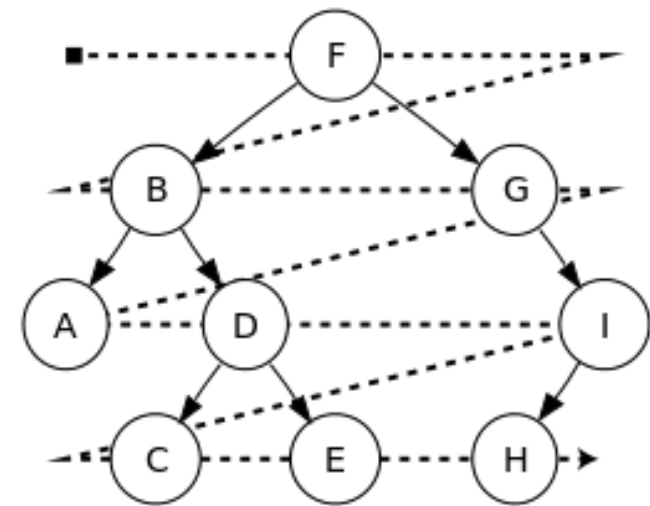
Pre-Order

In-order

Post-Order



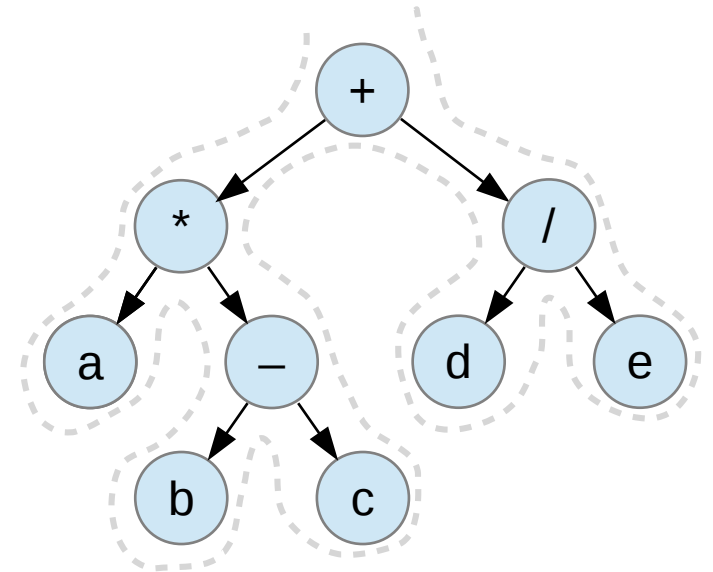
Breadth First Search



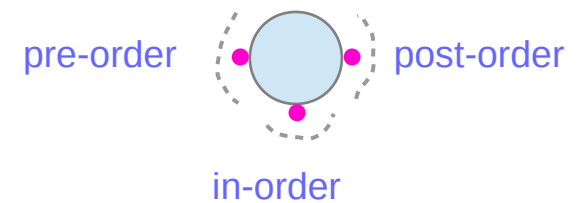
<https://en.wikipedia.org/wiki/Morphism>

Depth First Search on Binary Trees

Depth First Search

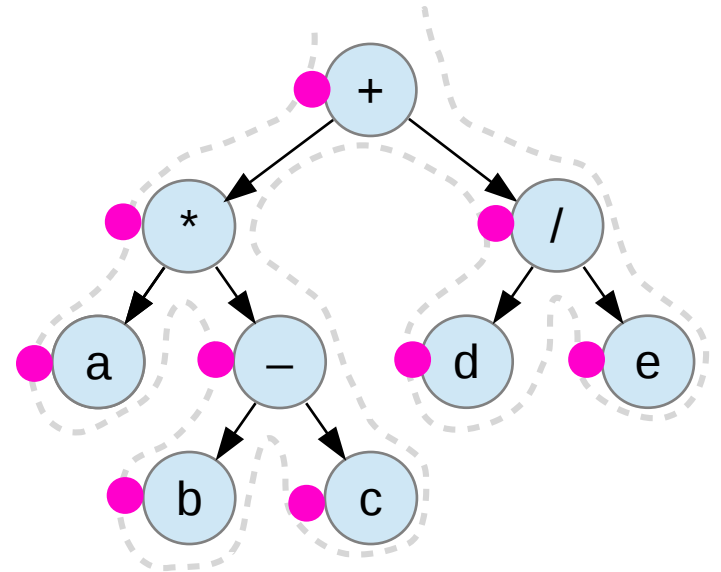


Three Variations
Pre-Order, In-Order, Post-Order



https://en.wikipedia.org/wiki/Tree_traversal

Pre-Order Binary Tree Traversals



$(a*(b-c))+(d/e)$

$a * b - c + d / e$

$+ * a - b c / d e$

$a b c - * d e / +$

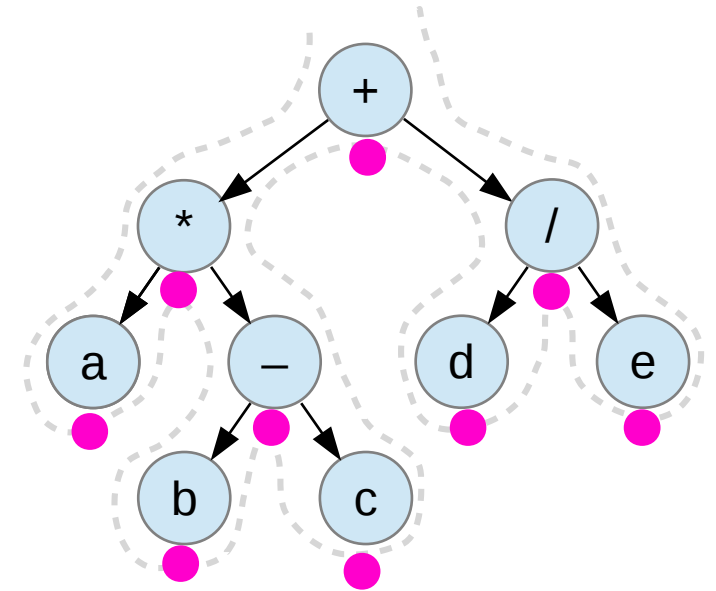
Infix notation

Prefix notation

Postfix notation

https://en.wikipedia.org/wiki/Tree_traversal

In-Order Binary Tree Traversals



$(a*(b-c))+d/e$

$a * b - c + d / e$

$+ * a - b c / d e$

$a b c - * d e / +$

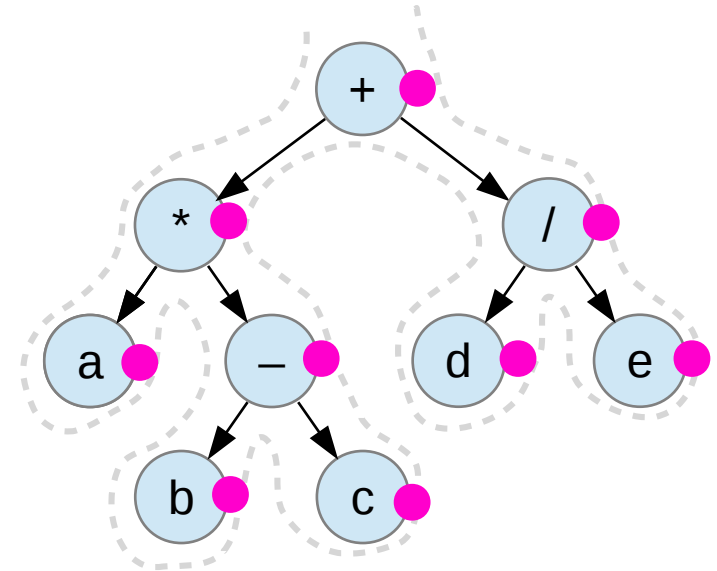
Infix notation

Prefix notation

Postfix notation

https://en.wikipedia.org/wiki/Tree_traversal

Post-Order Binary Tree Traversals



$(a*(b-c))+(d/e)$

$a * b - c + d / e$

$+ * a - b c / d e$

$a b c - * d e / +$

Infix notation

Prefix notation

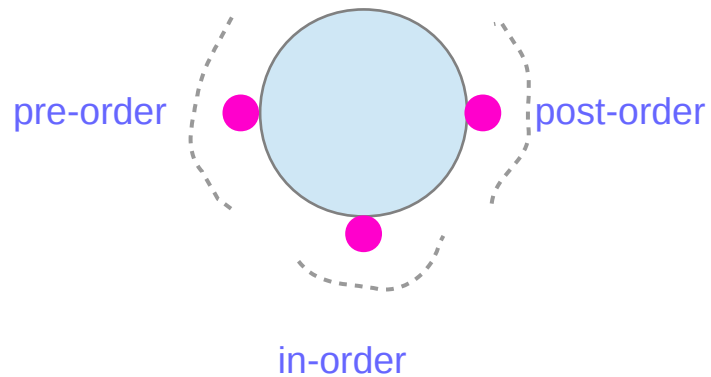
Postfix notation

https://en.wikipedia.org/wiki/Tree_traversal

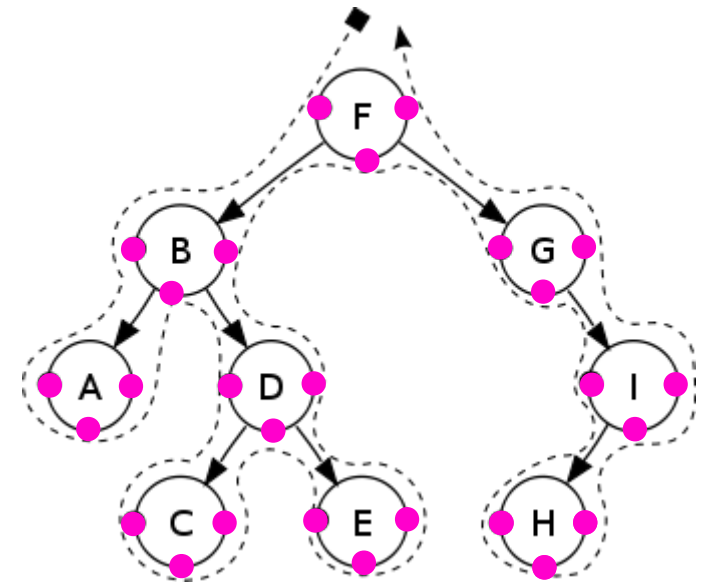
Binary Tree Traversal

Depth First Search
Pre-Order
In-order
Post-Order

Breadth First Search



https://en.wikipedia.org/wiki/Tree_traversal



Pre-Order Traversal on Binary Trees

pre-order function

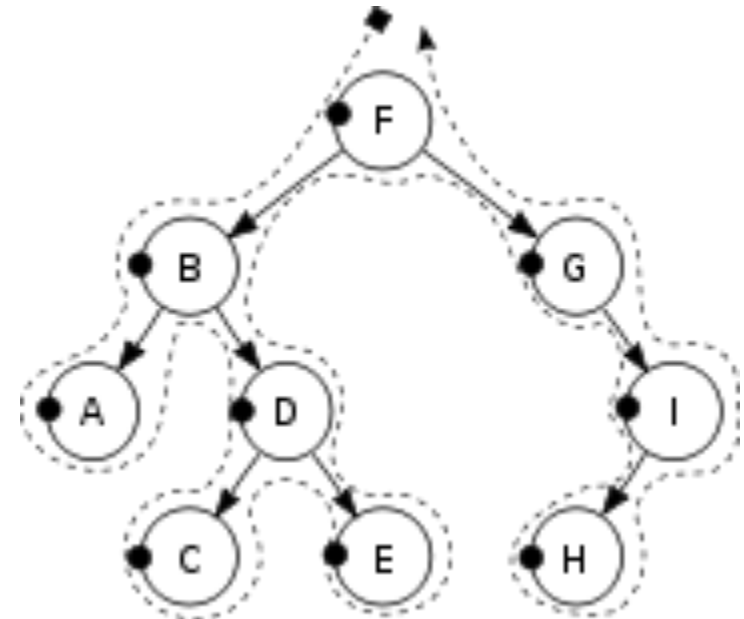
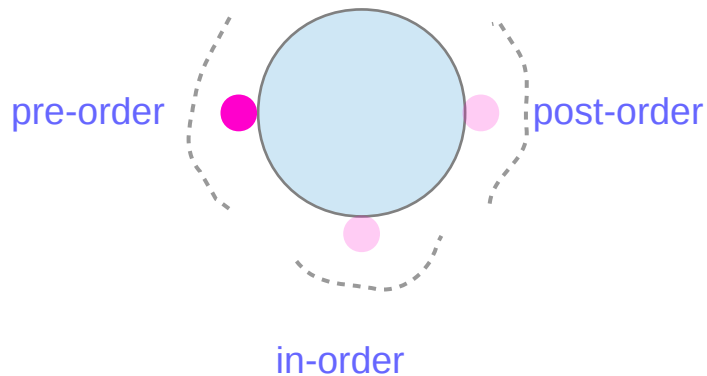
Check if the current node is empty / null.

Display the data part of the root (or current node).

Traverse the **left** subtree by recursively calling the **pre-order** function.

Traverse the **right** subtree by recursively calling the **pre-order** function.

FBADCEGIH



https://en.wikipedia.org/wiki/Tree_traversal

In-Order Traversal on Binary Trees

in-order function

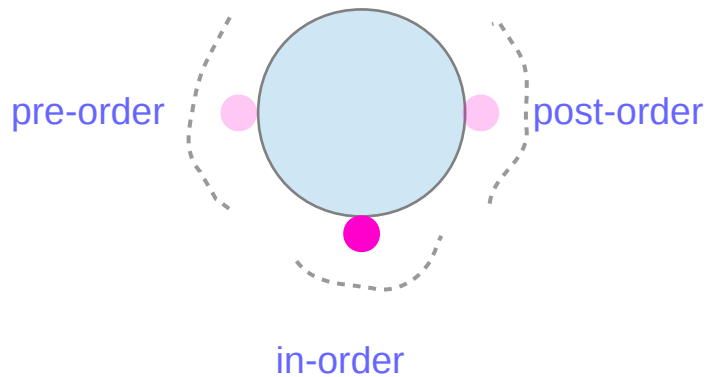
Check if the current node is empty / null.

Traverse the left subtree by recursively calling the **in-order** function.

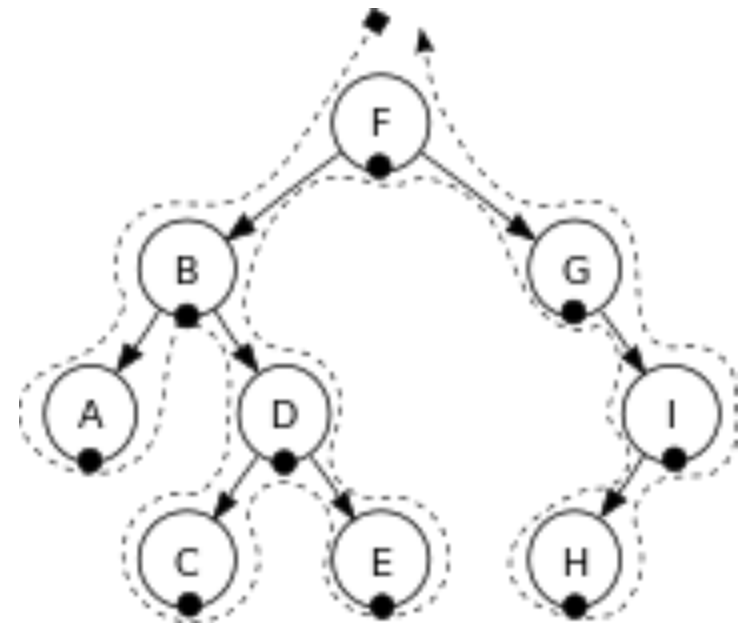
Display the data part of the root (or current node).

Traverse the right subtree by recursively calling the **in-order** function.

ABCDEFGHI



https://en.wikipedia.org/wiki/Tree_traversal



Post-Order Traversal on Binary Trees

post-order function

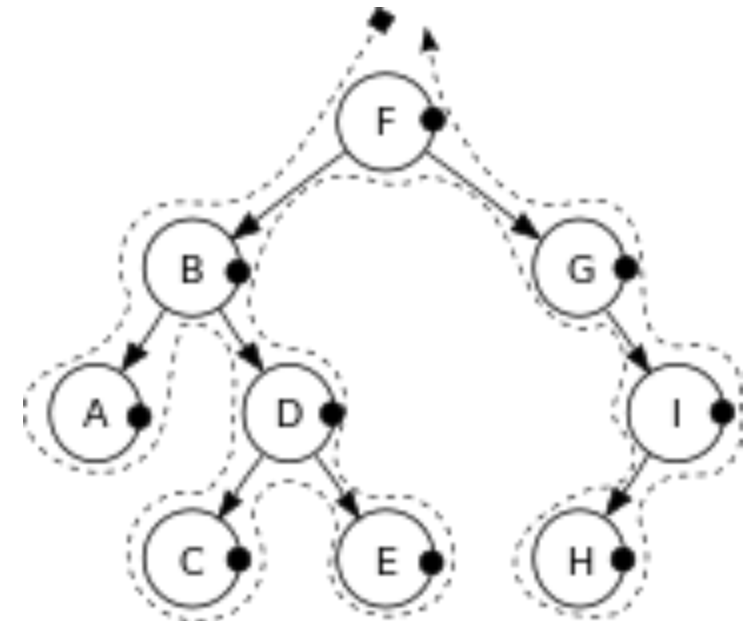
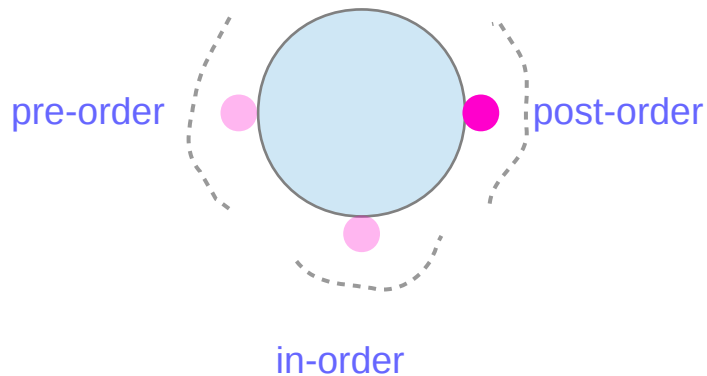
Check if the current node is empty / null.

Traverse the left subtree by recursively calling the **post-order** function.

Traverse the right subtree by recursively calling the **post-order** function.

Display the data part of the root (or current node).

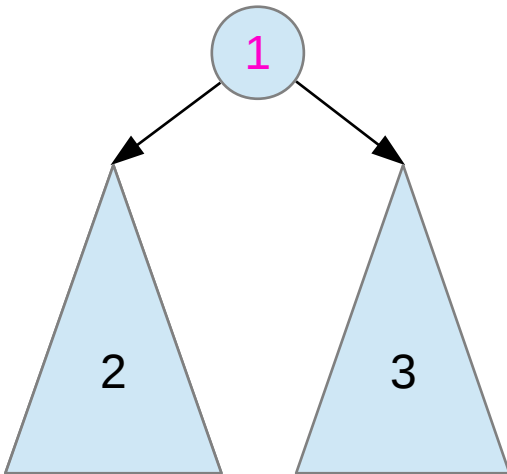
ACEDBHIGH



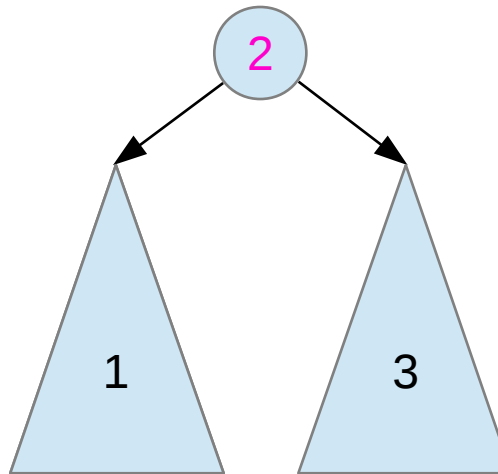
https://en.wikipedia.org/wiki/Tree_traversal

Recursive Algorithms

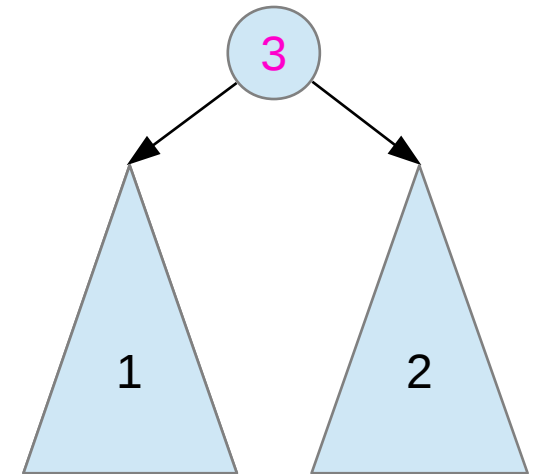
```
preorder(node)
if (node = null)
  return
visit(node)
preorder(node.left)
preorder(node.right)
```



```
inorder(node)
if (node = null)
  return
inorder(node.left)
visit(node)
inorder(node.right)
```



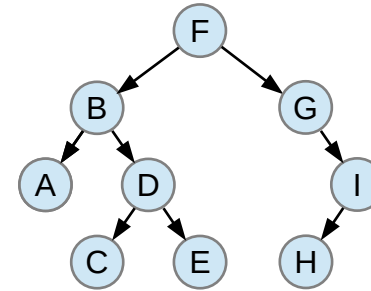
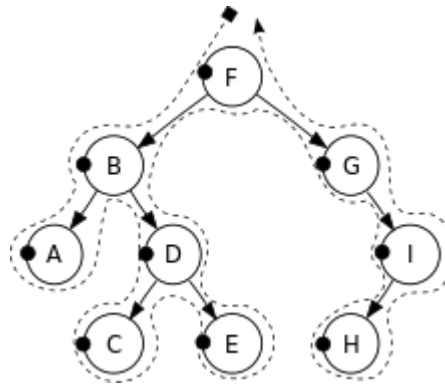
```
postorder(node)
if (node = null)
  return
postorder(node.left)
postorder(node.right)
visit(node)
```



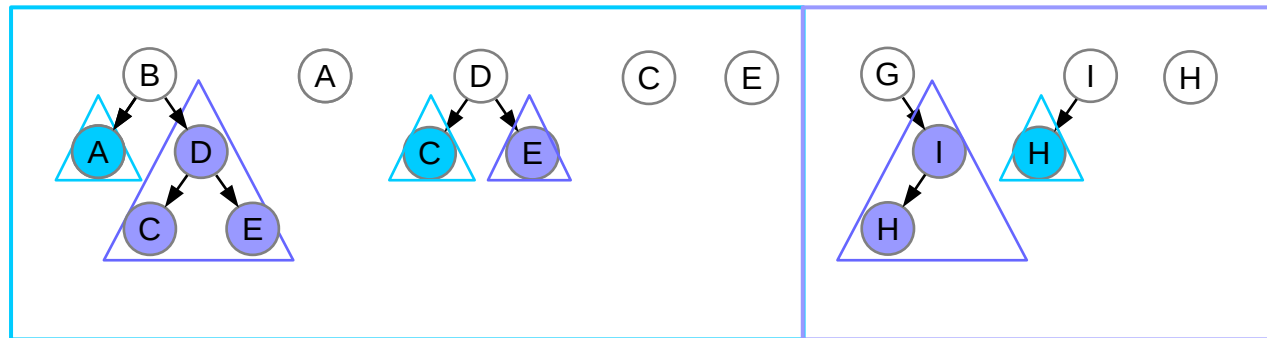
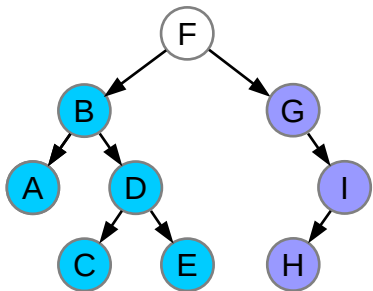
https://en.wikipedia.org/wiki/Tree_traversal

Pre-Order recursive algorithm

```
preorder(node)
  if (node = null)
    return
  visit(node)
  preorder(node.left)
  preorder(node.right)
```



F — B — A — D — C — E — G — I — H



https://en.wikipedia.org/wiki/Tree_traversal

Iterative Algorithms

iterativePreorder(node)

```
if (node = null)
  return
s ← empty stack
s.push(node)
```

while (not s.isEmpty())

```
node ← s.pop()
visit(node)
// right child is pushed first
// so that left is processed first
if (node.right ≠ null)
  s.push(node.right)
if (node.left ≠ null)
  s.push(node.left)
```

https://en.wikipedia.org/wiki/Tree_traversal

iterativeInorder(node)

```
s ← empty stack

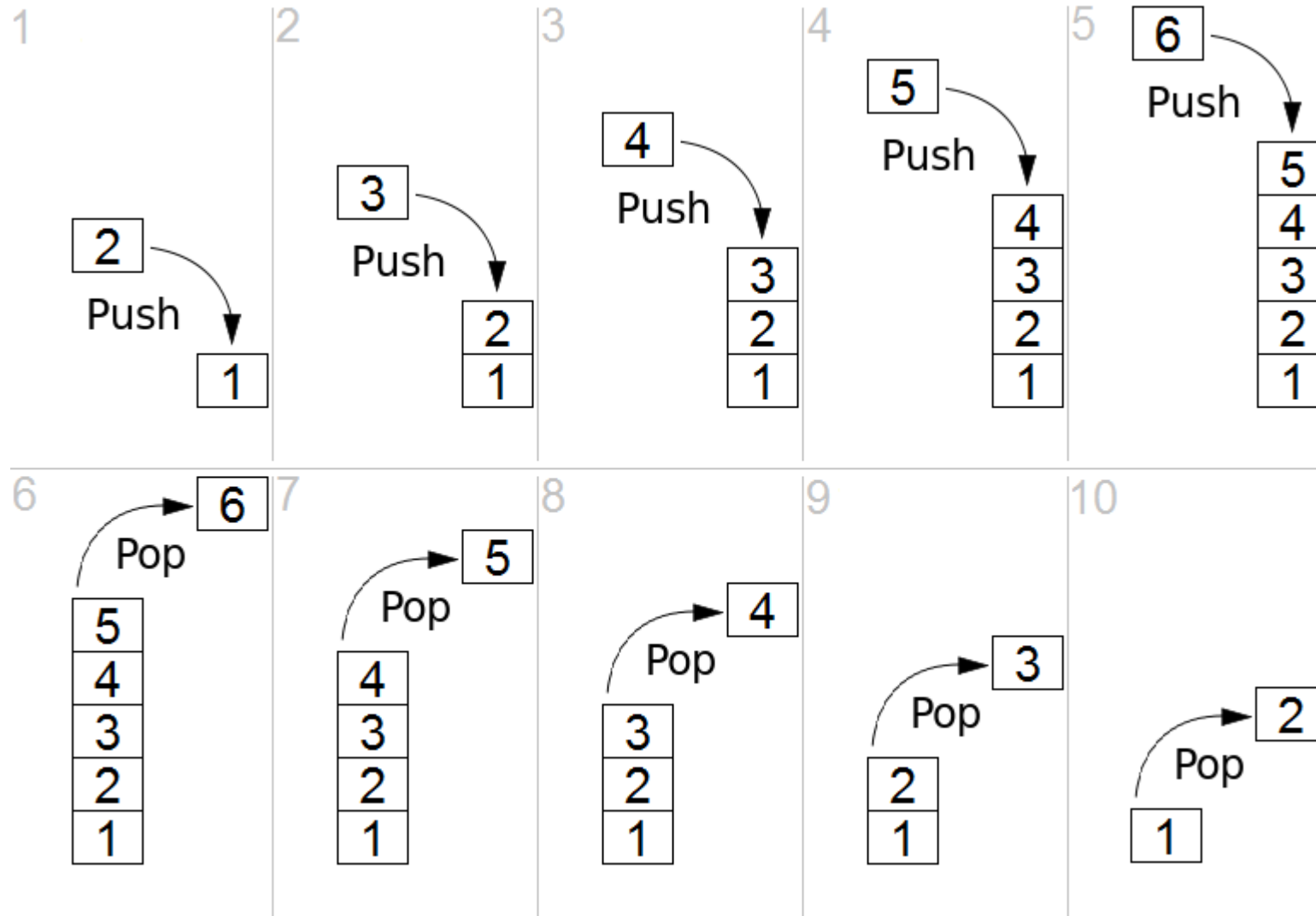
while (not s.isEmpty() or
  node ≠ null)
  if (node ≠ null)
    s.push(node)
    node ← node.left
  else
    node ← s.pop()
    visit(node)
    node ← node.right
```

iterativePostorder(node)

```
s ← empty stack
lastNodeVisited ← null

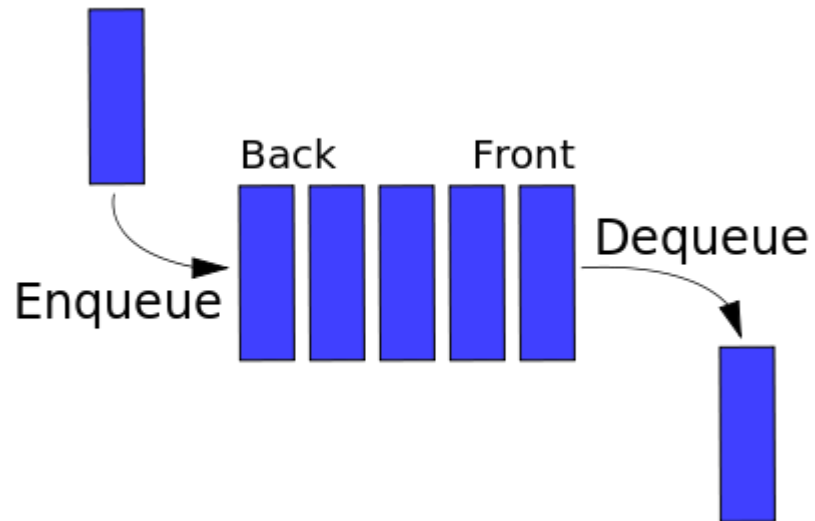
while (not s.isEmpty() or node ≠ null)
  if (node ≠ null)
    s.push(node)
    node ← node.left
  else
    peekNode ← s.peek()
    // if right child exists and traversing
    // node from left child, then move right
    if (peekNode.right ≠ null and
      lastNodeVisited ≠ peekNode.right)
      node ← peekNode.right
    else
      visit(peekNode)
      lastNodeVisited ← s.pop()
```

Stack



[https://en.wikipedia.org/wiki/Stack_\(abstract_data_type\)](https://en.wikipedia.org/wiki/Stack_(abstract_data_type))

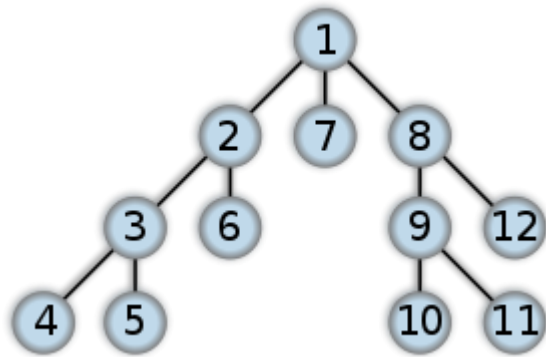
Queue



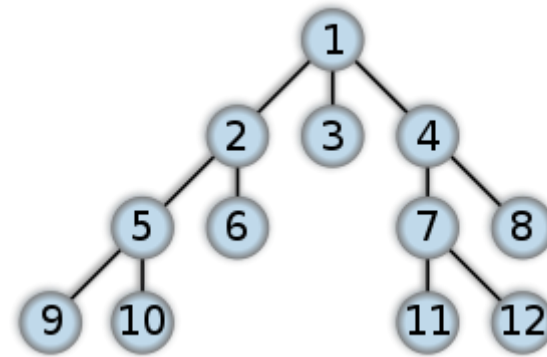
[https://en.wikipedia.org/wiki/Queue_\(abstract_data_type\)#/media/File:Data_Queue.svg](https://en.wikipedia.org/wiki/Queue_(abstract_data_type)#/media/File:Data_Queue.svg)

Search Algorithms

DFS (Depth First Search)



BFS (Breadth First Search)



https://en.wikipedia.org/wiki/Breadth-first_search, [/Depth-first_search](https://en.wikipedia.org/wiki/Depth-first_search)

DFS Algorithm

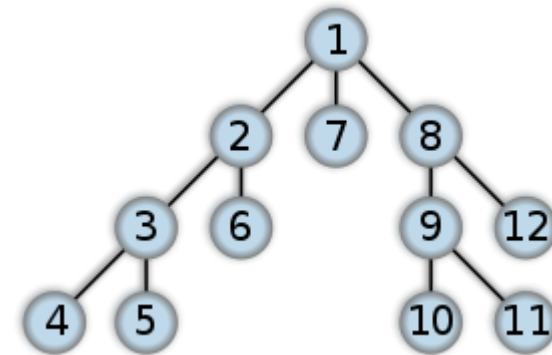
A recursive implementation of DFS:

```
procedure DFS(G,v):  
  label v as discovered  
  for all edges from v to w in G.adjacentEdges(v) do  
    if vertex w is not labeled as discovered then  
      recursively call DFS(G,w)
```

A non-recursive implementation of DFS:

```
procedure DFS-iterative(G,v):  
  let S be a stack  
  S.push(v)  
  while S is not empty  
    v = S.pop()  
    if v is not labeled as discovered:  
      label v as discovered  
      for all edges from v to w in G.adjacentEdges(v) do  
        S.push(w)
```

DFS (Depth First Search)



https://en.wikipedia.org/wiki/Breadth-first_search, /Depth-first_search

BFS Algorithm

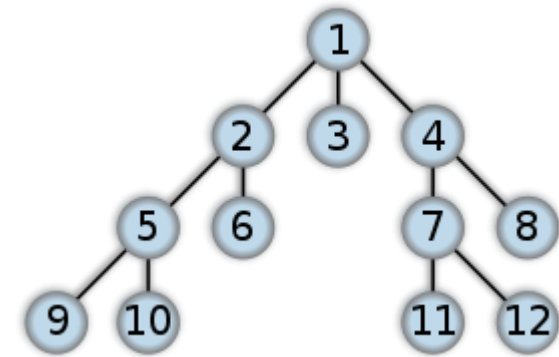
Breadth-First-Search(Graph, root):

create empty set S
create empty queue Q

add root to S
Q.enqueue(root)

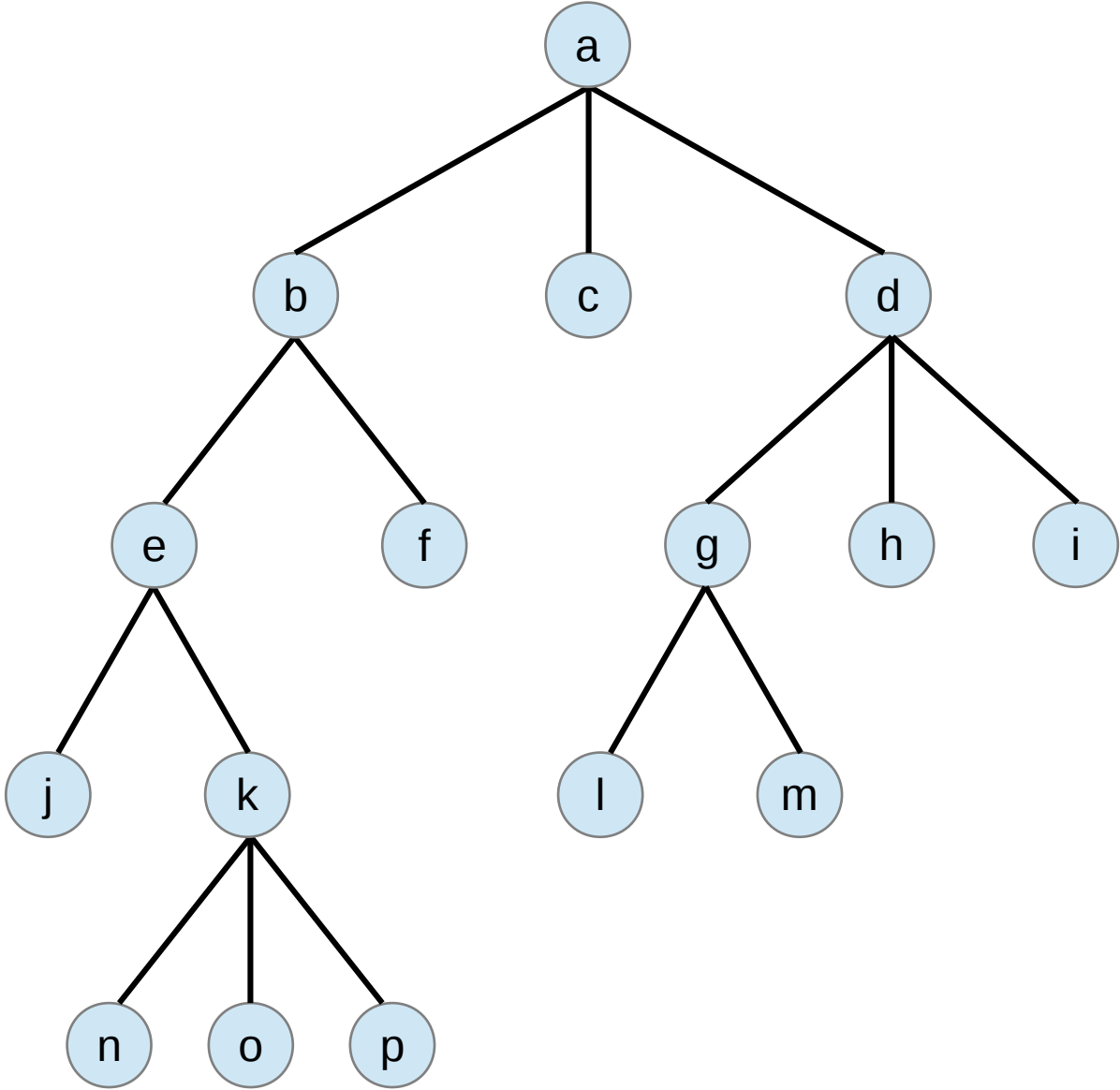
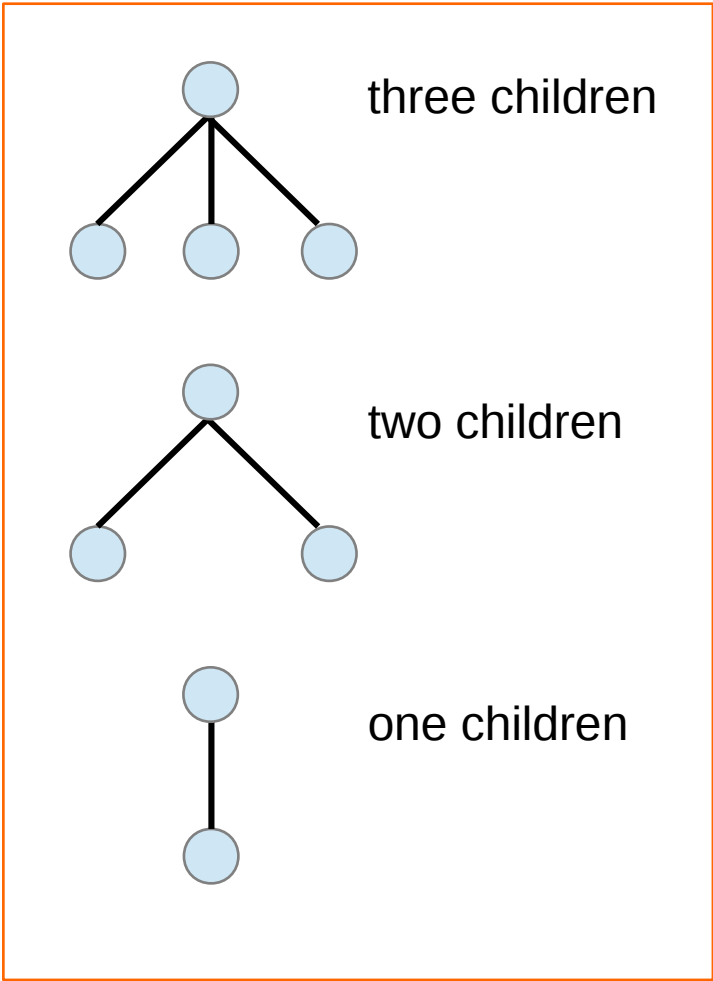
while Q is not empty:
 current = Q.dequeue()
 if current is the goal:
 return current
 for each node n that is adjacent to current:
 if n is not in S:
 add n to S
 n.parent = current
 Q.enqueue(n)

BFS (Breadth First Search)



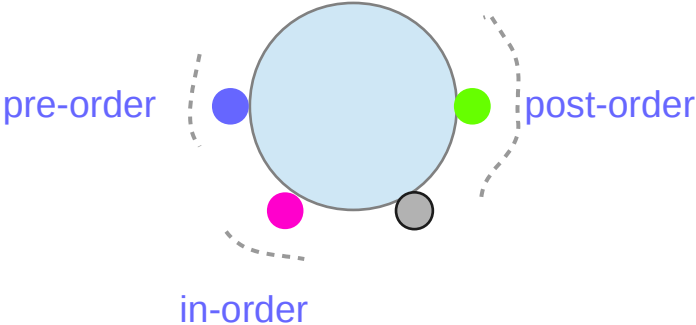
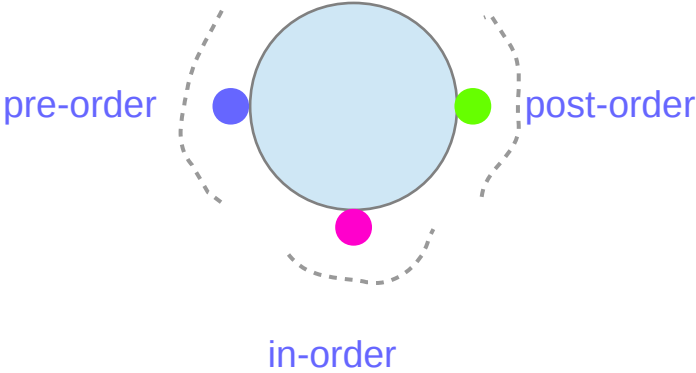
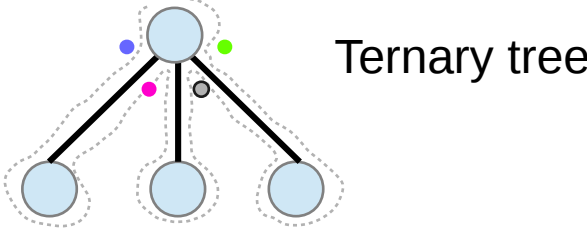
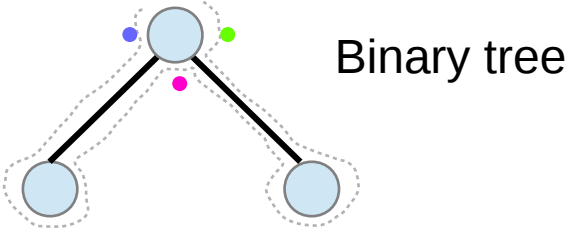
https://en.wikipedia.org/wiki/Breadth-first_search, /Depth-first_search

Ternary Tree



Rosen

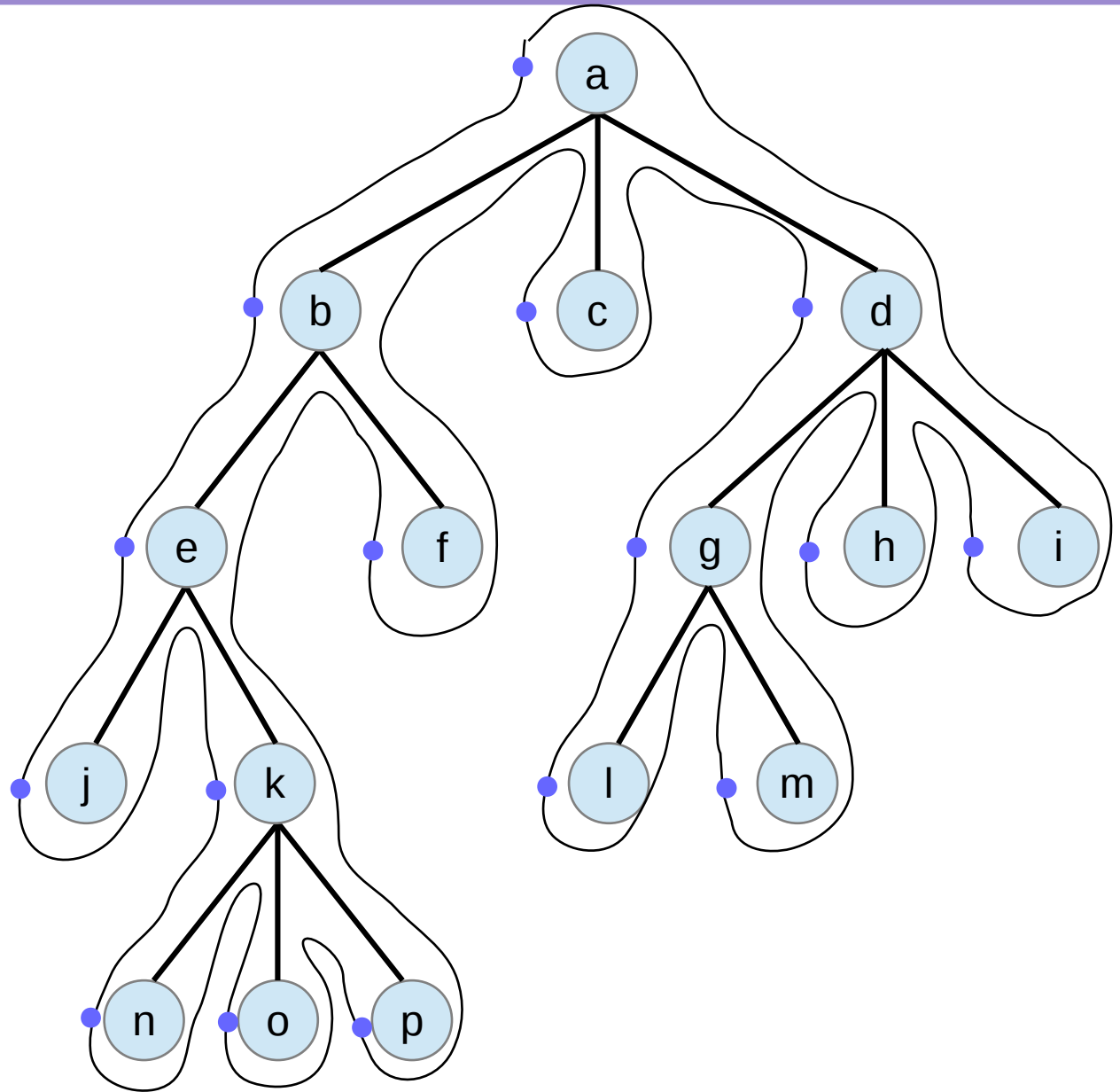
Ternary Tree Traversal



Rosen

Pre-Order Traversal on Ternary Trees

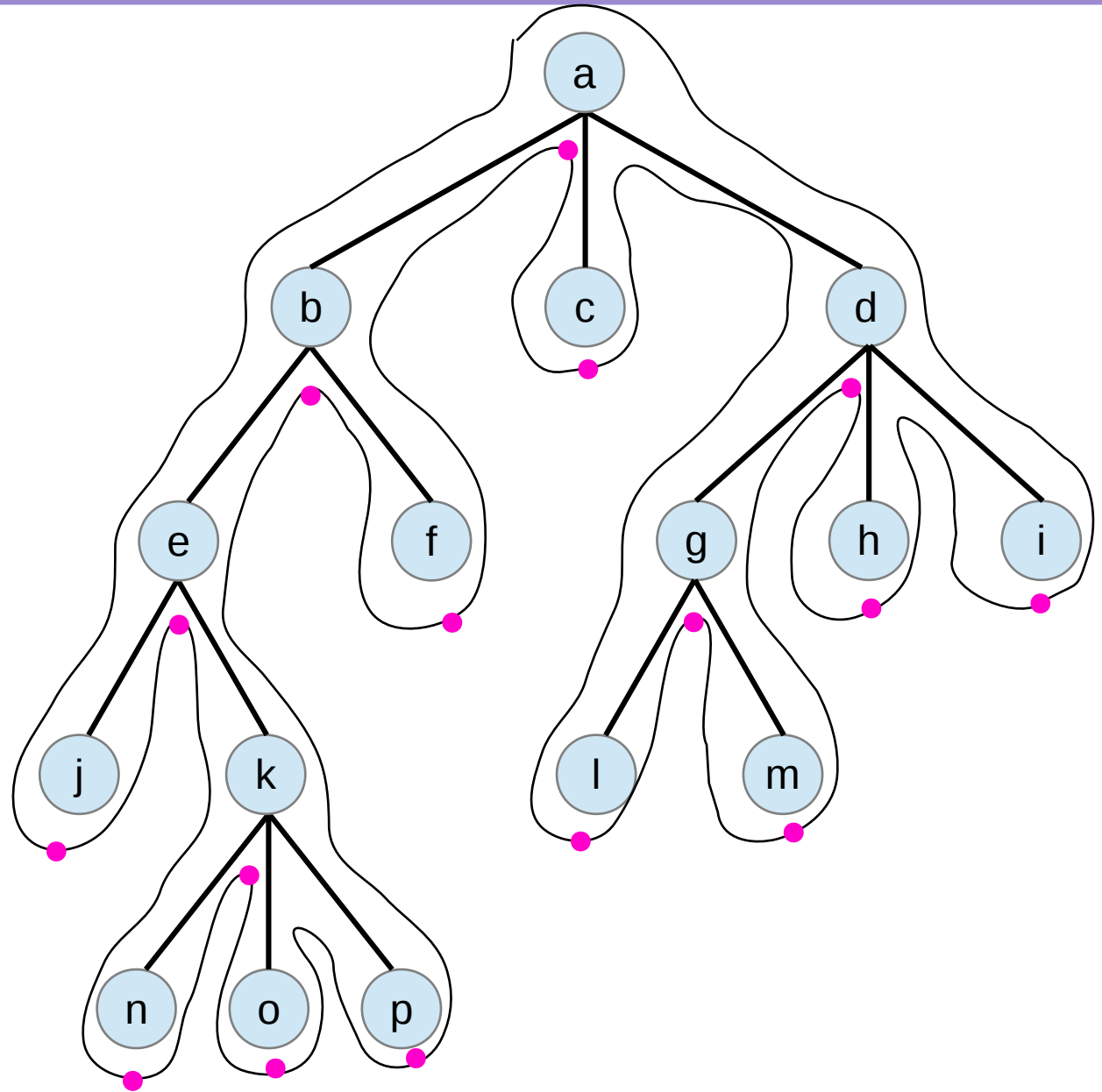
a-b-e-j-k-n-o-p-f-c-d-g-l-m-h-i



Rosen

In-Order Traversal on Ternary Trees

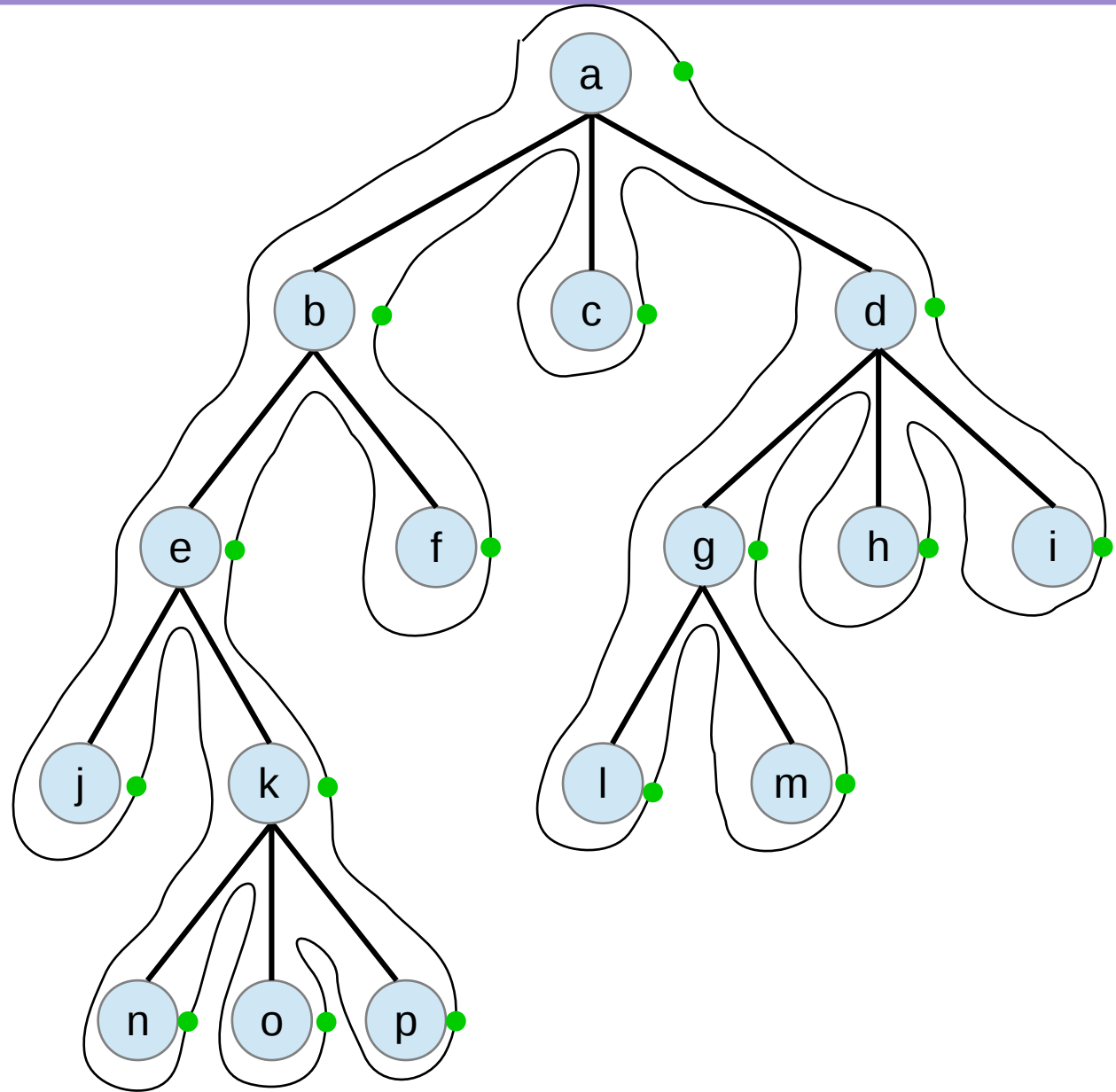
j-e-n-k-o-p-b-f-a-c-l-g-m-d-h-i



Rosen

Post-Order Traversal on Ternary Trees

j-n-o-p-k-e-f-b-c-l-m-g-h-i-d-a



Rosen

Ternary

Ternary

Etymology

Late Latin ternarius (“consisting of three things”), from terni (“three each”).

Adjective

ternary (not comparable)

Made up of three things; treble, triadic, triple, triplex

Arranged in groups of three

(mathematics) To the base three [quotations ▼]

(mathematics) Having three variables

<https://en.wiktionary.org/wiki/ternary>

The sequence continues with **quaternary**, **quinary**, **senary**, **septenary**, **octonary**, **nonary**, and **denary**, although most of these terms are rarely used. There's no word relating to the number eleven but there is one that relates to the number twelve: **duodenary**.

<https://en.oxforddictionaries.com/explore/what-comes-after-primary-secondary-tertiary>

References

[1] <http://en.wikipedia.org/>

[2]

Binary Search Tree (3A)

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Binary Search Tree (1)

Binary search trees (BST),
ordered binary trees
sorted binary trees

are a particular type of **container**:
data structures that store "items"
(such as numbers, names etc.) in memory.

They allow fast **lookup**, **addition** and **removal** of items
can be used to implement either dynamic sets of items
lookup tables that allow finding an item by its **key**
(e.g., finding the phone number of a person by name).

https://en.wikipedia.org/wiki/Binary_search_tree

Binary Search Tree (2)

keep their **keys** in sorted order
lookup operations can use
the principle of **binary search**

allowing to skip searching half of the tree
each operation (**lookup**, **insertion** or **deletion**)
takes time proportional to **log n**

much better than the **linear time**
but slower than the corresponding operations
on **hash tables**.

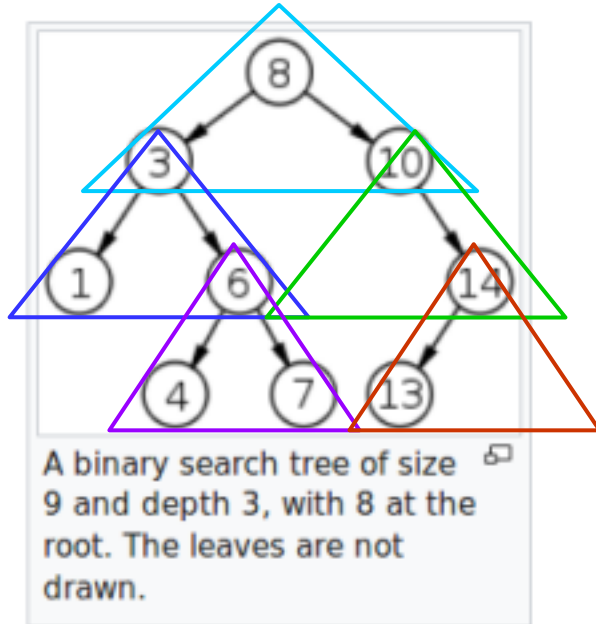
https://en.wikipedia.org/wiki/Binary_search_tree

Binary Search Tree (3)

when **looking** for a **key** in a tree
or **looking** for a **place** to insert a new key,
they traverse the tree from root to leaf,
making comparisons to keys stored in the nodes
deciding to continue in the **left** or **right subtrees**,
on the basis of the comparison.

https://en.wikipedia.org/wiki/Binary_search_tree

Node, Left Child, Right Child



$$3 < 8 < 10$$

$$1 < 3 < 6$$

$$10 < 14$$

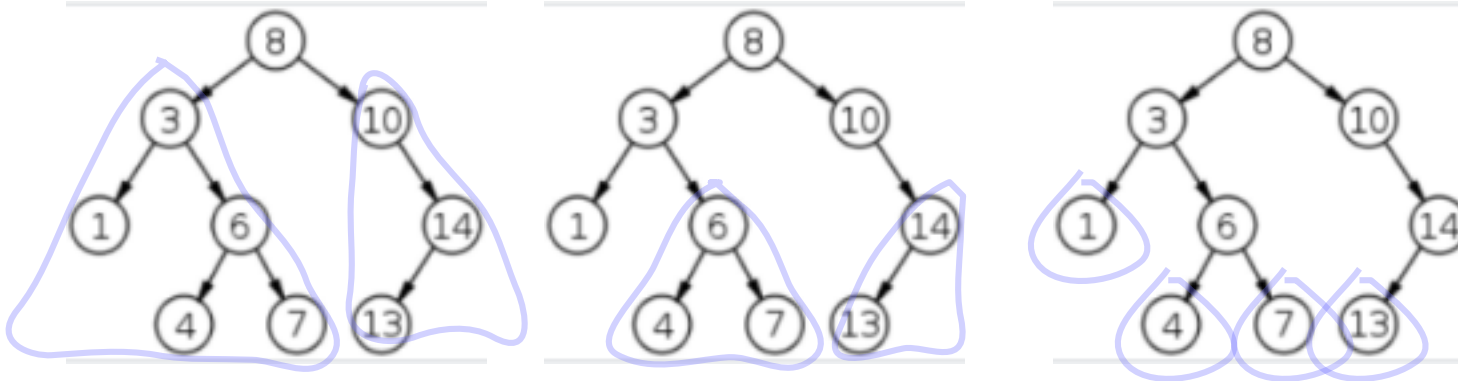
$$4 < 6 < 7$$

$$13 < 14$$

1, 3, 4, 6, 7, 8, 10, 13, 14

https://www.tutorialspoint.com/data_structures_algorithms/expression_parsing.html

Subtrees

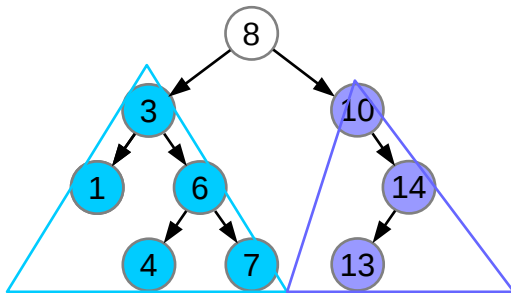


1, 3, 4, 6, 7, 8, 10, 13, 14

https://www.tutorialspoint.com/data_structures_algorithms/expression_parsing.html

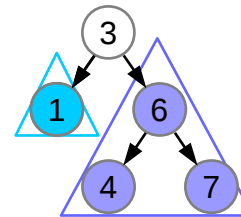
Node, Left Subtree, Right Subtree

$1, 3, 4, 6, 7 < 8 < 10, 13, 14$

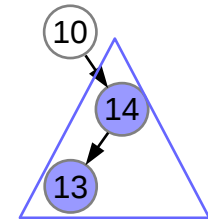


1, 3, 4, 6, 7, 8, 10, 13, 14

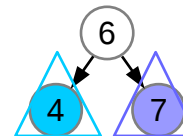
$1 < 3 < 4, 6, 7$



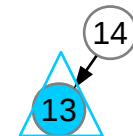
$10 < 13, 14$



$4 < 6 < 7$

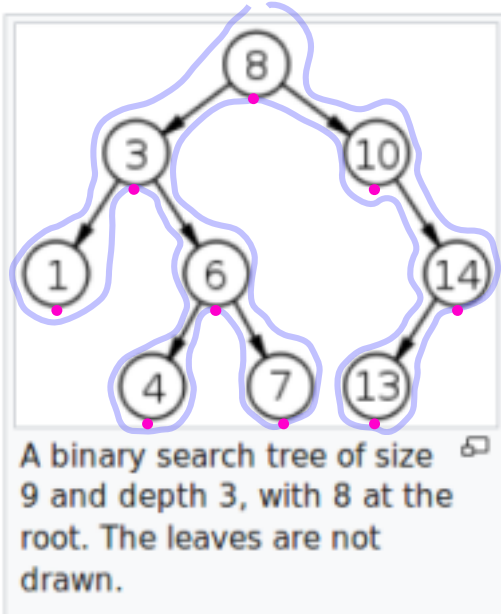


$13 < 14$



https://www.tutorialspoint.com/data_structures_algorithms/expression_parsing.html

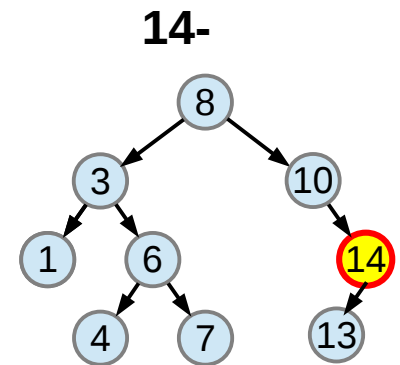
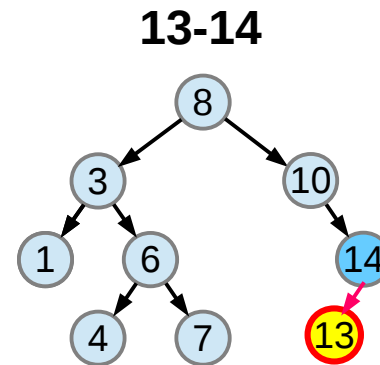
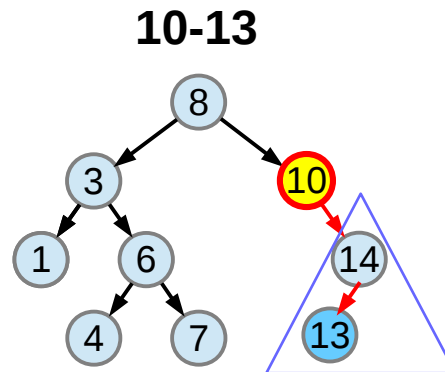
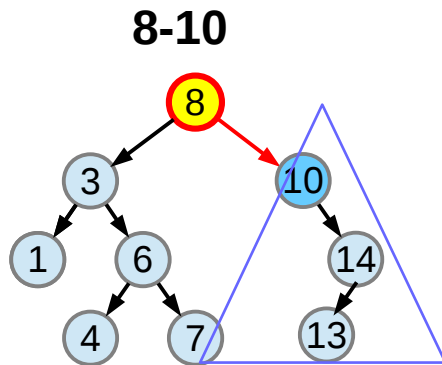
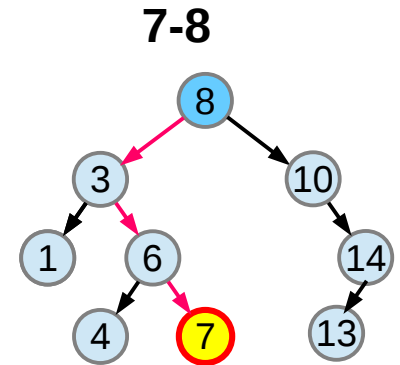
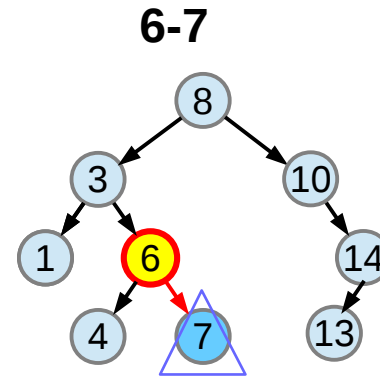
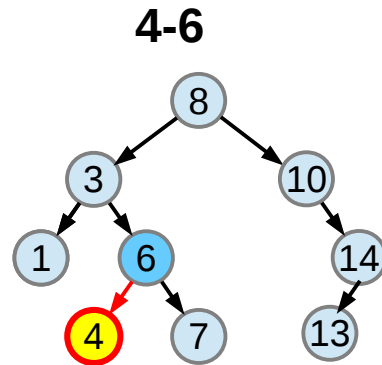
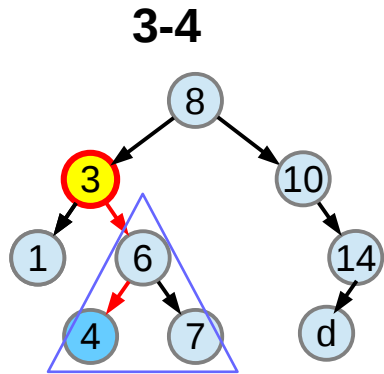
In-Order Traversal



1, 3, 4, 6, 7, 8, 10, 13, 14

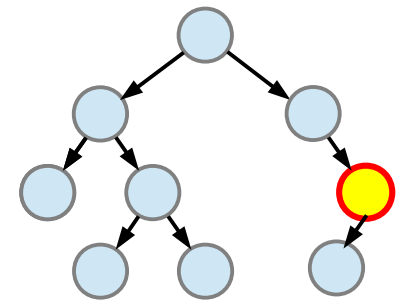
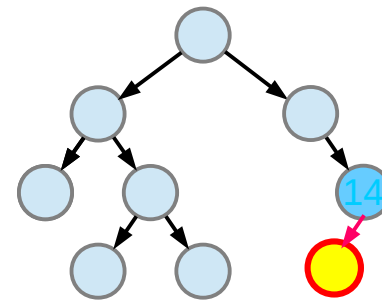
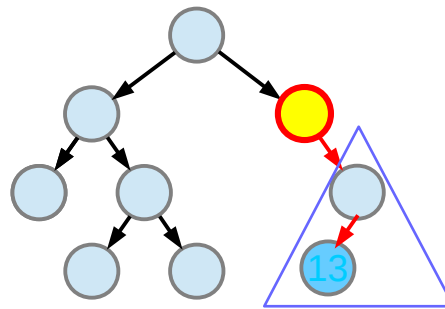
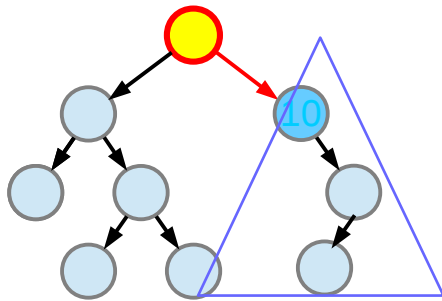
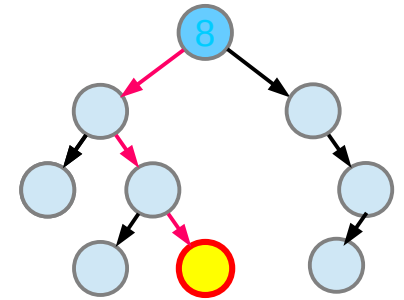
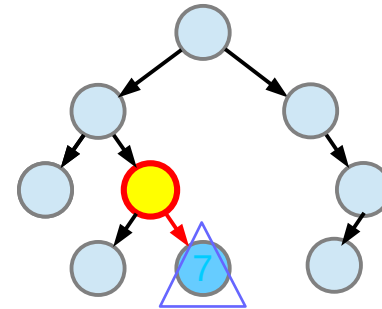
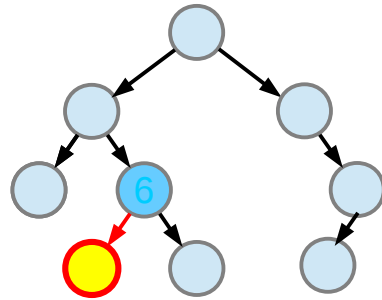
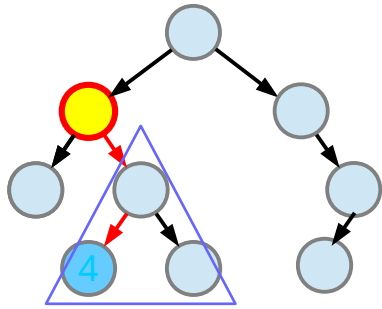
https://www.tutorialspoint.com/data_structures_algorithms/expression_parsing.html

Successor Examples (1)



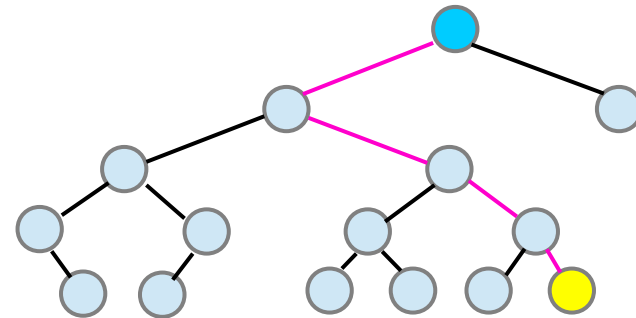
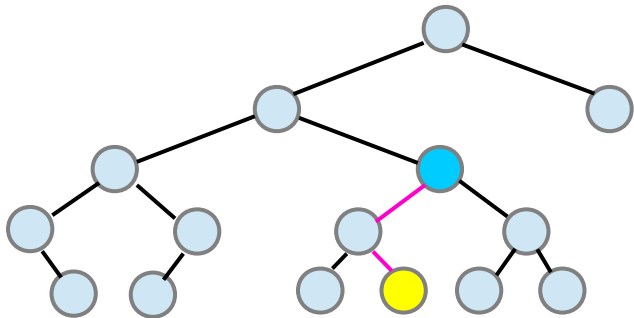
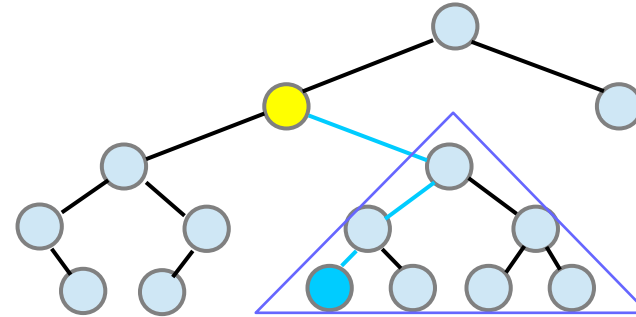
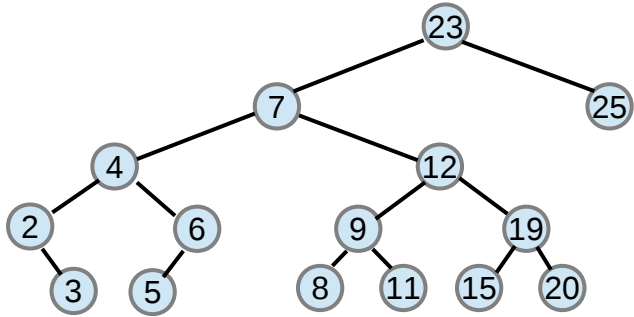
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Successor Examples (2)



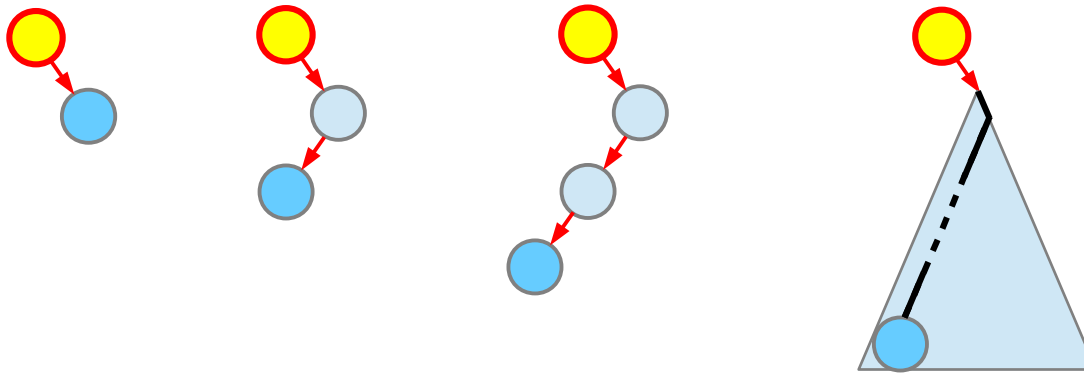
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Successor Examples (3)

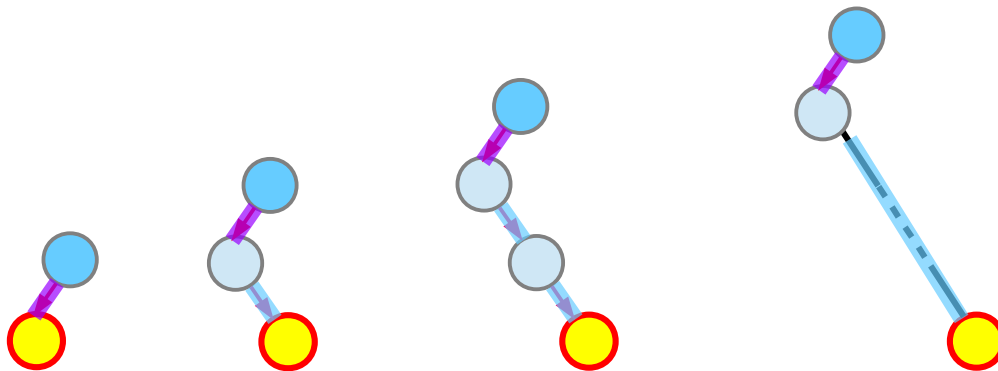


<https://www.cs.rochester.edu/~gildea/csc282/slides/C12-bst.pdf>

Successor Cases



If the right child exists,
then the minimum
in the **right** subtree
– the **leftmost** node

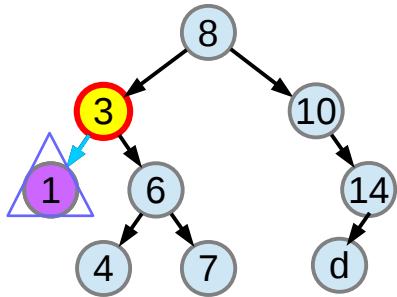


the **parent** of the farthest
node that can be reached
by following only **right**
edges **backward**.

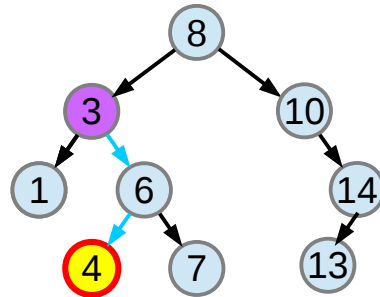
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Predecessor Examples (1)

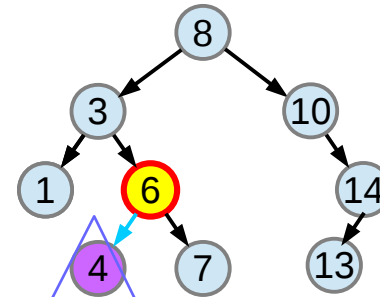
1-3



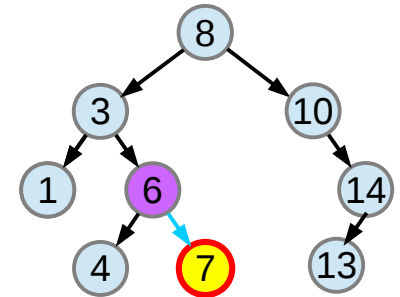
3-4



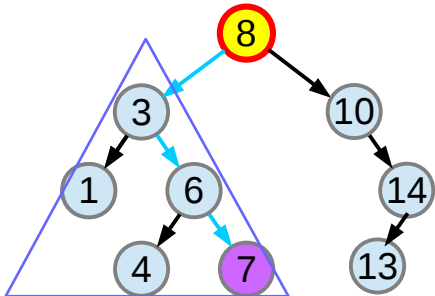
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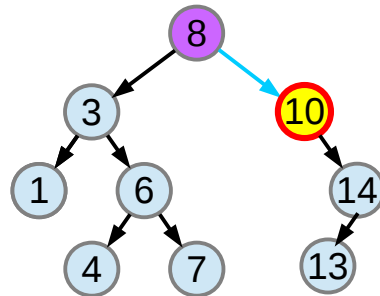
6-7



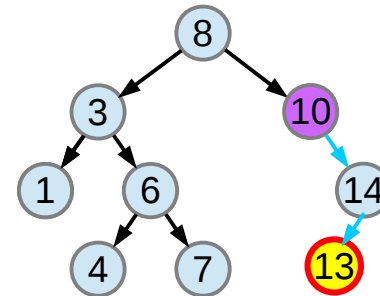
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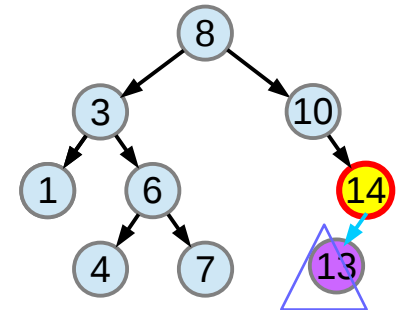
8-10



10-13

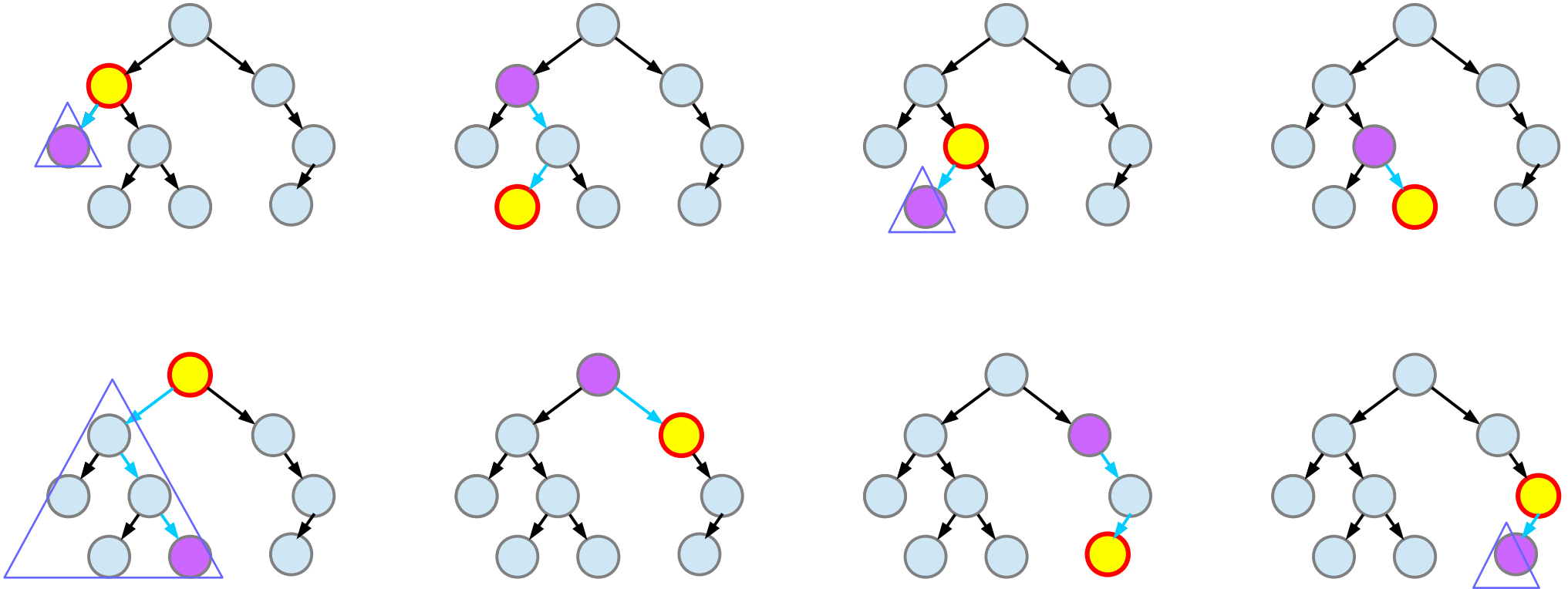


13-14



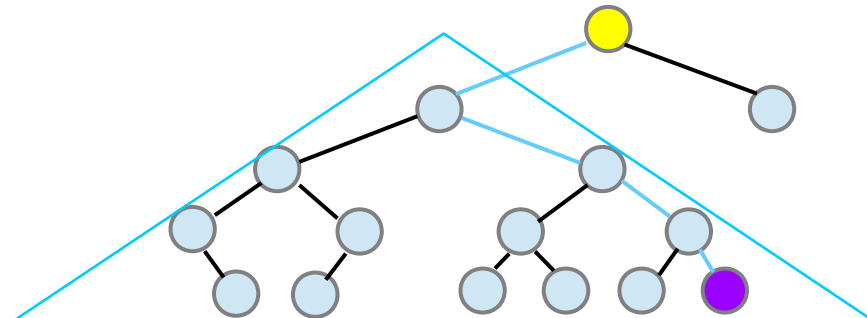
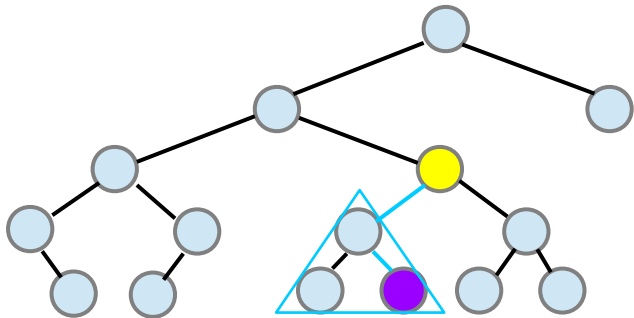
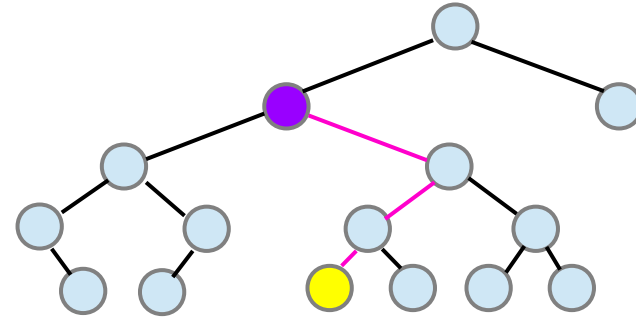
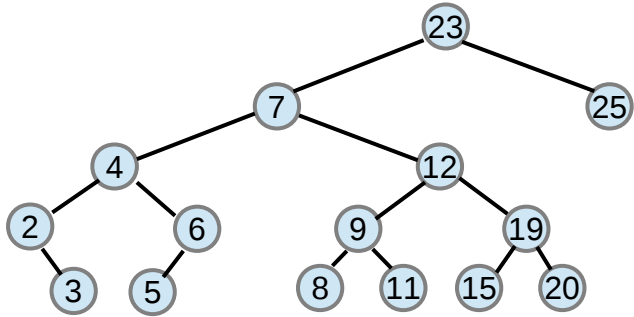
https://www.tutorialspoint.com/data_structures_algorithms/expression_parsing.html

Predecessor Examples (2)



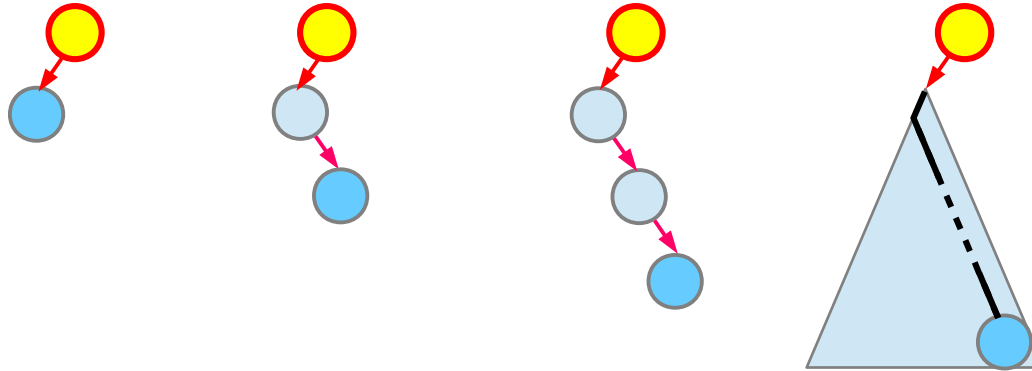
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Predecessor Examples (3)

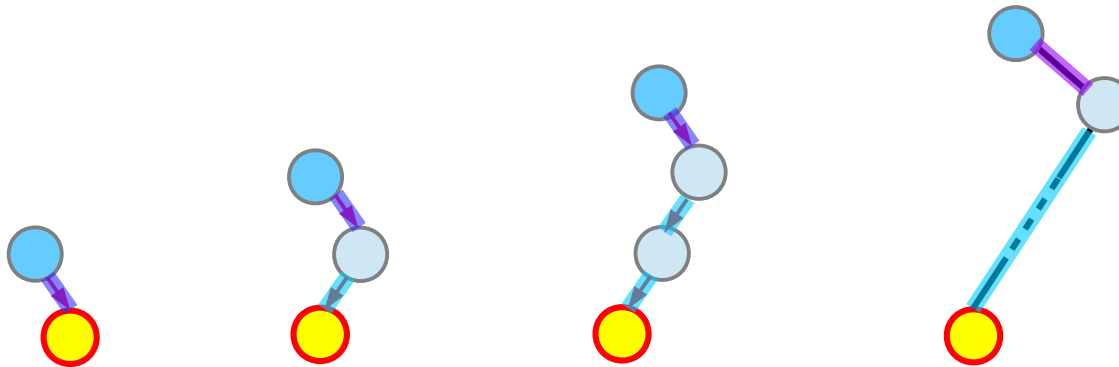


<https://www.cs.rochester.edu/~gildea/csc282/slides/C12-bst.pdf>

Predecessor Cases



If the left child exists, then the maximum in the **left** subtree – the **rightmost** node

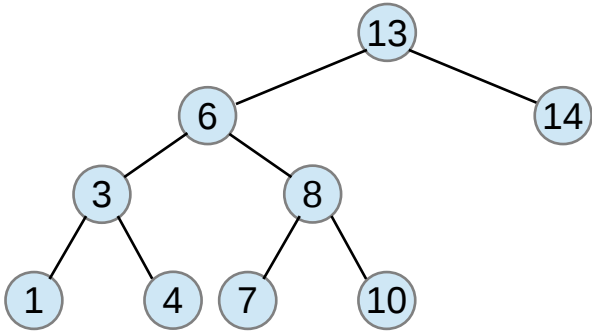


the **parent** of the farthest node that can be reached by following only **left** edges **backward**.

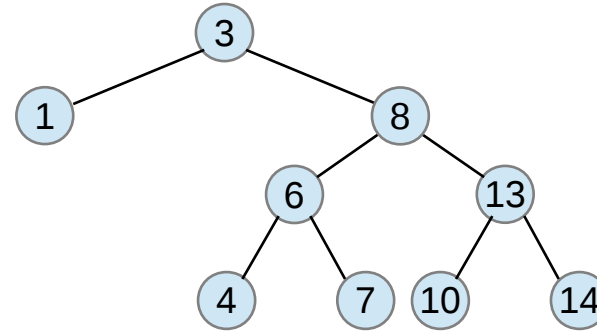
https://www.tutorialspoint.com/data_structures_algorithms/expression_parsing.html

Different BST's with the same data

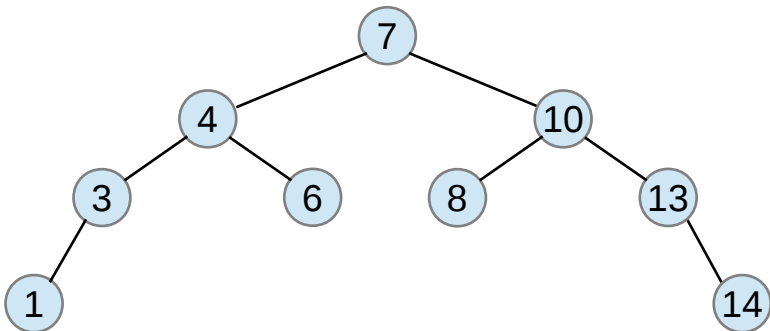
1, 3, 4, 6, 7, 8, 10, 13, 14



1, 3, 4, 6, 7, 8, 10, 13, 14

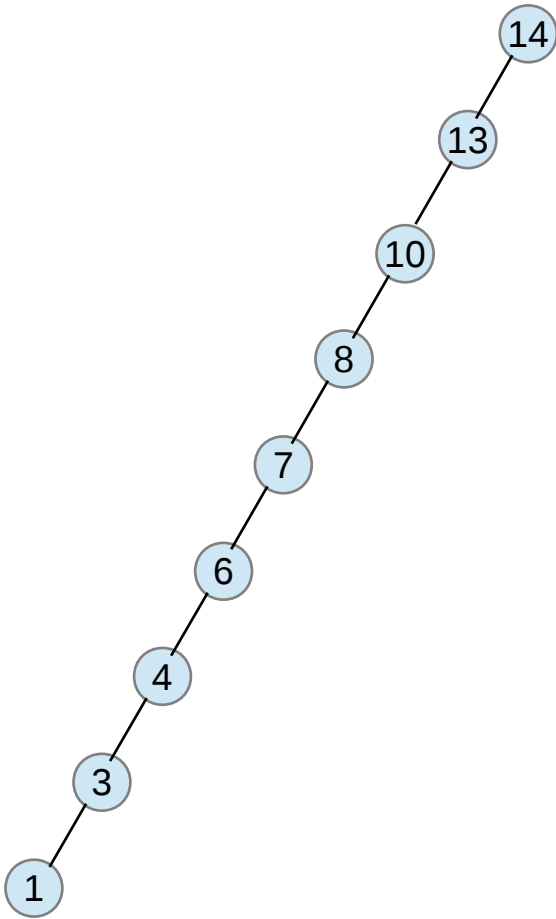


1, 3, 4, 6, 7, 8, 10, 13, 14

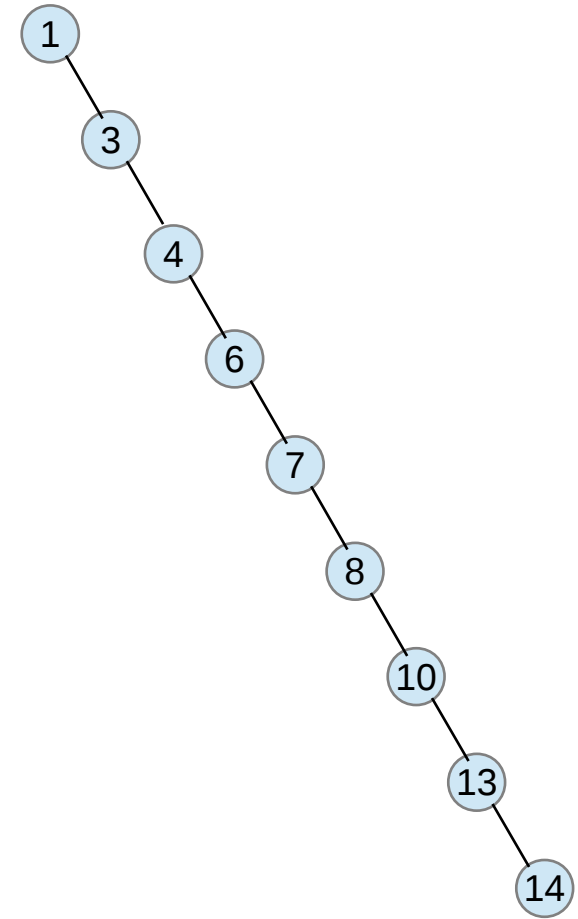


Unbalanced BSTs

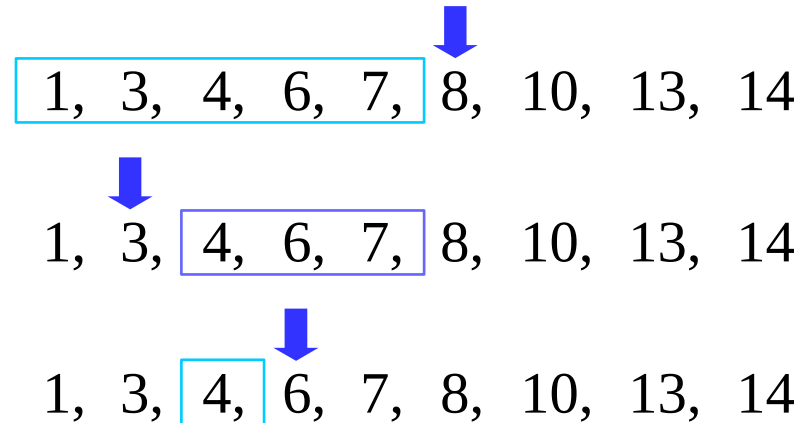
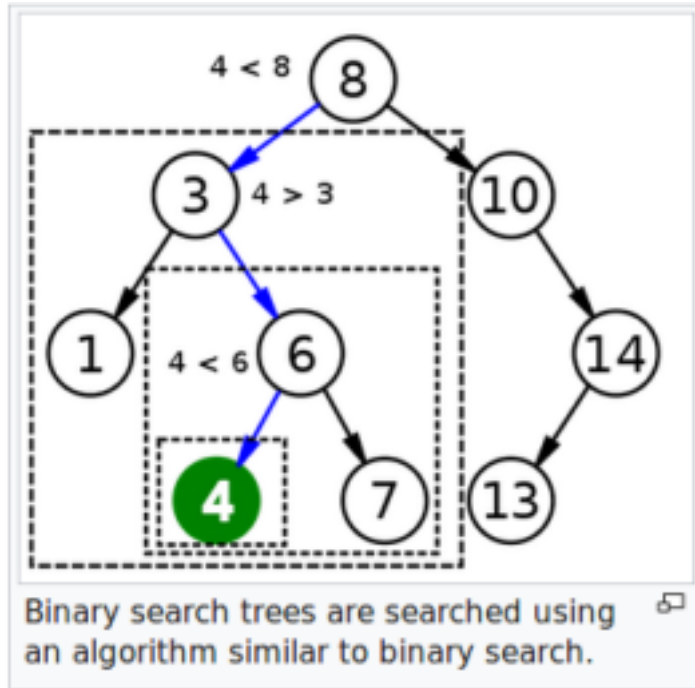
1, 3, 4, 6, 7, 8, 10, 13, 14



1, 3, 4, 6, 7, 8, 10, 13, 14



Binary Search on a Binary Search Tree



https://en.wikipedia.org/wiki/Binary_search_algorithm

Insertion

Insertion begins as a **search** would begin;
if the key is not equal to that of the **root**,
we search the **left** or **right** subtrees as before.

at an **leaf node**, **add** the new key-value pair
as its **right** or **left child**,
depending on the node's **key**.

first examine the **root**
and recursively insert the new node
to the **left** subtree if its key is less than that of the **root**,
or the **right** subtree if its key is greater than or equal to the **root**.

https://en.wikipedia.org/wiki/Binary_search_tree

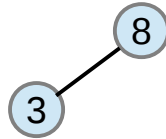
Insertion Example (1)

Insert(8 → 3 → 10 → 1 → 6 → 4 → 7 → 14 → 13)

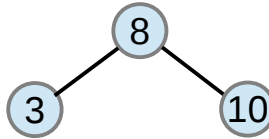
insert(8)



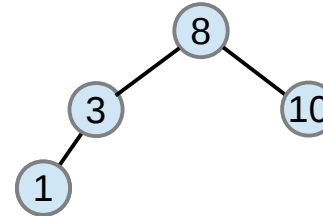
insert(3)



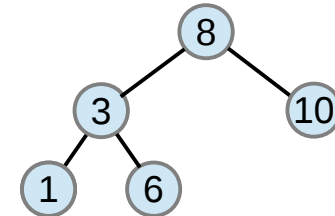
insert(10)



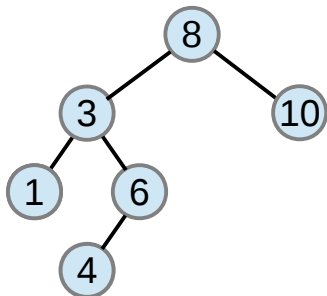
insert(1)



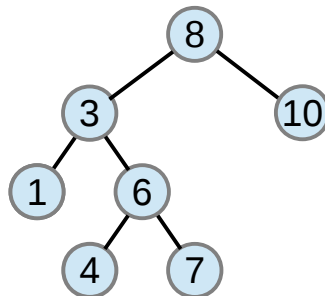
insert(6)



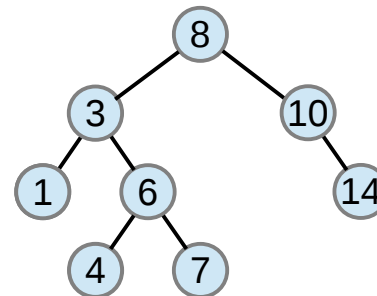
insert(4)



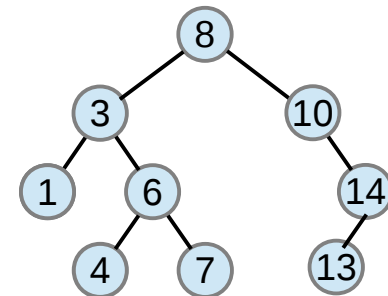
insert(7)



insert(14)



insert(13)



Insertion Example (2)

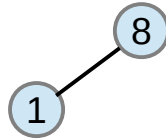
Insert(8 → 3 → 10 → 1 → 6 → 4 → 7 → 14 → 13)

Insert(8 → 1 → 10 → 3 → 6 → 4 → 7 → 13 → 14)

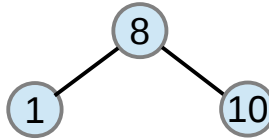
insert(8)



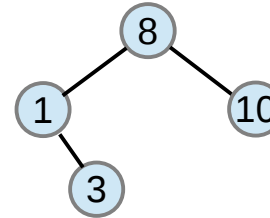
insert(1)



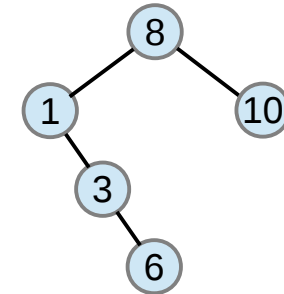
insert(10)



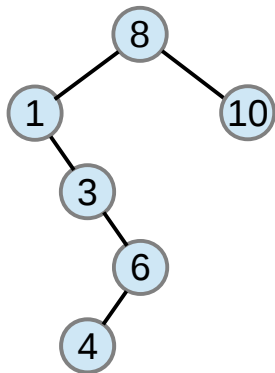
insert(3)



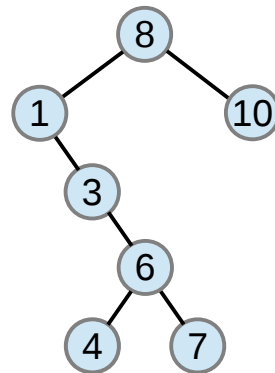
insert(6)



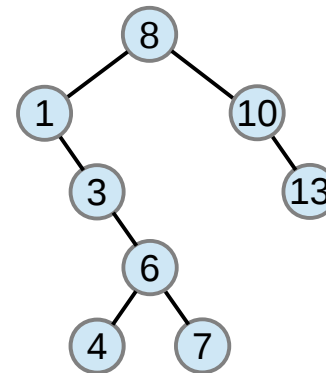
insert(4)



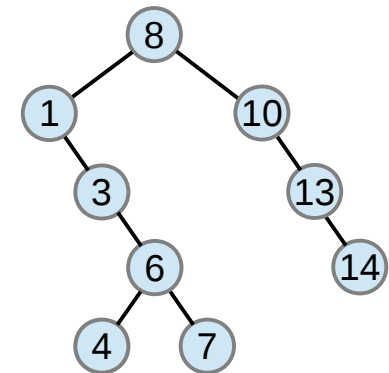
insert(7)



insert(13)



insert(14)



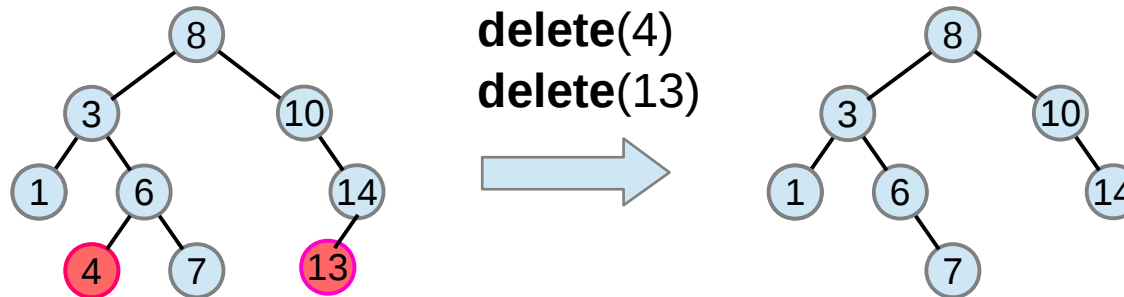
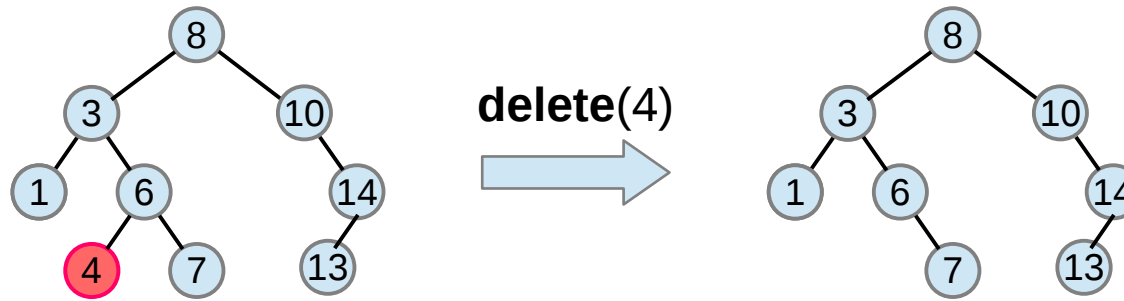
Deletion

1. Deleting a **node** with no children:
simply remove the node from the tree.
2. Deleting a **node** with one child:
remove the node and replace it with its child.
3. Deleting a **node** with two children:
call the **node** to be deleted D.
Do not delete D.
Instead, choose either its in-order **predecessor node** 3(a)
or its in-order **successor node** as replacement node E. 3(b)
Copy the user values of E to D
If E does not have a **child**
 simply remove E from its previous parent G.
If E has a **child**, say F, it is a right child.
 Replace E with F at E's parent.

https://en.wikipedia.org/wiki/Binary_search_tree

Deletion – Case 1

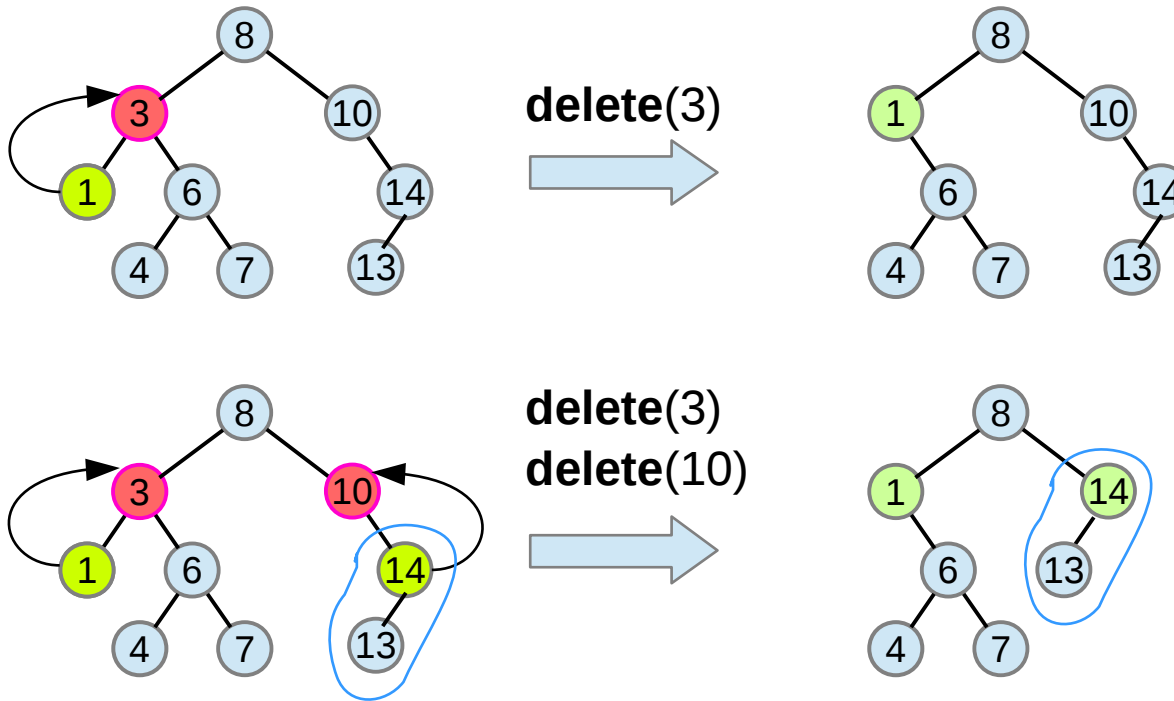
1. Deleting a node with no children:
simply remove the node from the tree.



https://en.wikipedia.org/wiki/Binary_search_tree

Deletion – Case 2

2. Deleting a node with one child:
remove the node and replace it with its child.



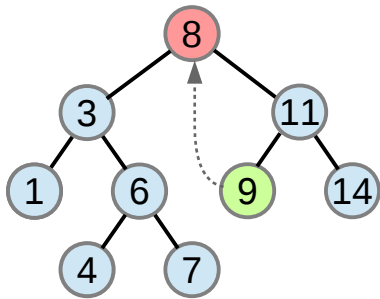
https://en.wikipedia.org/wiki/Binary_search_tree

Deletion – Case 3 : using a successor

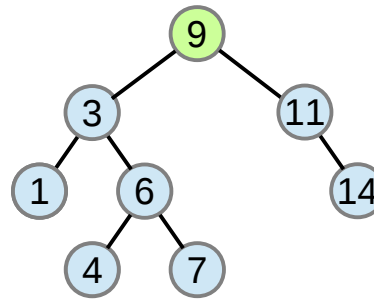
3. Deleting a node with two children:

call the **node** to be deleted **D**.

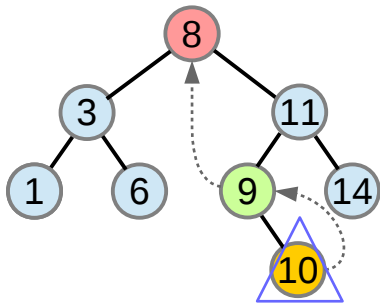
its in-order **successor node** as **E**. Copy E to D



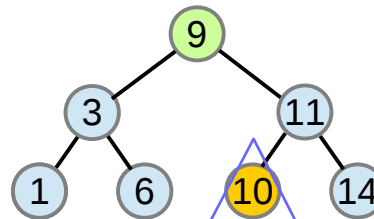
delete(8)



Leftmost
E has no **child**
simply remove E
from its parent **G**.



delete(8)



Leftmost
E has a child **F**
it is a **right** child
replace **E** with **F**
at **E**'s parent.

https://en.wikipedia.org/wiki/Binary_search_tree

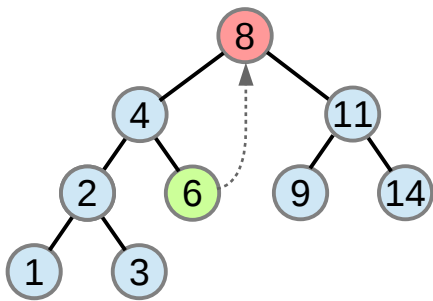
Deletion – Case 3 : using a predecessor

3. Deleting a node with two children:

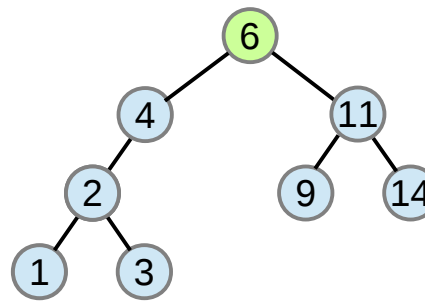
call the **node** to be deleted **D**.

its in-order predecessor node as **E**.

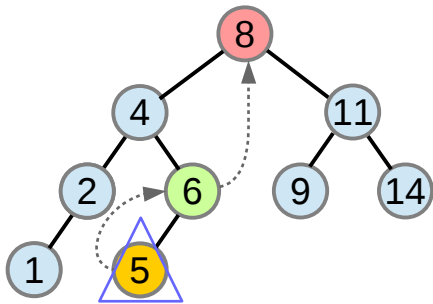
Copy E to D



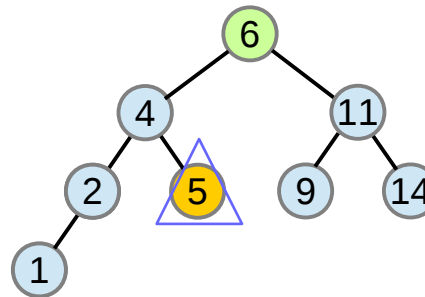
delete(8)



Rightmost **E** has no **child** simply remove E from its parent **G**.



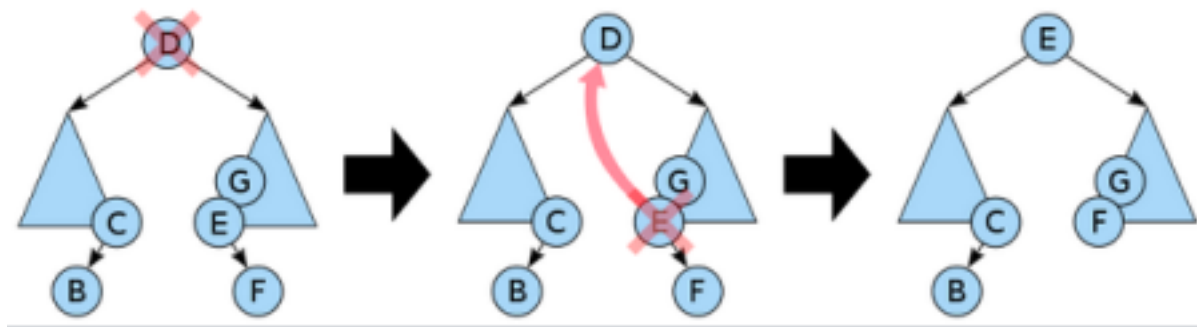
delete(8)



Rightmost **E** has a child **F** it is a **left** child replace **E** with **F** at **E**'s parent.

https://en.wikipedia.org/wiki/Binary_search_tree

Deletion



Deleting a **node** with **two children** from a binary search tree. First the **leftmost** node in the **right** subtree, the in-order **successor E**, is identified. Its value is **copied** into the **node D** being deleted. The in-order successor can then be easily deleted because it has at most one child. The same method works symmetrically using the in-order **predecessor C**.

https://en.wikipedia.org/wiki/Binary_search_tree

References

[1] <http://en.wikipedia.org/>

[2]

Finite State Machine (1A)

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Please send corrections (or suggestions) to youngwlim@hotmail.com.

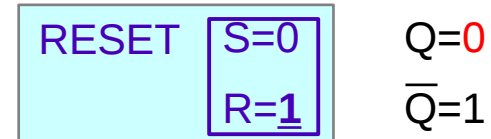
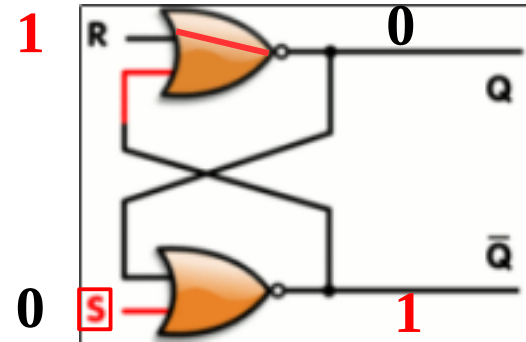
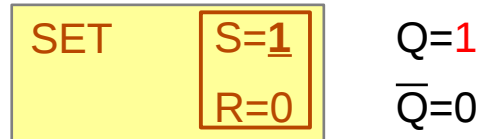
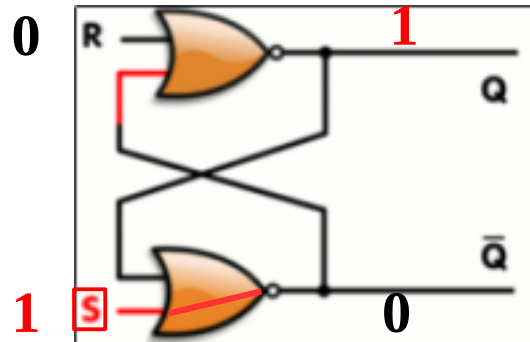
This document was produced by using LibreOffice and Octave.

FSM and Digital Logic Circuits

- Latch
- D FlipFlop
- Registers
- Timing
- Mealy machine
- Moore machine
- Traffic Lights Examples

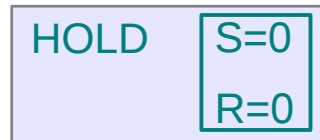
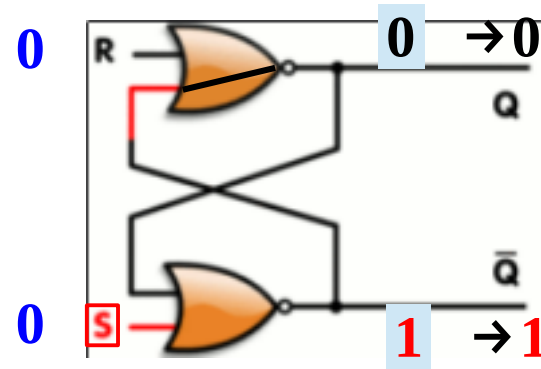
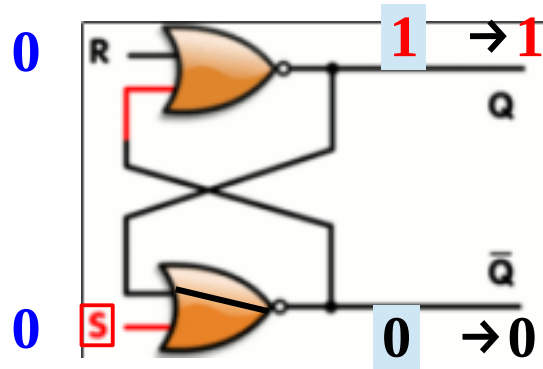
https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

NOR-based SR Latch - SET / RESET

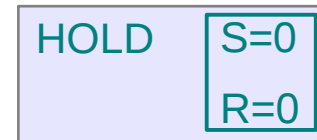


[https://en.wikipedia.org/wiki/Flip-flop_\(electronics\)](https://en.wikipedia.org/wiki/Flip-flop_(electronics))

NOR-based SR Latch - HOLD



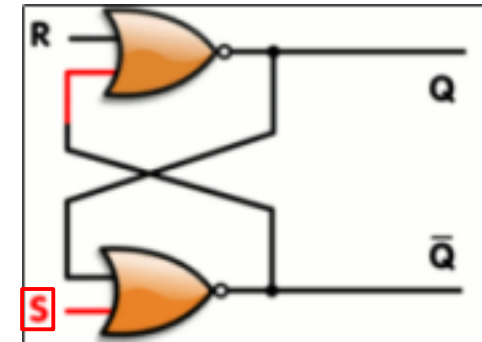
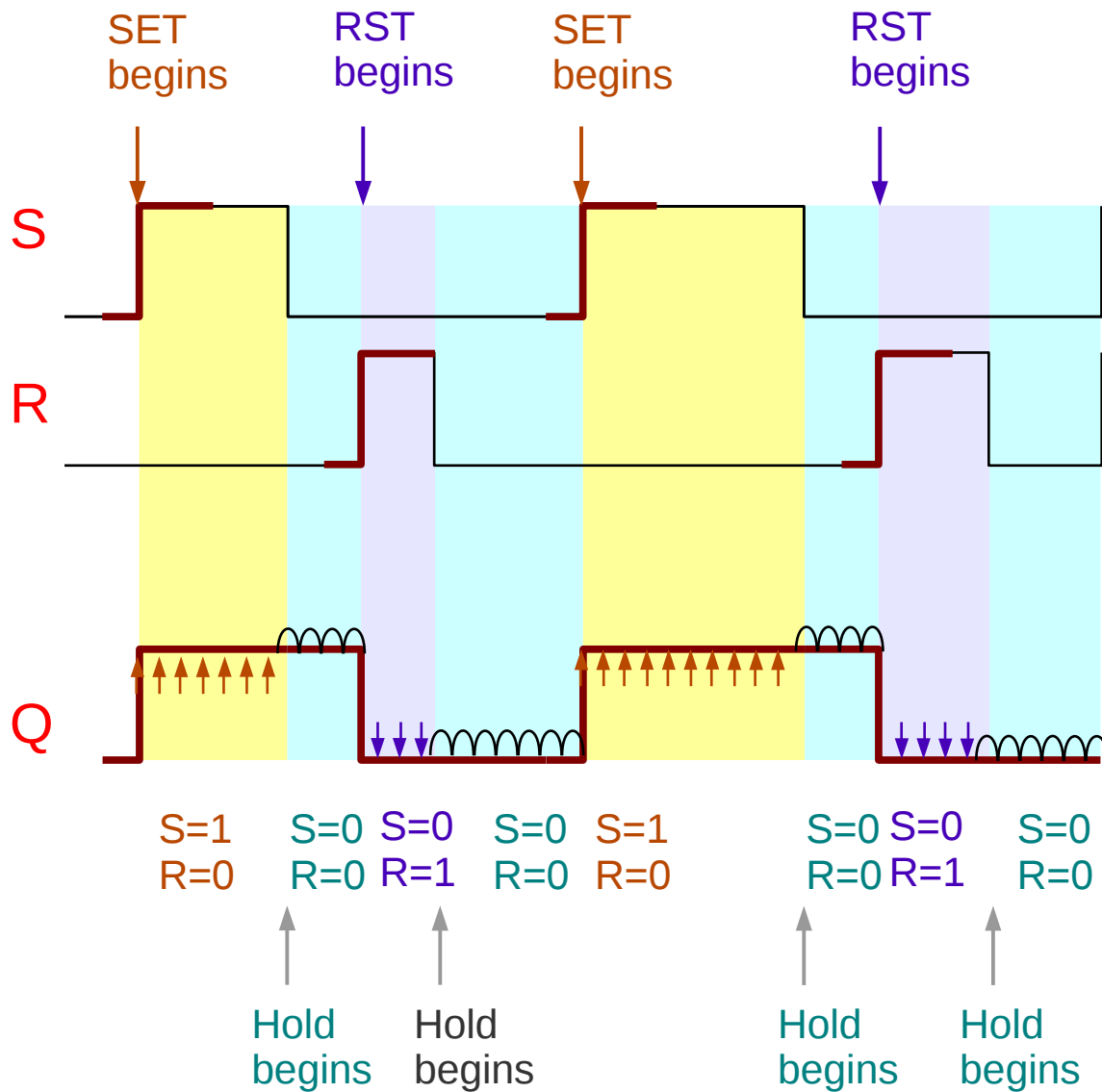
Q=old Q
 \bar{Q} =old \bar{Q}



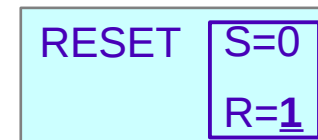
Q=old Q
 \bar{Q} =old \bar{Q}

[https://en.wikipedia.org/wiki/Flip-flop_\(electronics\)](https://en.wikipedia.org/wiki/Flip-flop_(electronics))

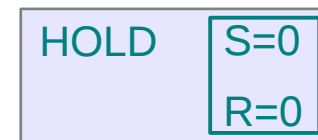
NOR-based SR Latch



Q=1
Q-bar=0



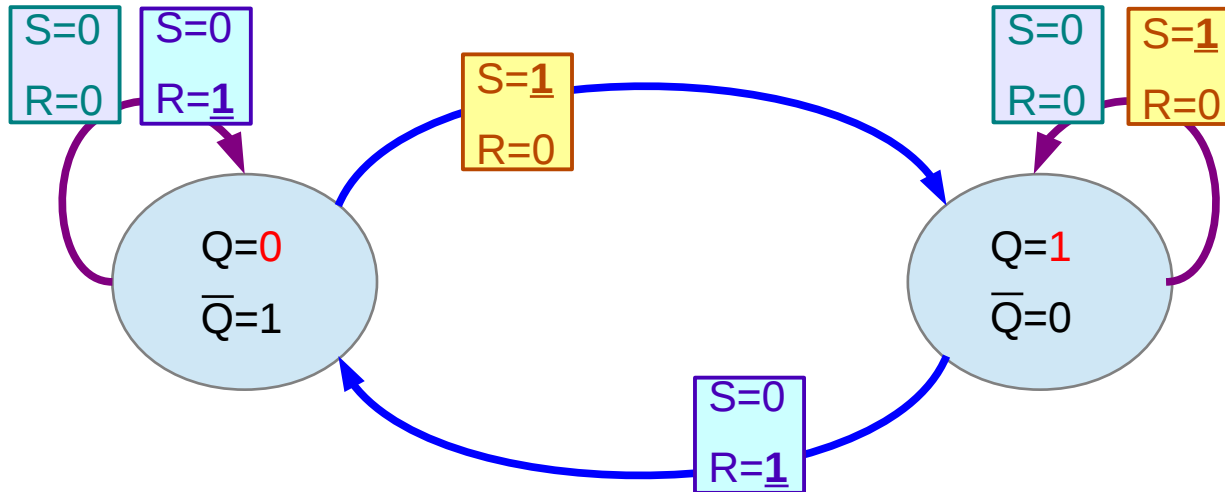
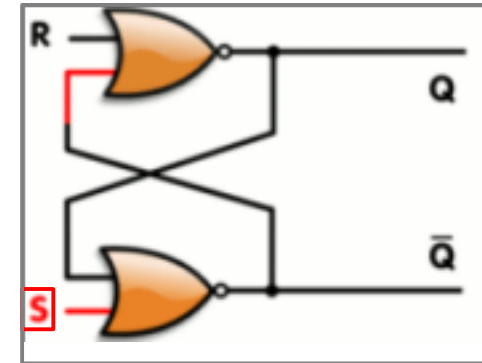
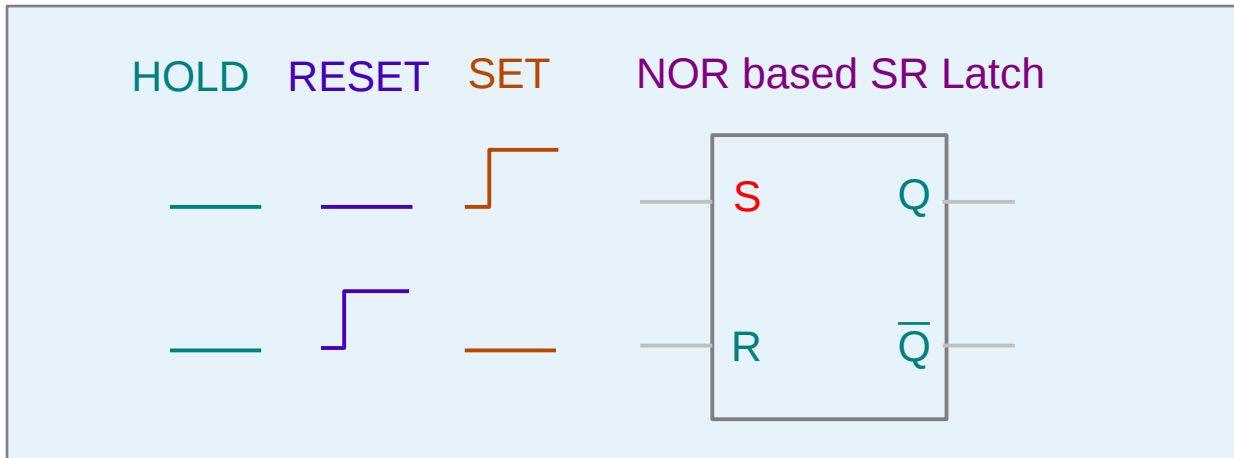
Q=0
Q-bar=1



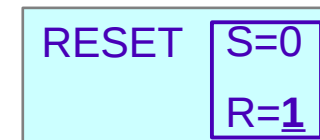
Q=old Q
Q-bar=old Q-bar

https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

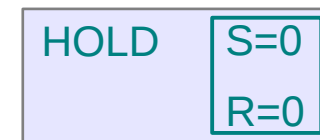
NOR-based SR Latch States



Q=1
Q-bar=0



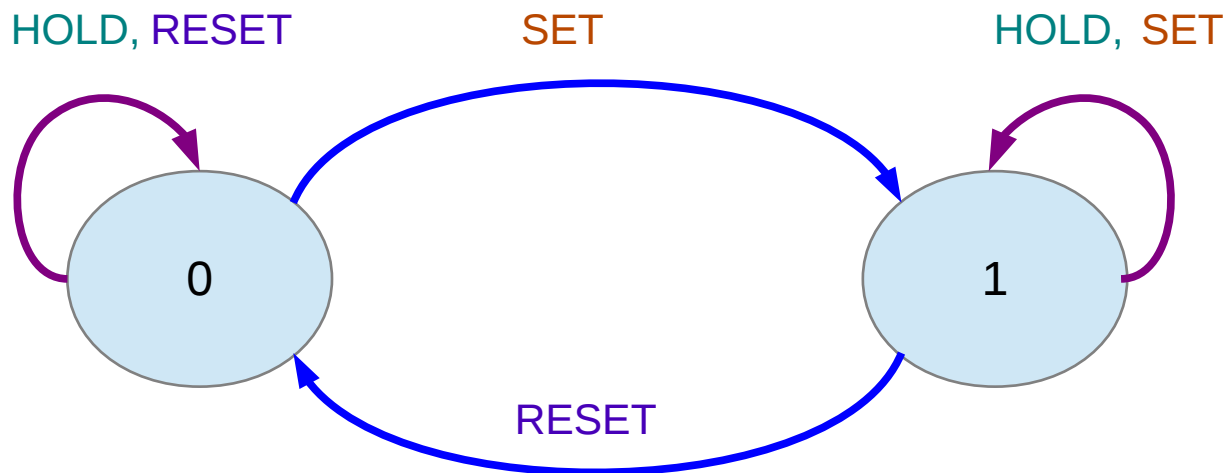
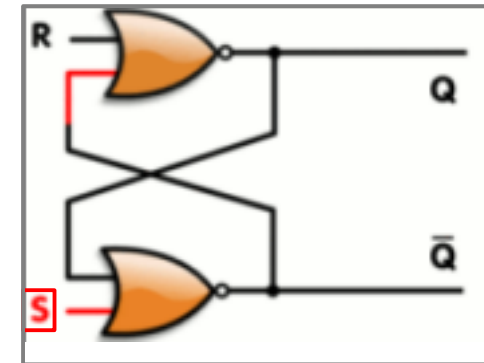
Q=0
Q-bar=1



Q=old Q
Q-bar=old Q-bar

https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

SR Latch States



SET	S= <u>1</u> R=0	Q=1 \bar{Q} =0
RESET	S=0 R= <u>1</u>	Q=0 \bar{Q} =1
HOLD	S=0 R=0	Q=old Q \bar{Q} =old \bar{Q}

https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

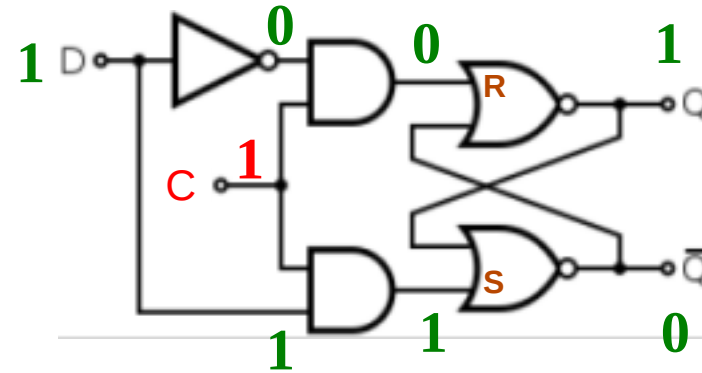
NOR-based D Latch - SET / RESET

[https://en.wikipedia.org/wiki/Flip-flop_\(electronics\)](https://en.wikipedia.org/wiki/Flip-flop_(electronics))

D=1
C=1

SET
S=1
R=0

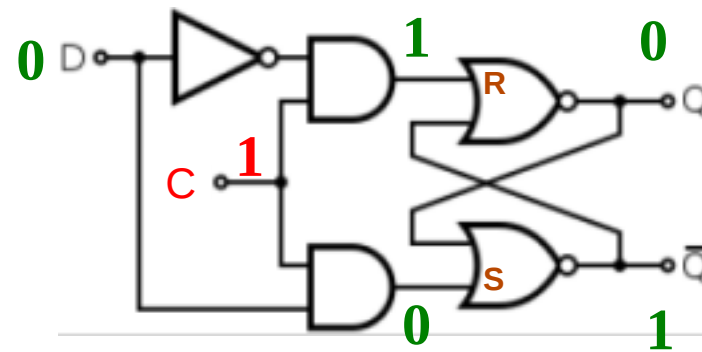
Q=1
 $\bar{Q}=0$



D=0
C=1

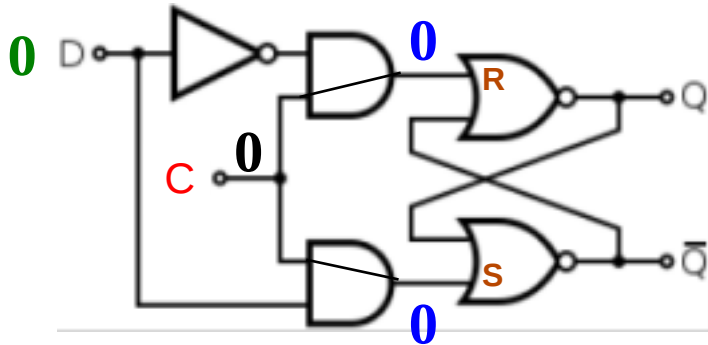
RESET
S=0
R=1

Q=0
 $\bar{Q}=1$



NOR-based D Latch - HOLD

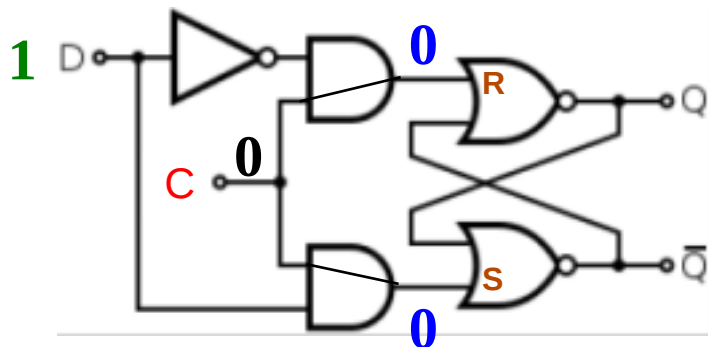
[https://en.wikipedia.org/wiki/Flip-flop_\(electronics\)](https://en.wikipedia.org/wiki/Flip-flop_(electronics))



$D=X$
 $C=0$

HOLD $S=0$
 $R=0$

$Q=old\ Q$
 $\bar{Q}=old\ \bar{Q}$



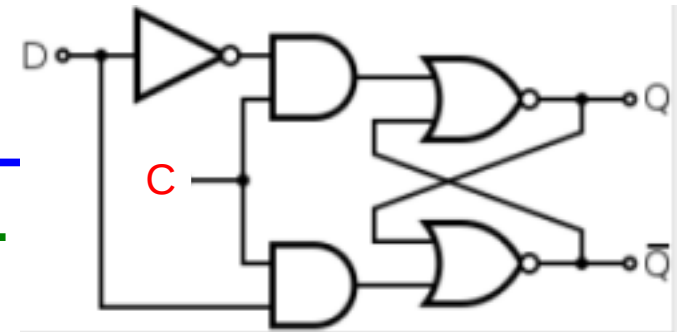
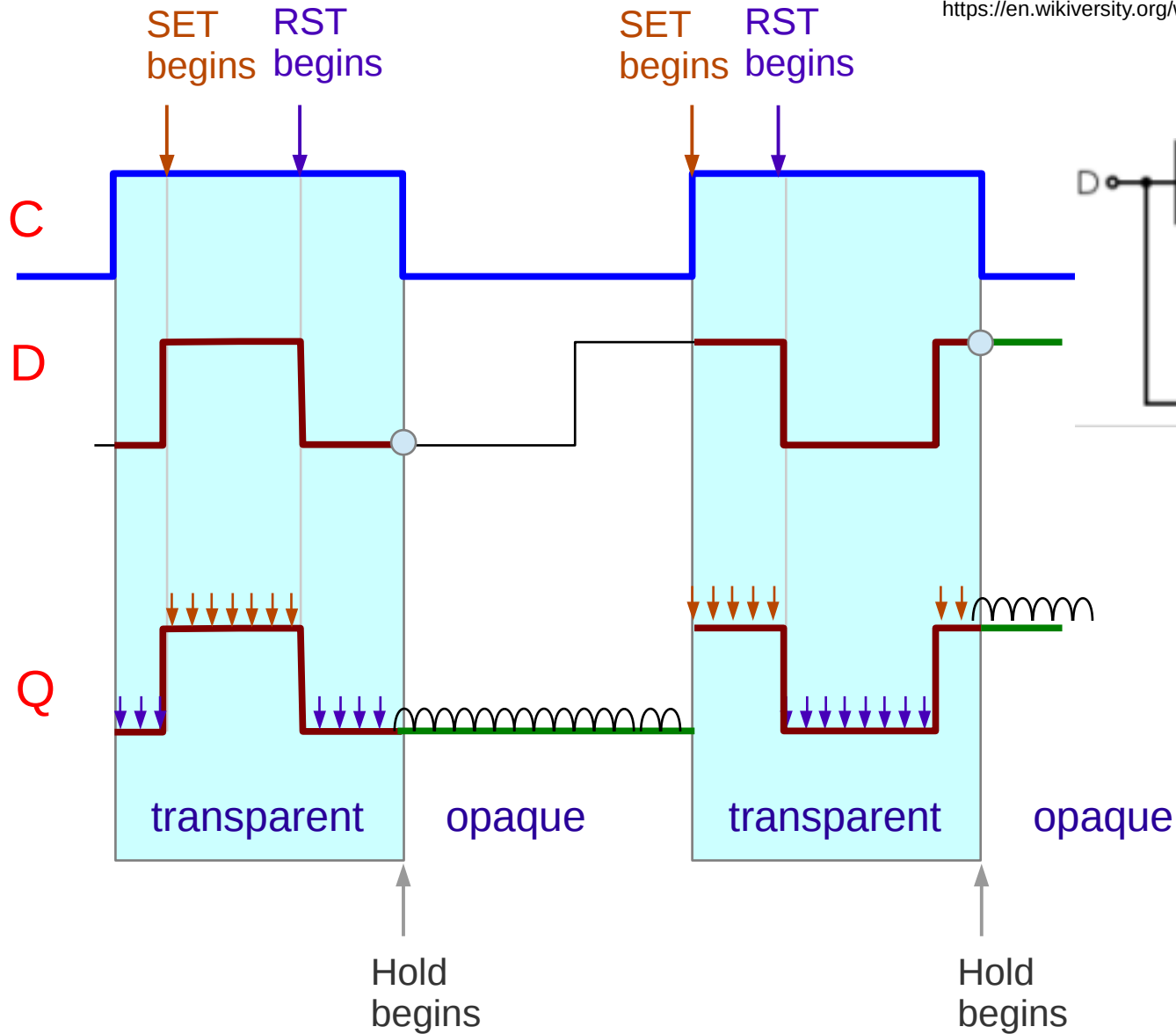
$D=X$
 $C=0$

HOLD $S=0$
 $R=0$

$Q=old\ Q$
 $\bar{Q}=old\ \bar{Q}$

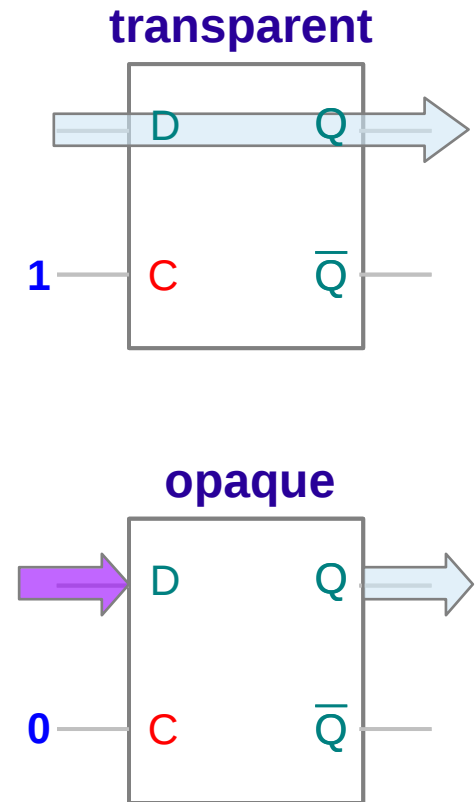
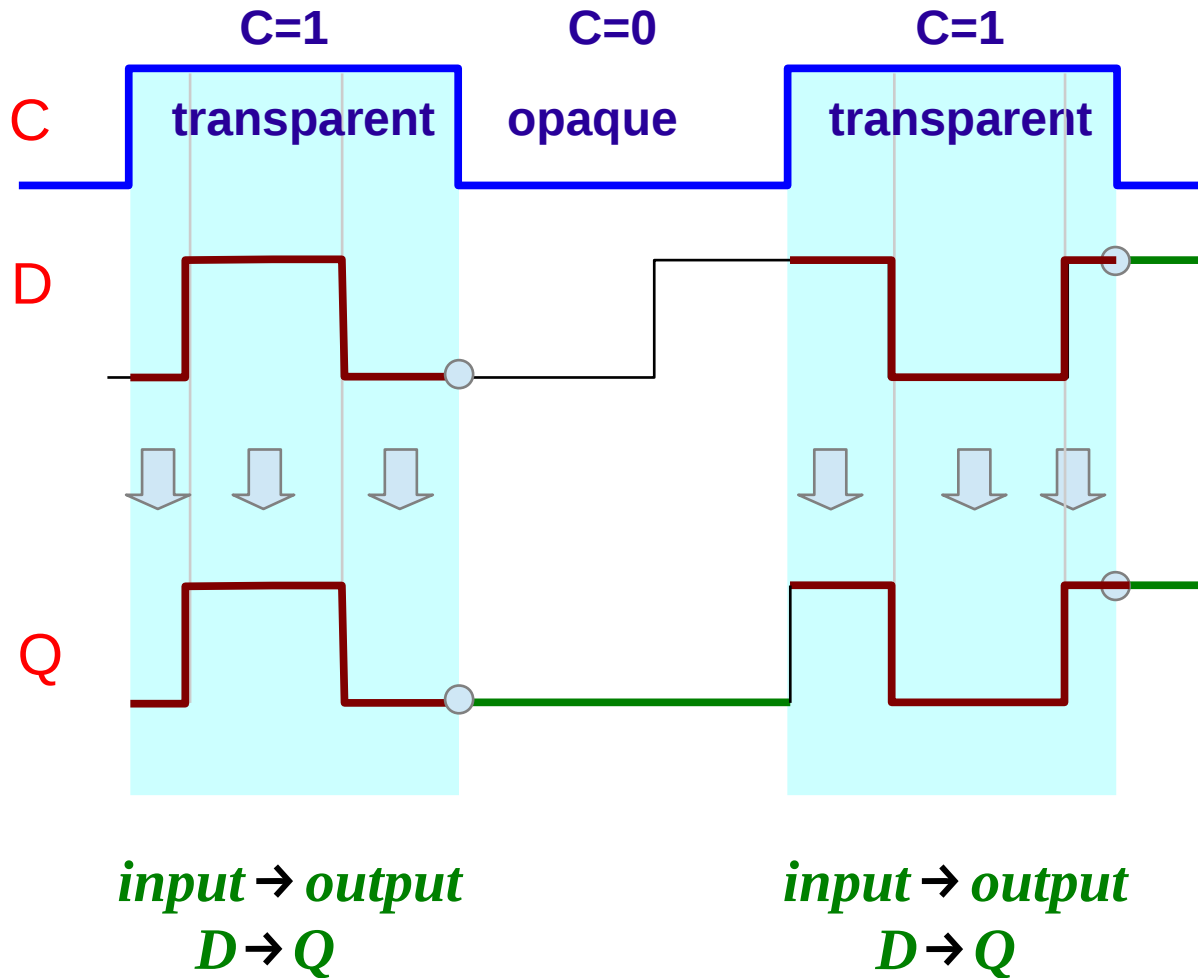
NOR-based D Latch - Set / Reset / Hold

https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

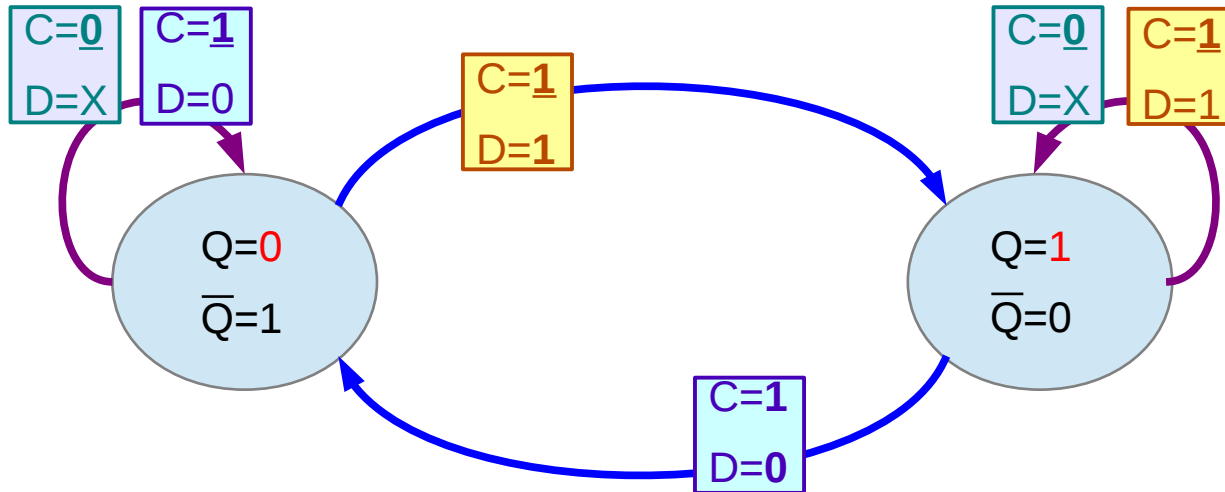
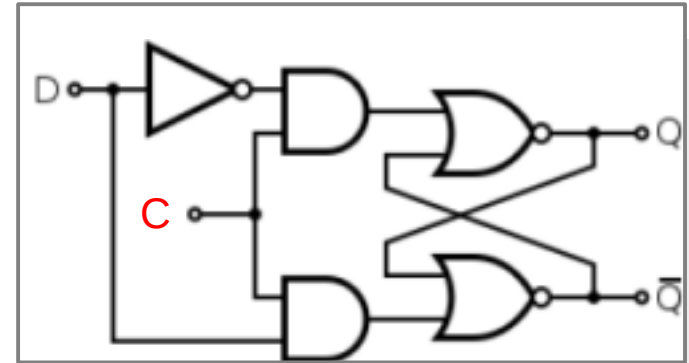
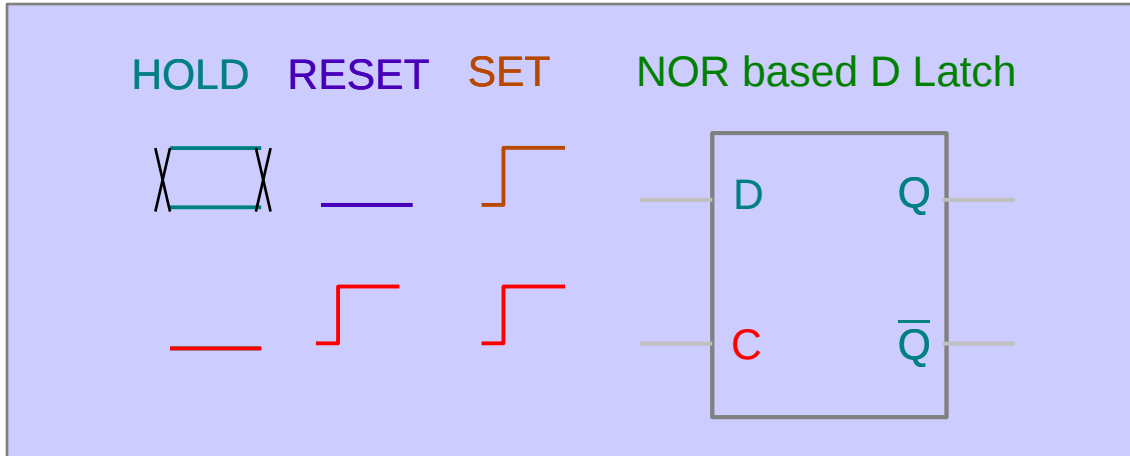


NOR-based D Latch - transparent / opaque

https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

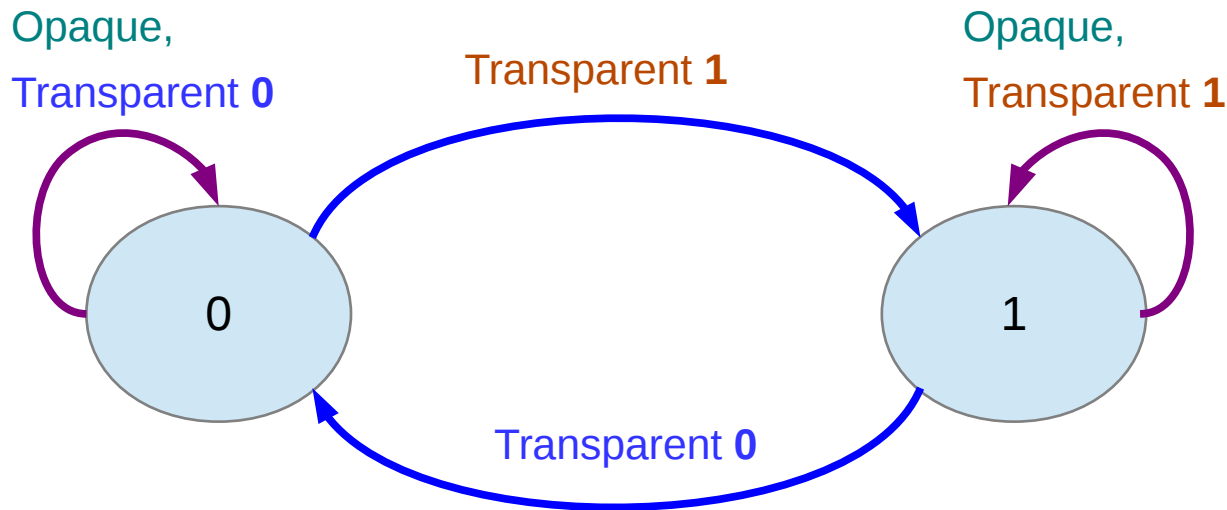
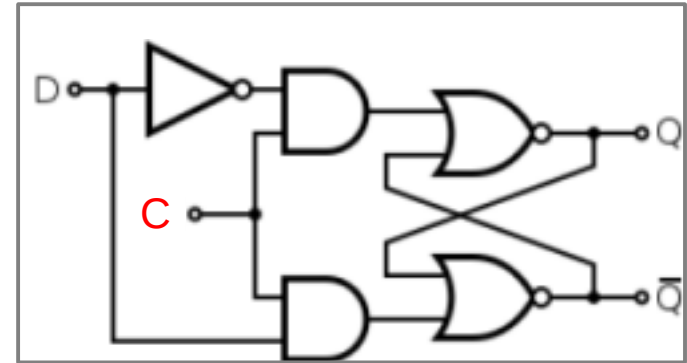


NOR-based D Latch States



https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

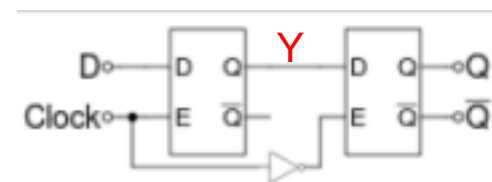
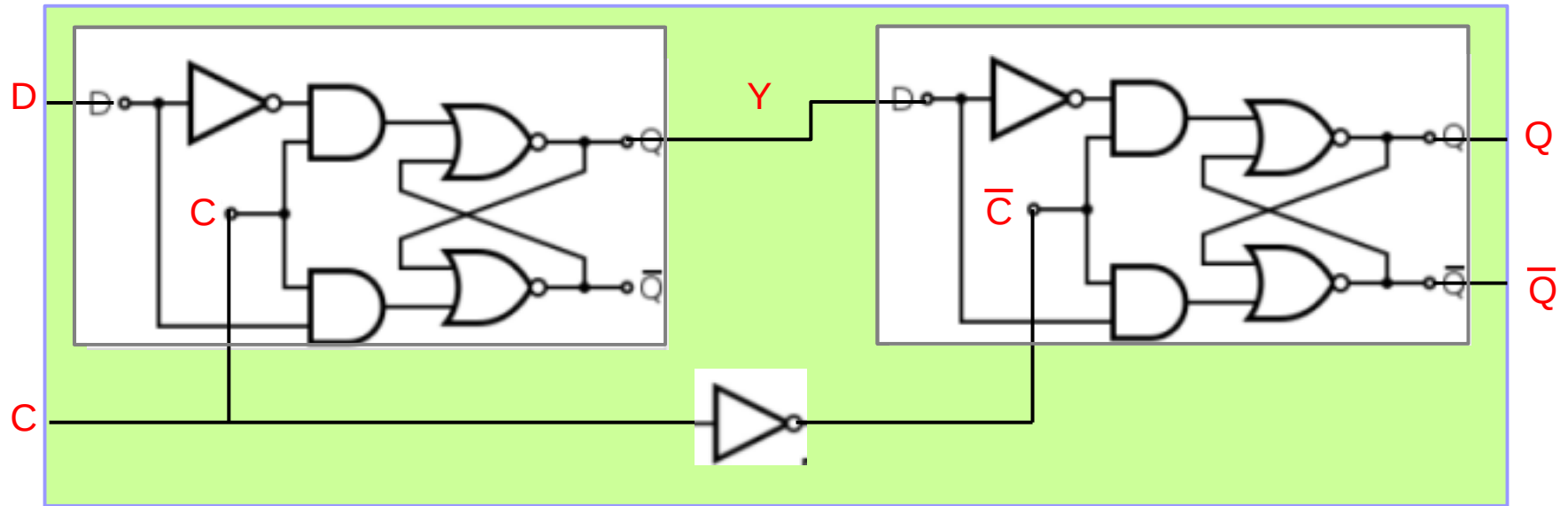
D Latch States



Trans 1	C= <u>1</u> D= <u>1</u>	Q=1 $\bar{Q}=0$
Trans 0	C= <u>1</u> D= <u>0</u>	Q=0 $\bar{Q}=1$
Opaque	C= <u>0</u> D=X	Q=old Q $\bar{Q}=\text{old } \bar{Q}$

https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

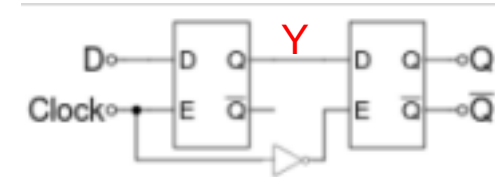
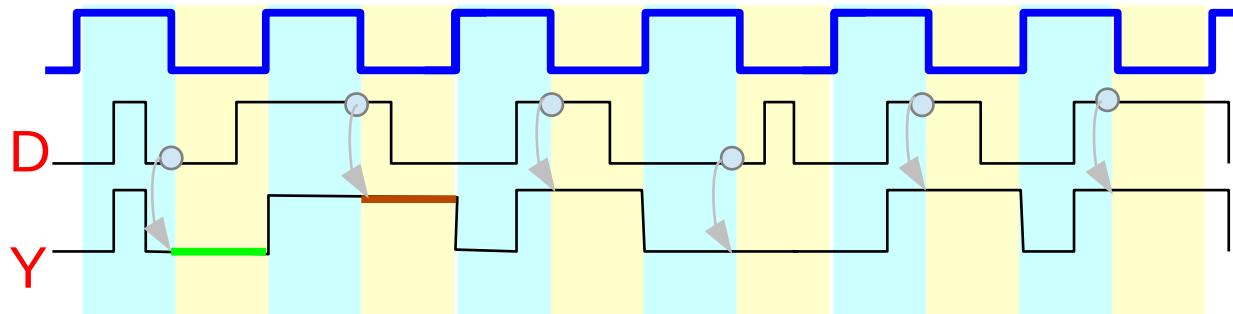
Master-Slave FlipFlops



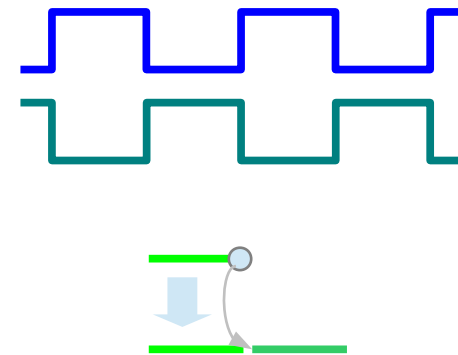
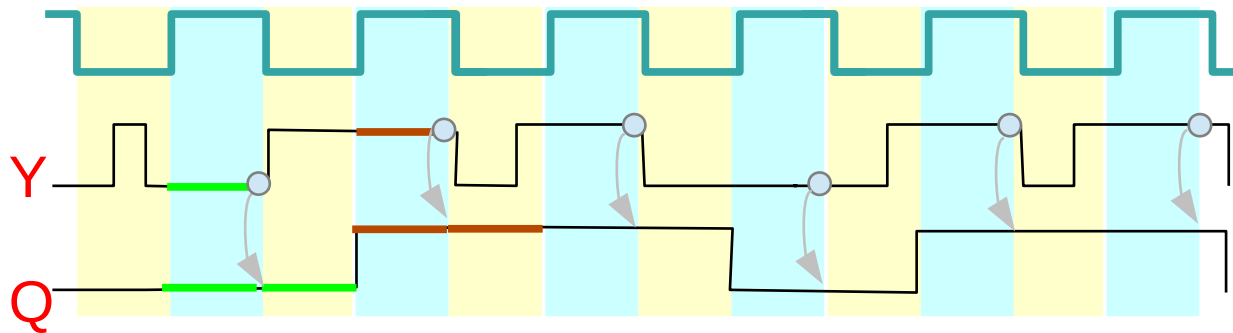
https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

Master-Slave D FlipFlop

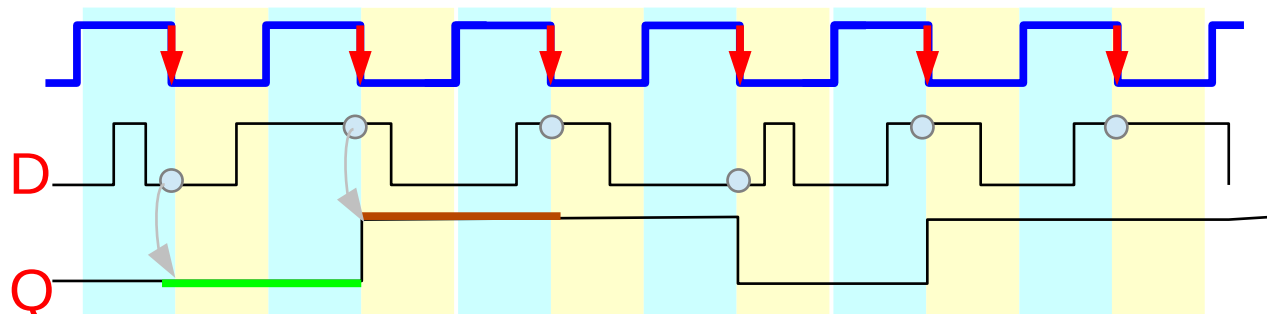
Master D Latch



Slave D Latch



Master-Slave D F/F

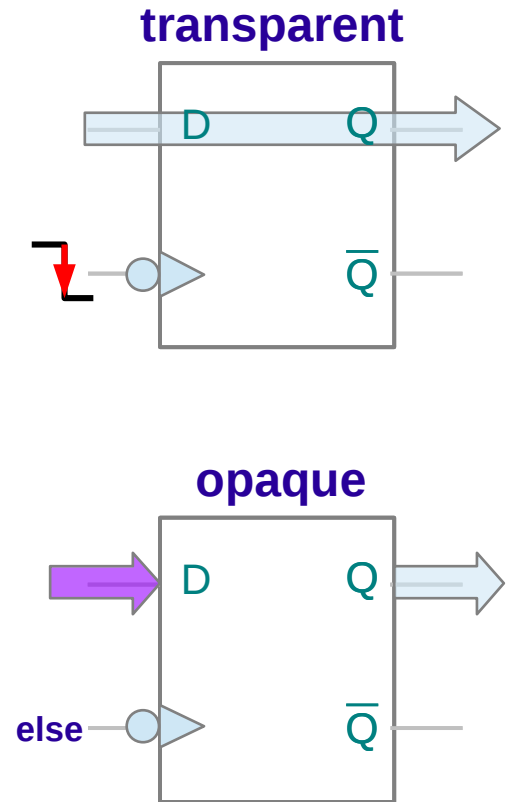
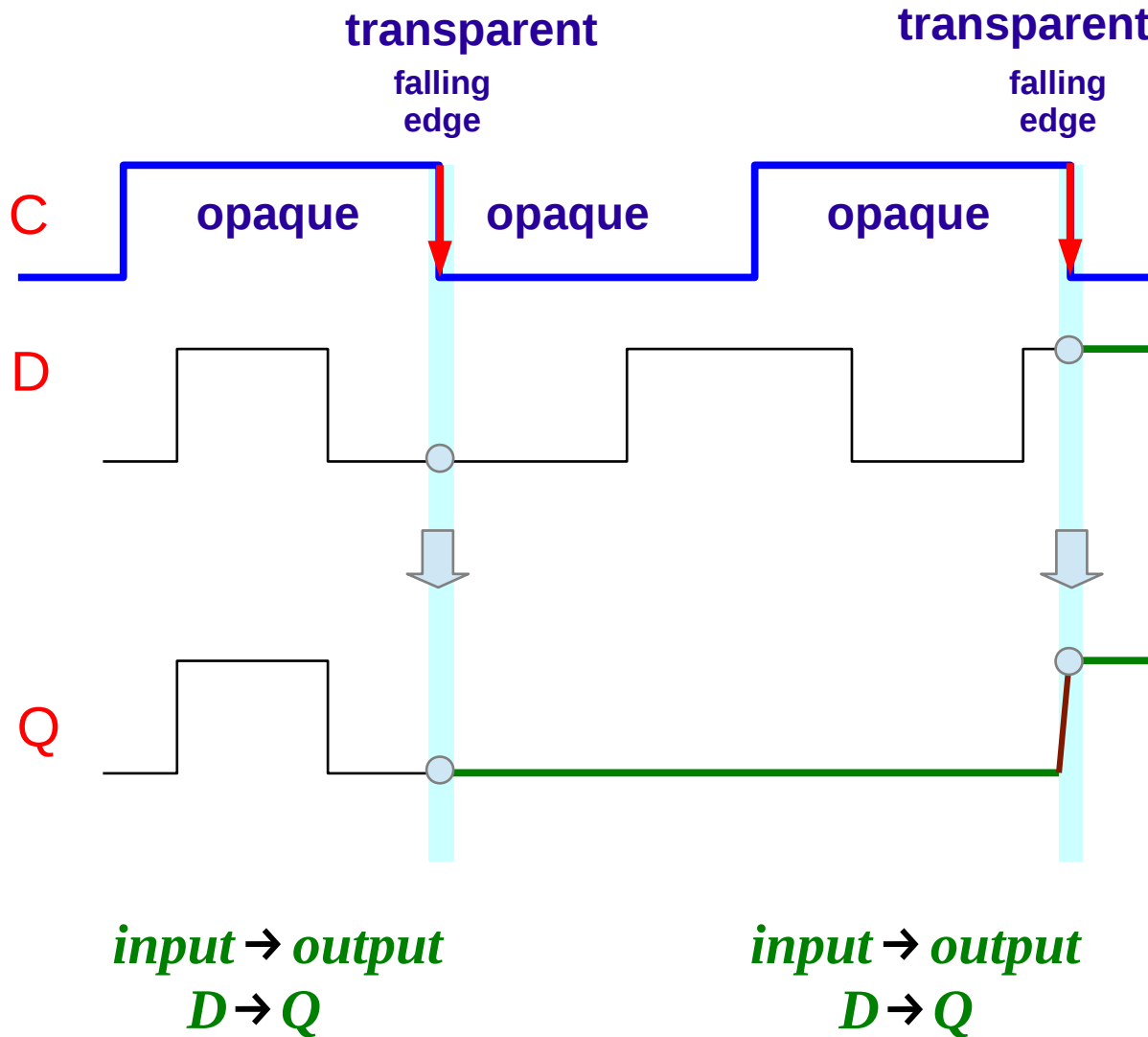


the hold output of the master is transparently reaches the output of the slave

this value is held for another half period

https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

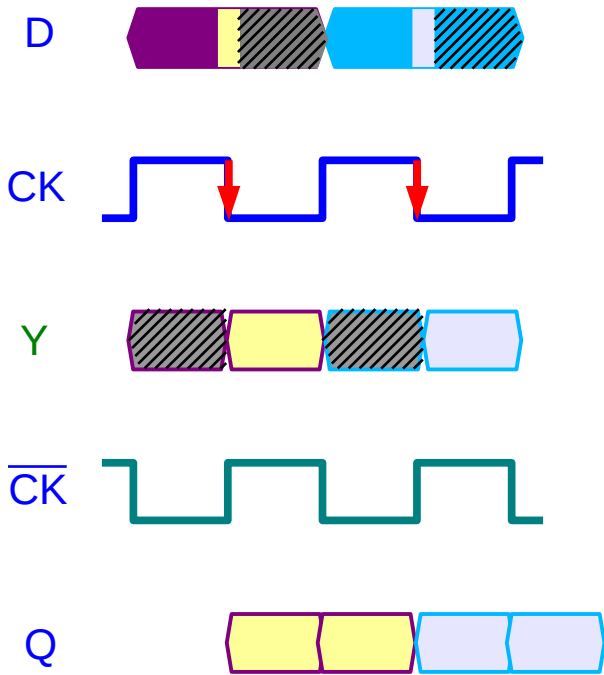
Master Slave D FlipFlop – transparent / opaque



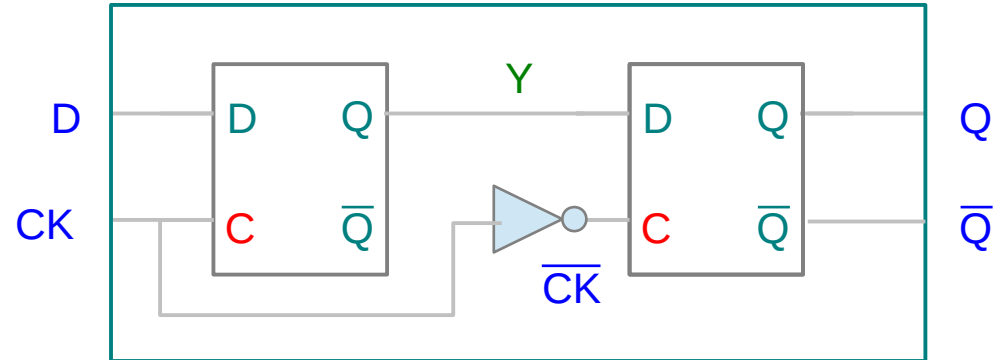
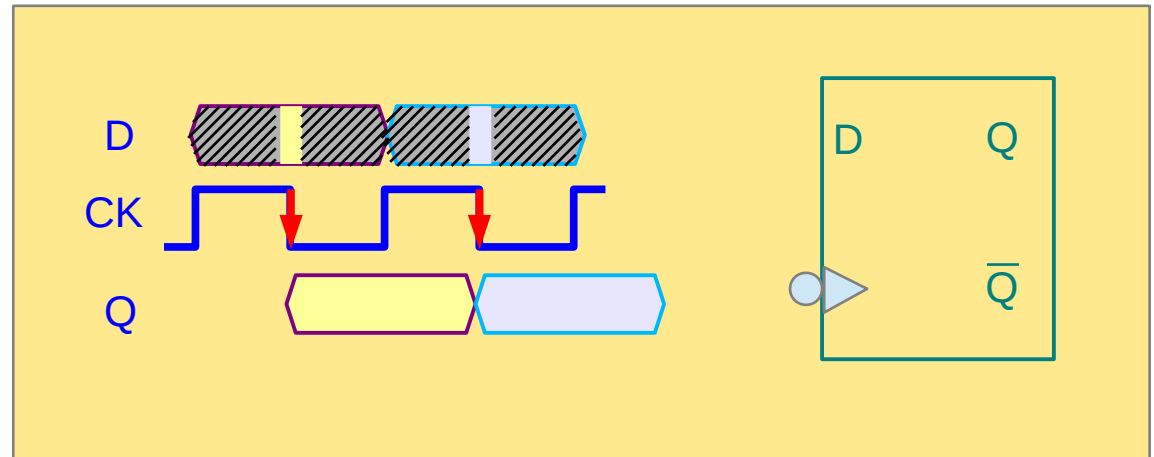
https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

Master-Slave D FlipFlop – Falling Edge

Master D Latch



Slave D Latch

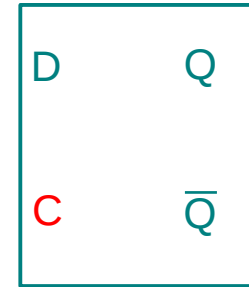
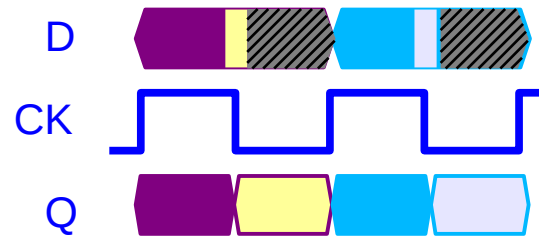


https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

D Latch & D FlipFlop

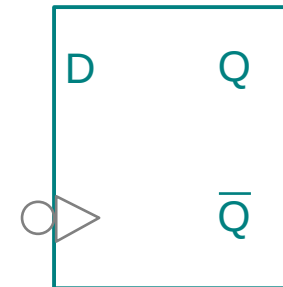
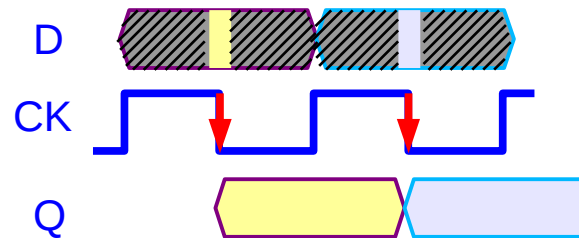
Level Sensitive D Latch

CK=1 transparent
CK=0 opaque



Edge Sensitive D FlipFlop

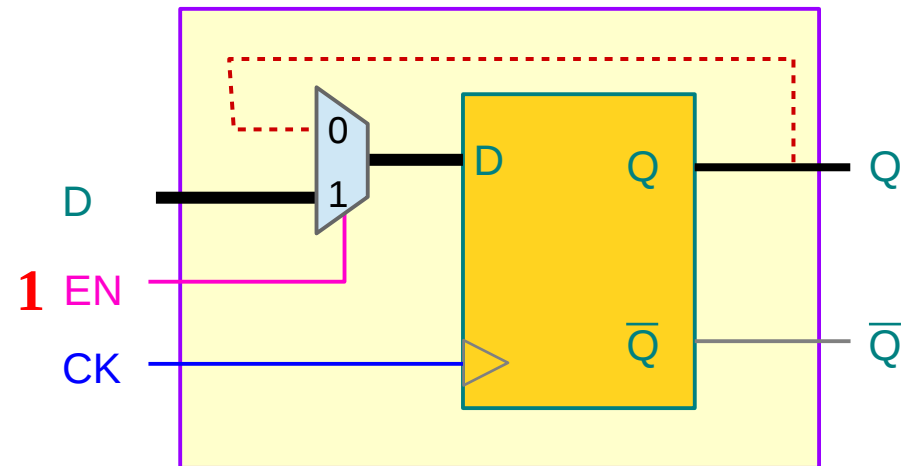
CK=1 → 0 transparent
else opaque



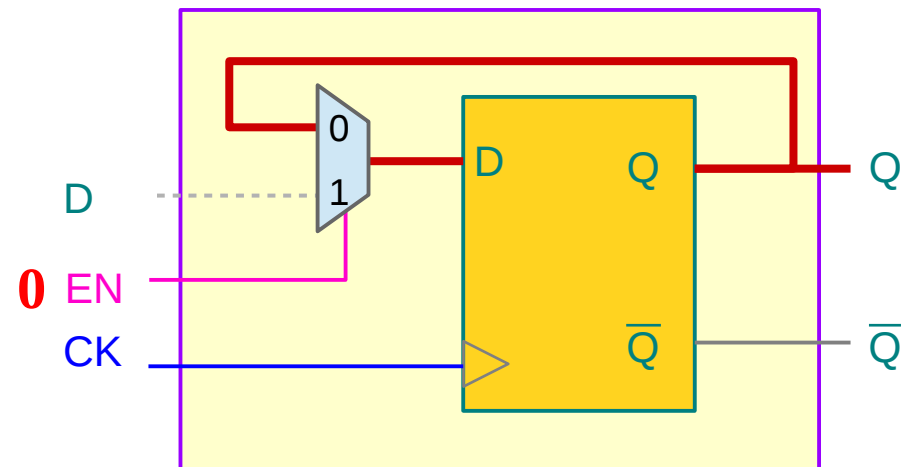
https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

D FlipFlop with Enable (1)

EN=1 Regular D Flip Flop
Sampling **D** input
@ **posedge** of **CK**

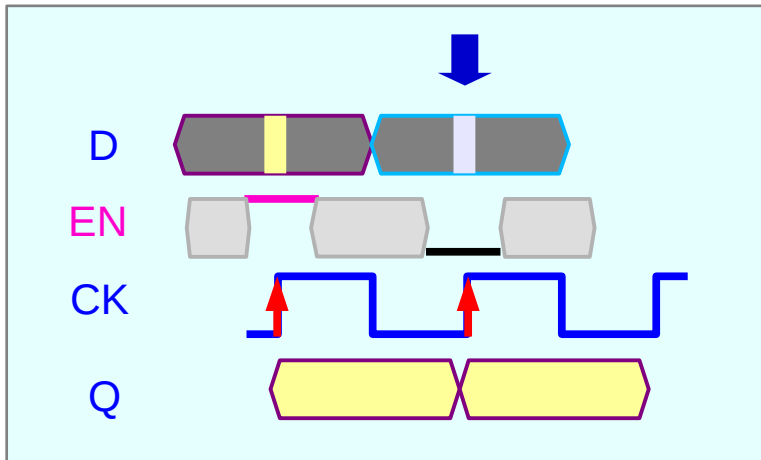
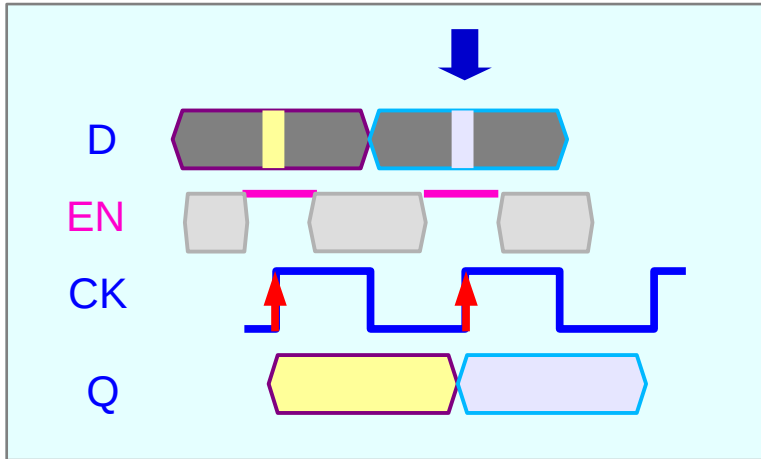


EN=0 Holding D Flip Flop
Sampling **Q** output
@ **posedge** of **CK**

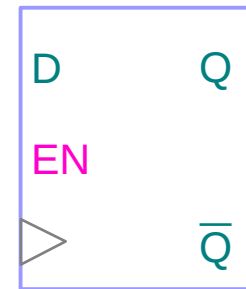
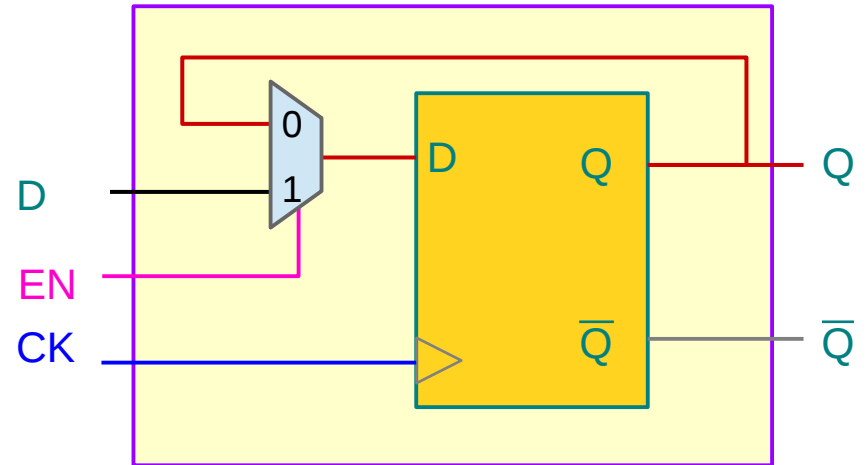


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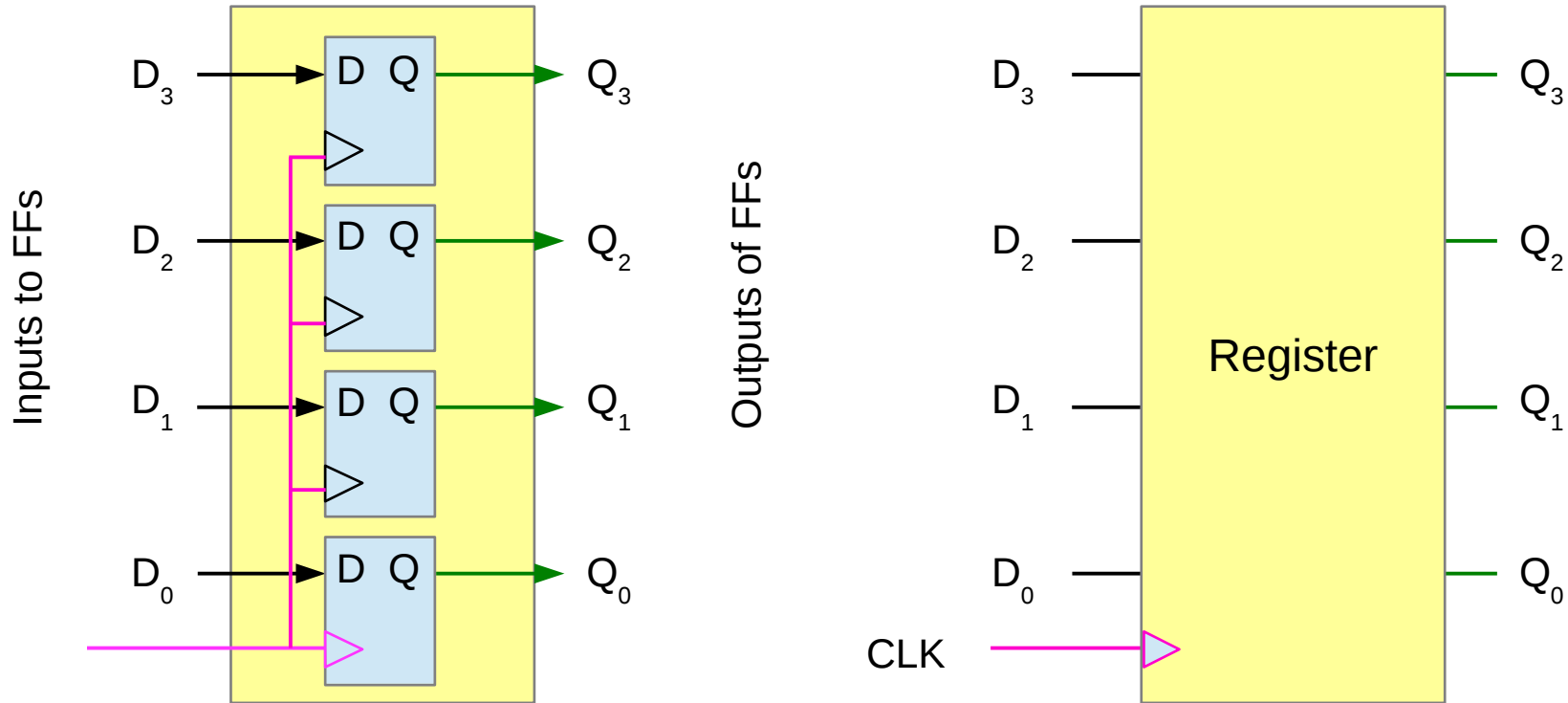
D FlipFlop with Enable (2)



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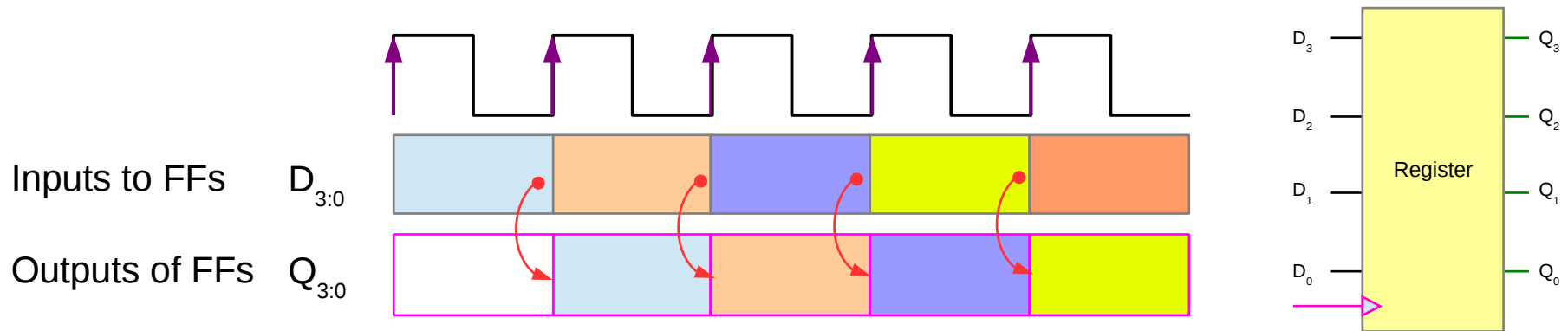


Registers



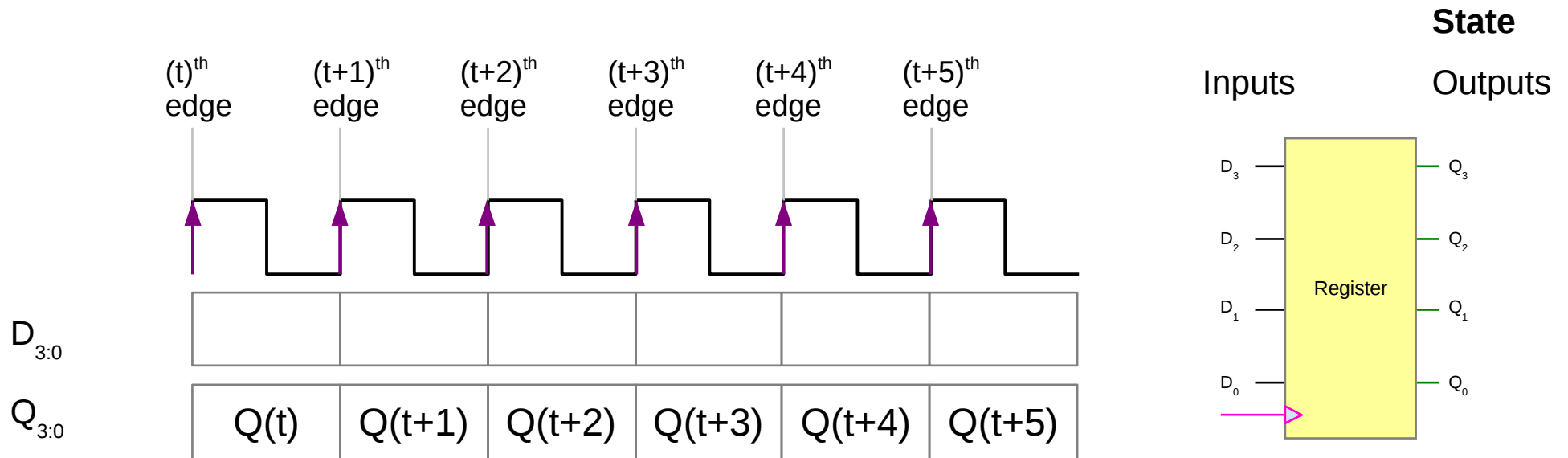
https://en.wikiversity.org/wiki/The_necessities_in_Computer_Design

FF Timing (Ideal)



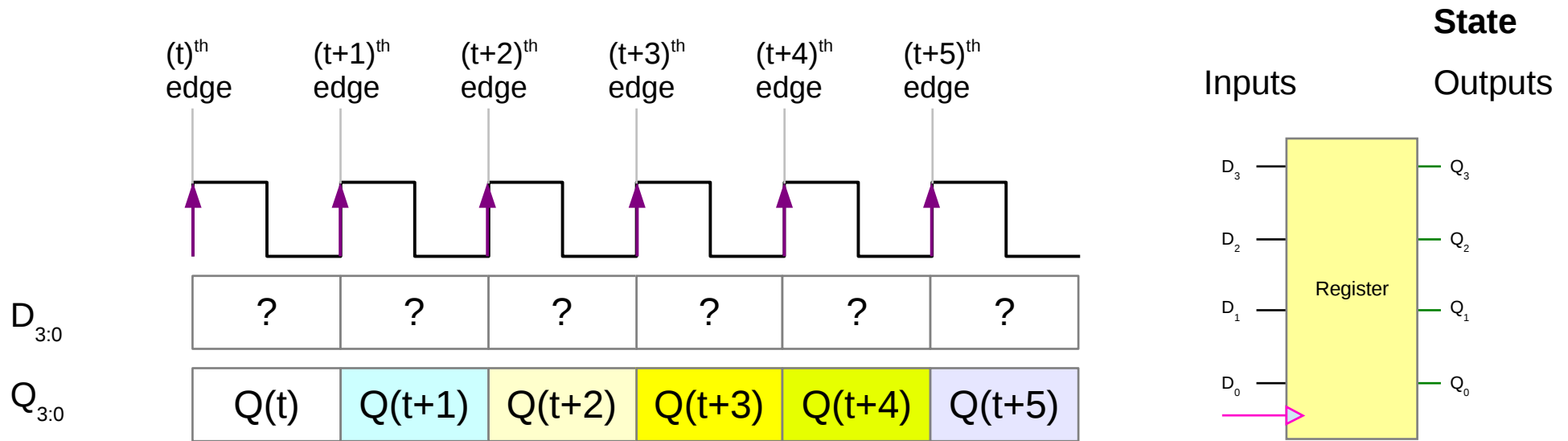
https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

States



https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

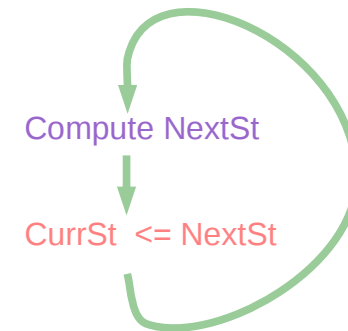
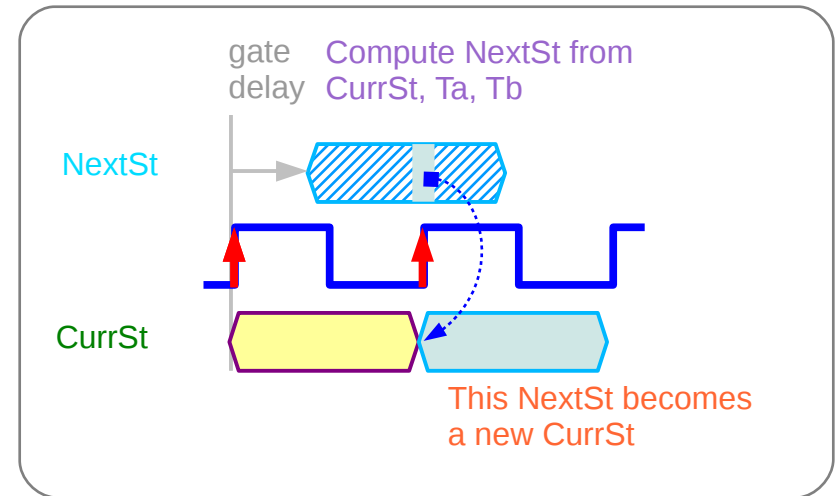
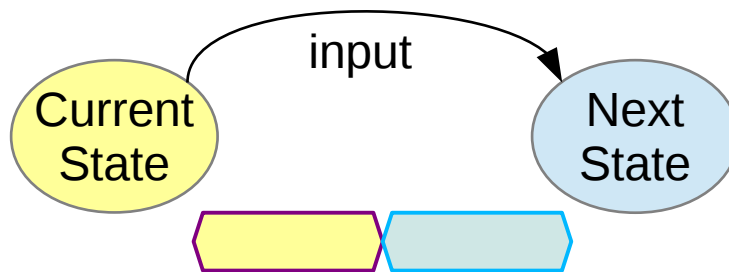
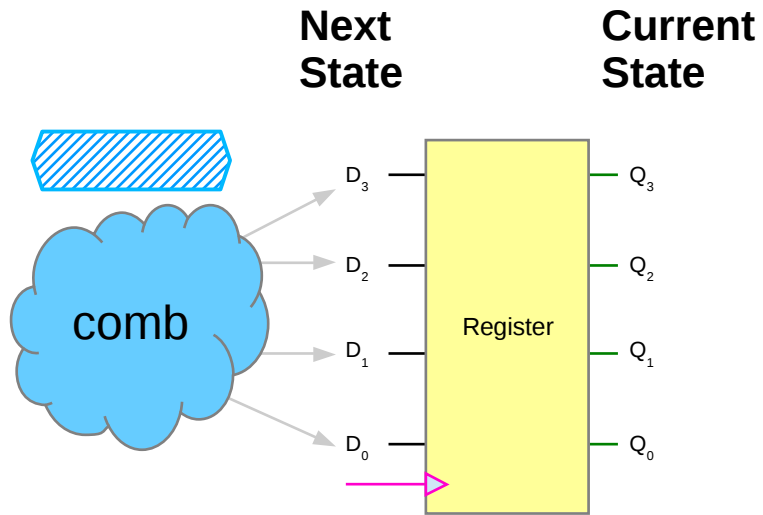
Sequence of States



Find inputs to FFs

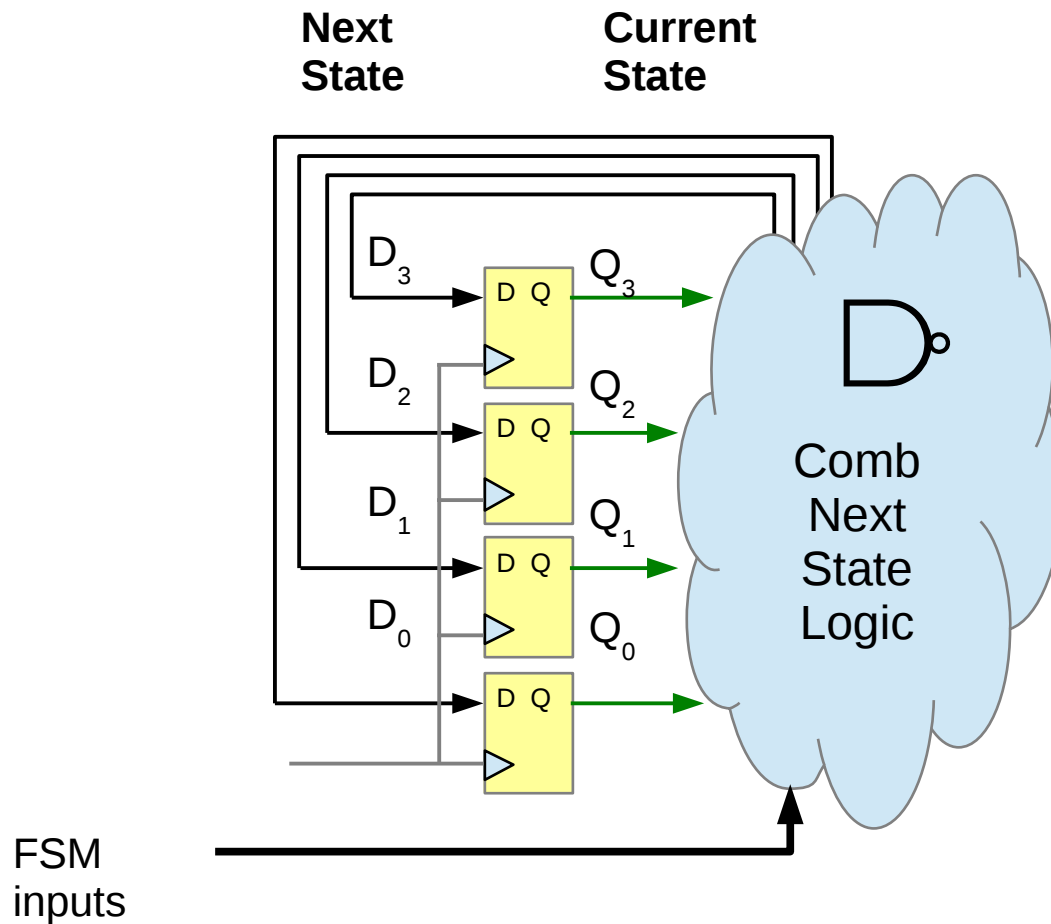
which will make outputs
in this sequence

How to change current state



https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

Finding FF Inputs



During the t^{th} clock edge period,

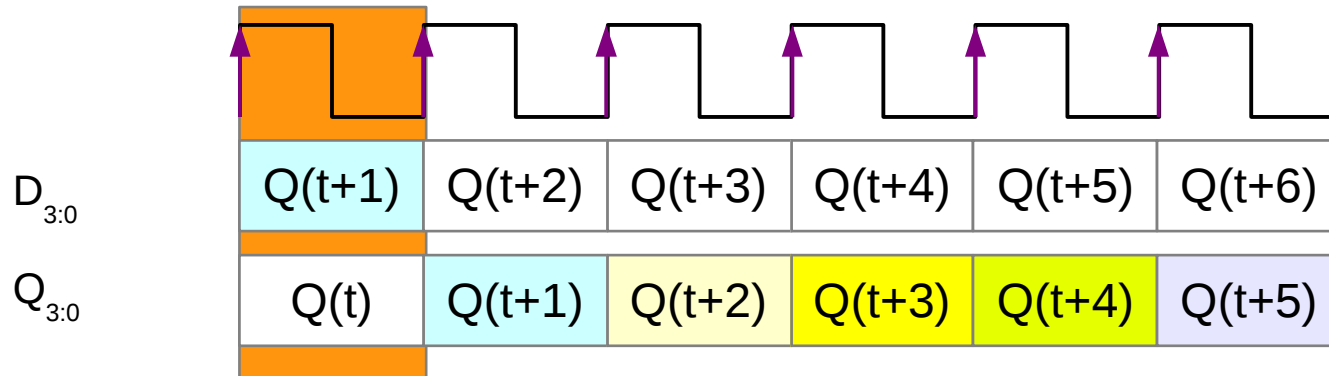
Compute the next state $Q(t+1)$ using the current state $Q(t)$ and other external inputs

Place it to FF inputs

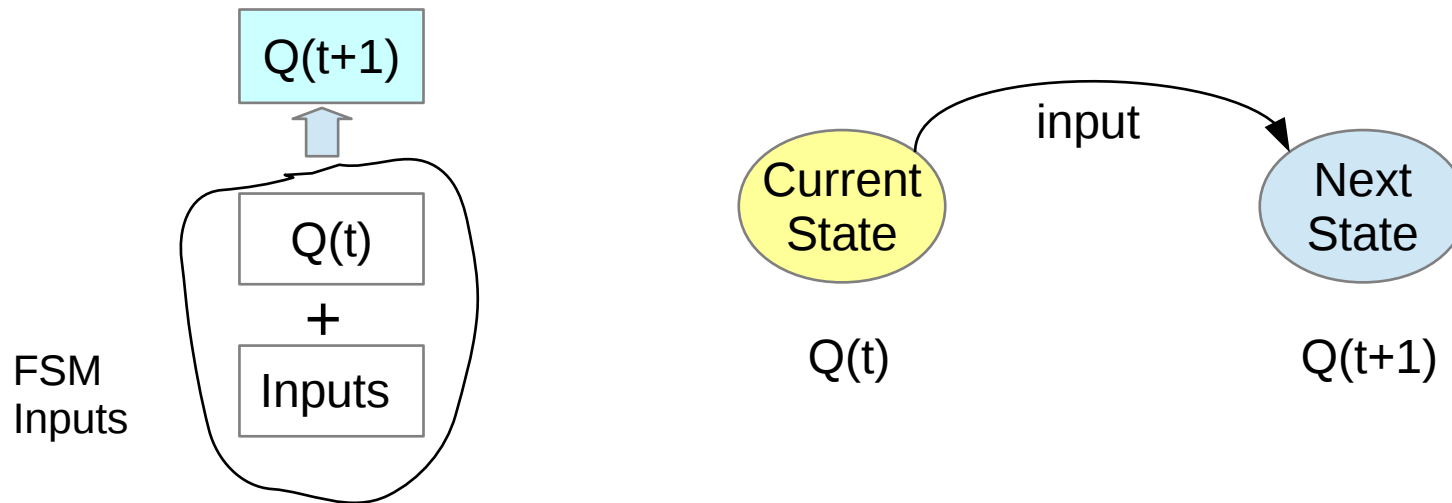
After the next clock edge, $(t+1)^{\text{th}}$, the **computed** next state $Q(t+1)$ becomes the current state

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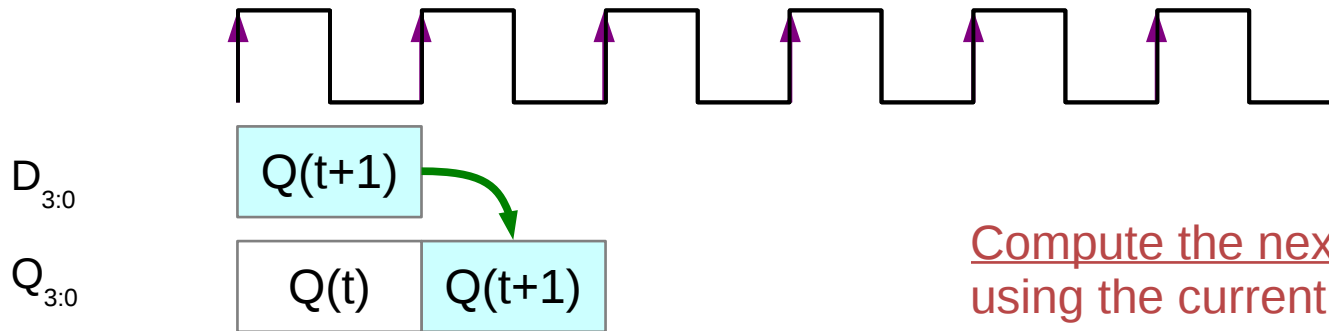
Method of Finding FF Inputs



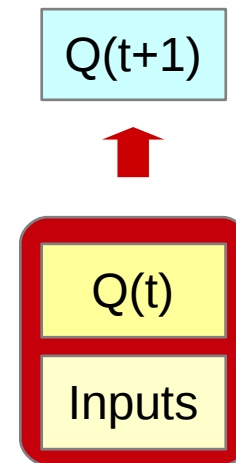
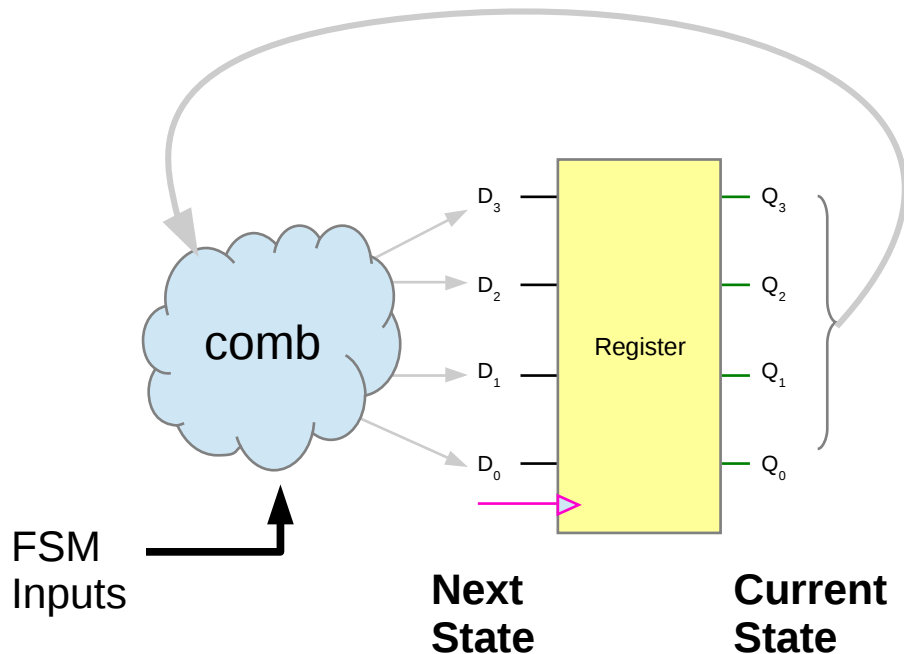
Find the **boolean functions** D_3, D_2, D_1, D_0 in terms of Q_3, Q_2, Q_1, Q_0 , and external FSM inputs **for all possible cases.**



State Transition



Compute the next state using the current state and external inputs in the current clock cycle



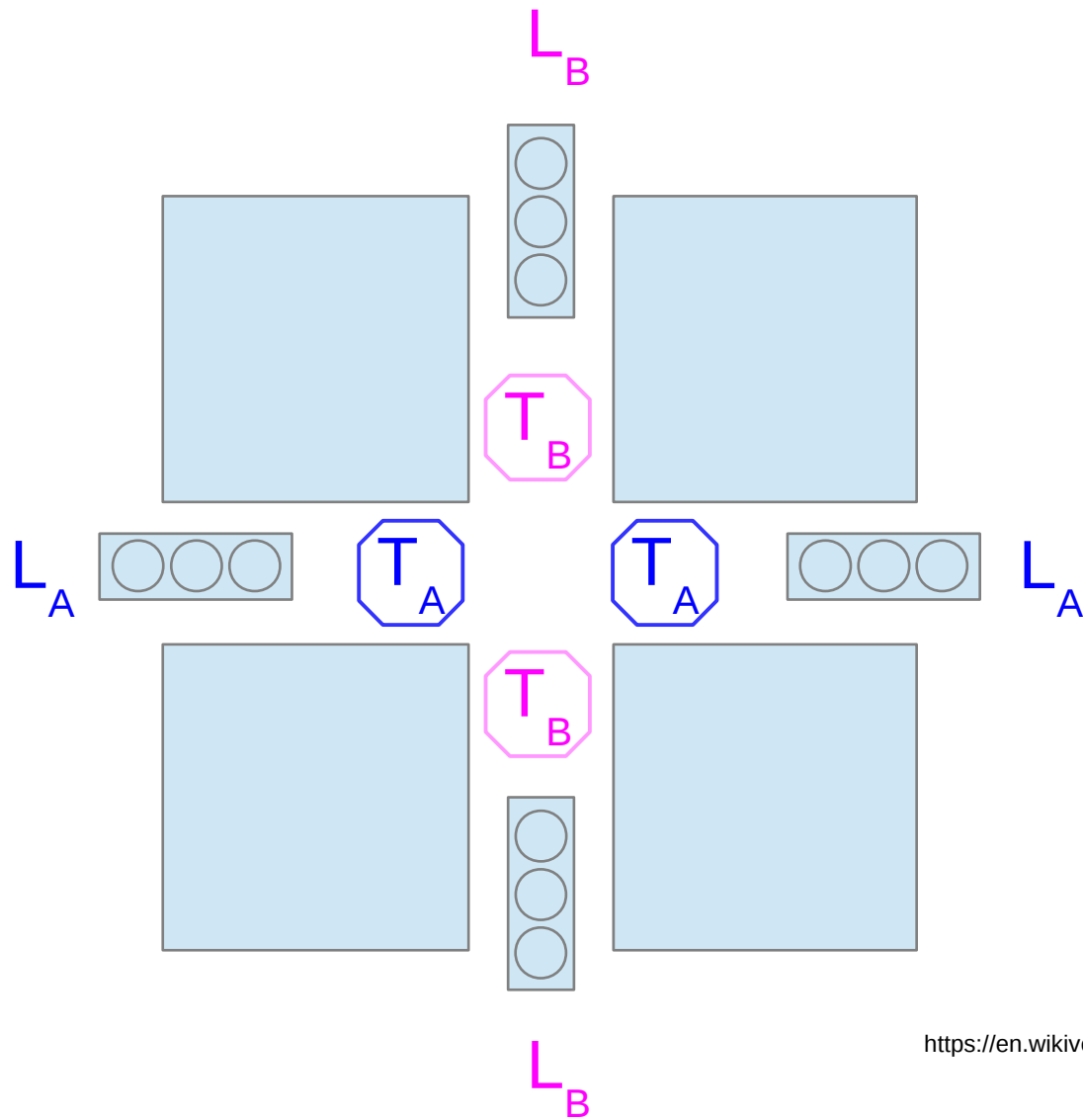
After the next clock edge, the computed next state (FF Inputs) becomes the current state (FF Outputs)

https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

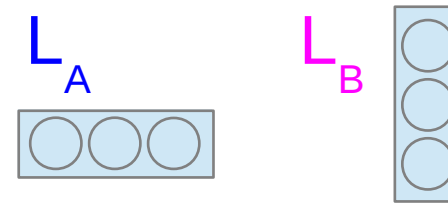
Traffic Lights Example

https://en.wikiversity.org/wiki/The_necessities_in_Computer_Design

FSM Inputs and Outputs



Traffic Lights - Outputs

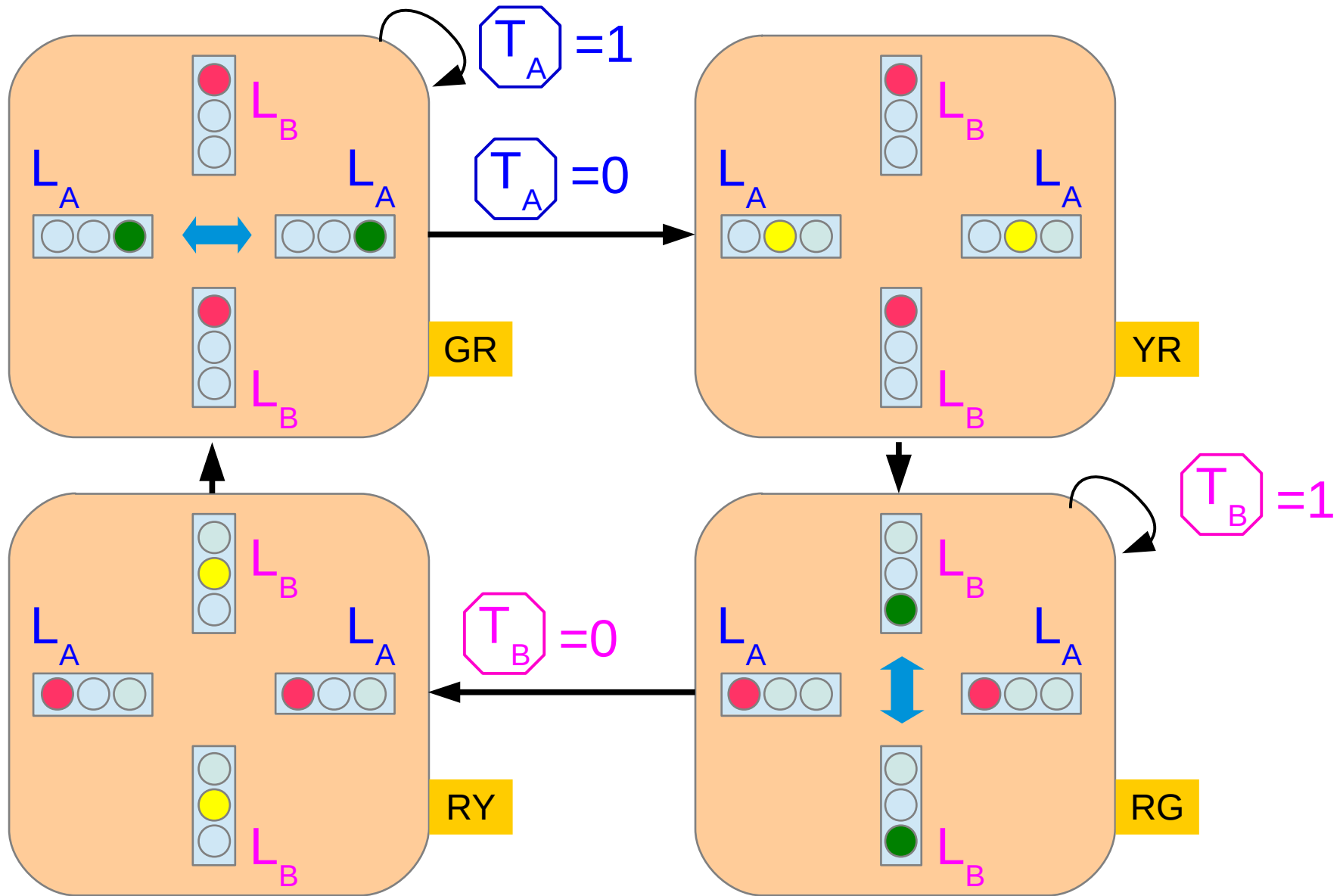


Sensor - Inputs



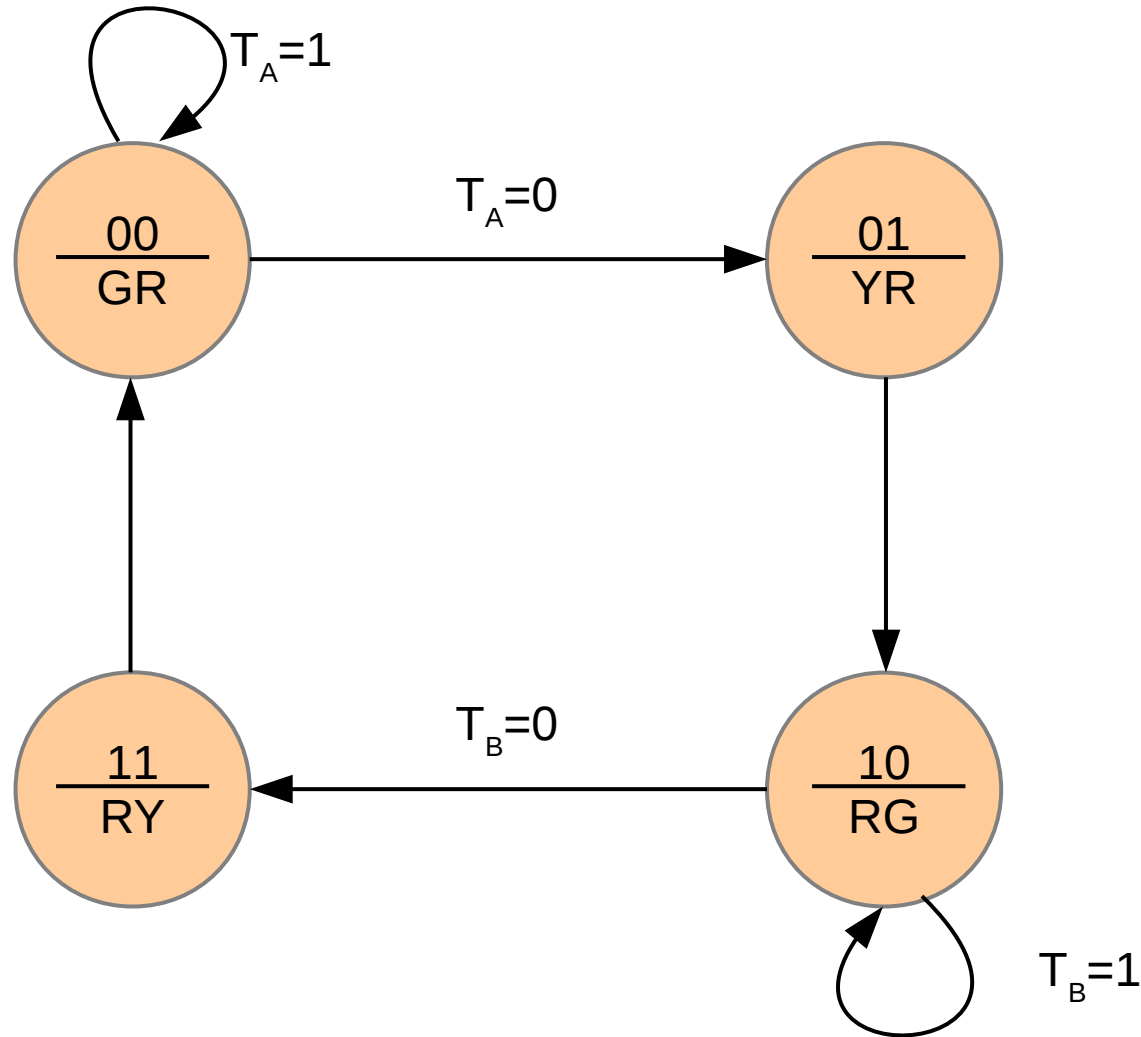
https://en.wikiversity.org/wiki/The_necessities_in_Computer_Design

Four States



https://en.wikiversity.org/wiki/The_necessities_in_Computer_Design

State Transition Diagrams and Tables



S_1	S_0	T_A	T_B	S'_1	S'_0
0	0	0	X	0	1
0	0	1	X	0	0
0	1	X	X	1	0
1	0	X	0	1	1
1	0	X	1	1	0
1	1	X	X	0	0

S_1	S_2	L_{A1}	L_{A0}	L_{B1}	L_{B0}
0	0	0	0	1	0
0	1	0	1	1	0
1	0	1	0	0	0
1	1	1	0	0	1

G	R
Y	R
R	G
R	Y

- G:00
- Y:01
- R:10

Next State Functions S_1' and S_2'

S_1	S_0	T_A	T_B	S_1'	S_0'
0	0	0	X	0	1
0	0	1	X	0	0
0	1	X	X	1	0
1	0	X	0	1	1
1	0	X	1	1	0
1	1	X	X	0	0

$$S_1' = S_1 + S_0$$

$$S_0' = \overline{S_1} \overline{S_0} \overline{T_A} + S_1 \overline{S_0} \overline{T_B}$$

S_1	S_0	T_A	T_B	S_1'
0	0	0	X	0
0	0	1	X	0
0	1	X	X	1
1	0	X	0	1
1	0	X	1	1
1	1	X	X	0

$$\overline{S_1} S_0$$

$$S_1 \overline{S_0} \overline{T_B}$$

$$S_1 \overline{S_0} T_B$$

$$S_1' = \overline{S_1} S_0 + S_1 \overline{S_0}$$

$$= S_1 \oplus S_0$$

S_1	S_0	T_A	T_B	S_0'
0	0	0	X	1
0	0	1	X	0
0	1	X	X	0
1	0	X	0	1
1	0	X	1	0
1	1	X	X	0

$$\overline{S_1} \overline{S_0} \overline{T_A}$$

$$S_1 \overline{S_0} \overline{T_B}$$

$$S_0' = \overline{S_1} \overline{S_0} \overline{T_A} + S_1 \overline{S_0} \overline{T_B}$$

https://en.wikiversity.org/wiki/The_necessities_in_Computer_Design

Output Functions : L_{A1} , L_{A0} , L_{B0} , L_{B1}

S_1	S_2	L_{A1}	L_{A0}	L_{B1}	L_{B0}		
0	0	0	0	1	0	●	●
0	1	0	1	1	0	●	●
1	0	1	0	0	0	●	●
1	1	1	0	0	1	●	●

●	00
●	01
●	10

$$L_{A1} = S_1$$

$$L_{A0} = \overline{S_1} S_0$$

$$L_{B1} = \overline{S_1}$$

$$L_{B0} = S_1 S_0$$

S_1	S_2	L_{A1}
0	0	0
0	1	0
1	0	1
1	1	1

$$L_{A1} = S_1$$

S_1	S_2	L_{A0}
0	0	0
0	1	1
1	0	0
1	1	0

$$L_{A0} = \overline{S_1} S_0$$

S_1	S_2	L_{B1}
0	0	1
0	1	1
1	0	0
1	1	0

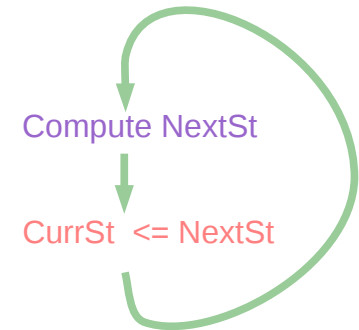
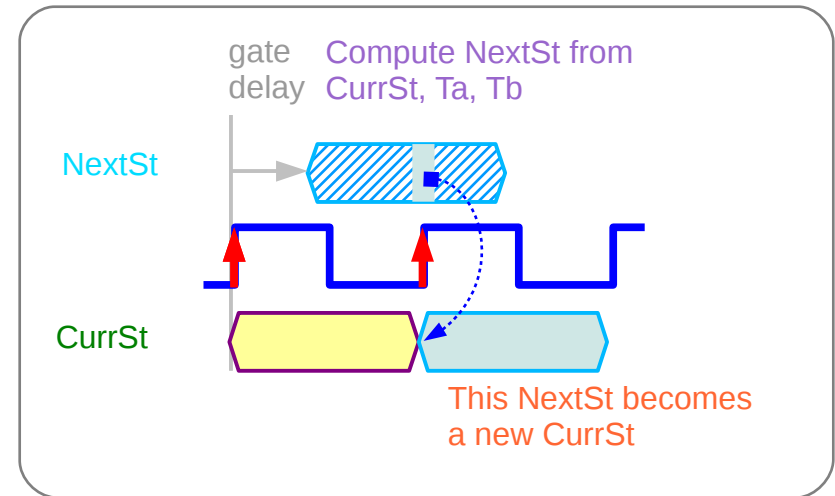
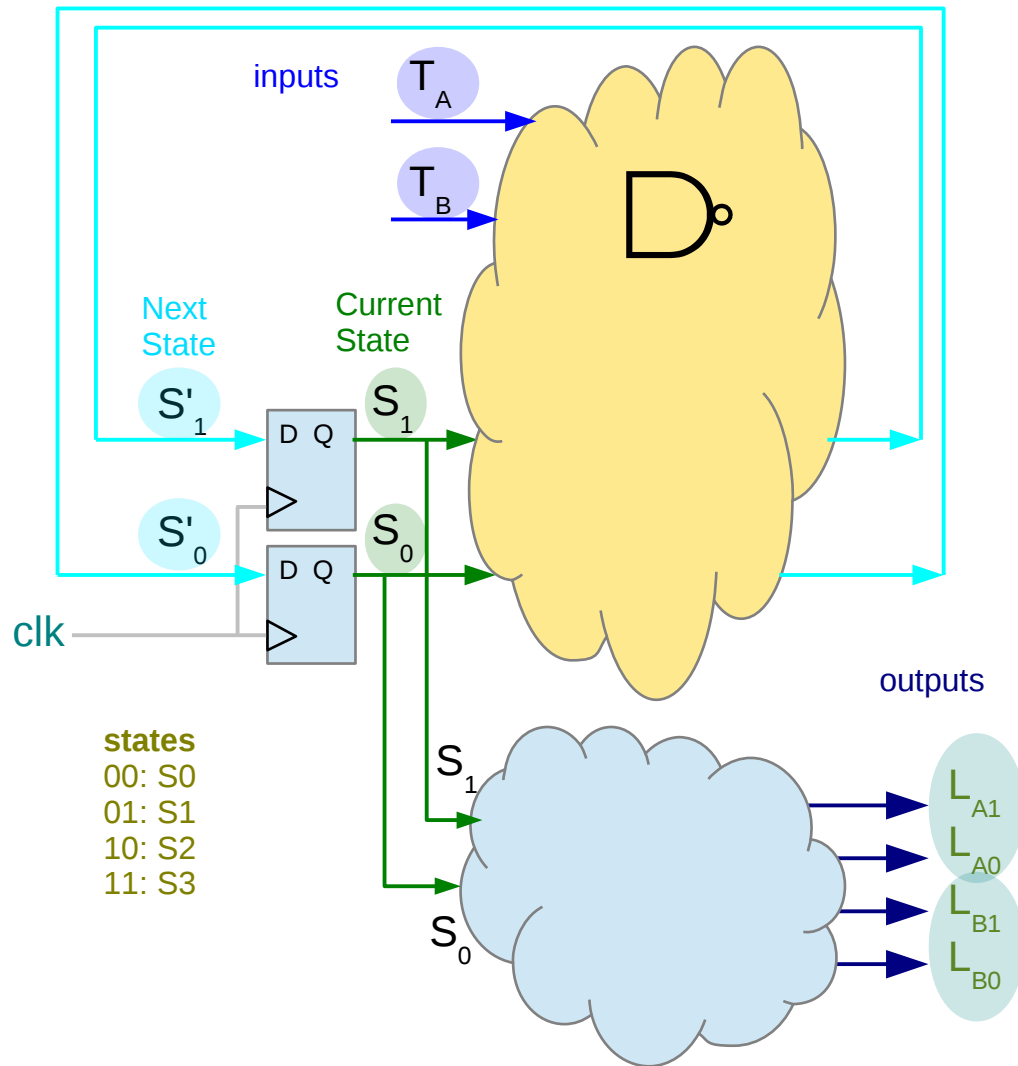
$$L_{B1} = \overline{S_1}$$

S_1	S_2	L_{B0}
0	0	0
0	1	0
1	0	0
1	1	1

$$L_{B0} = S_1 S_0$$

https://en.wikiversity.org/wiki/The_necessities_in_Computer_Design

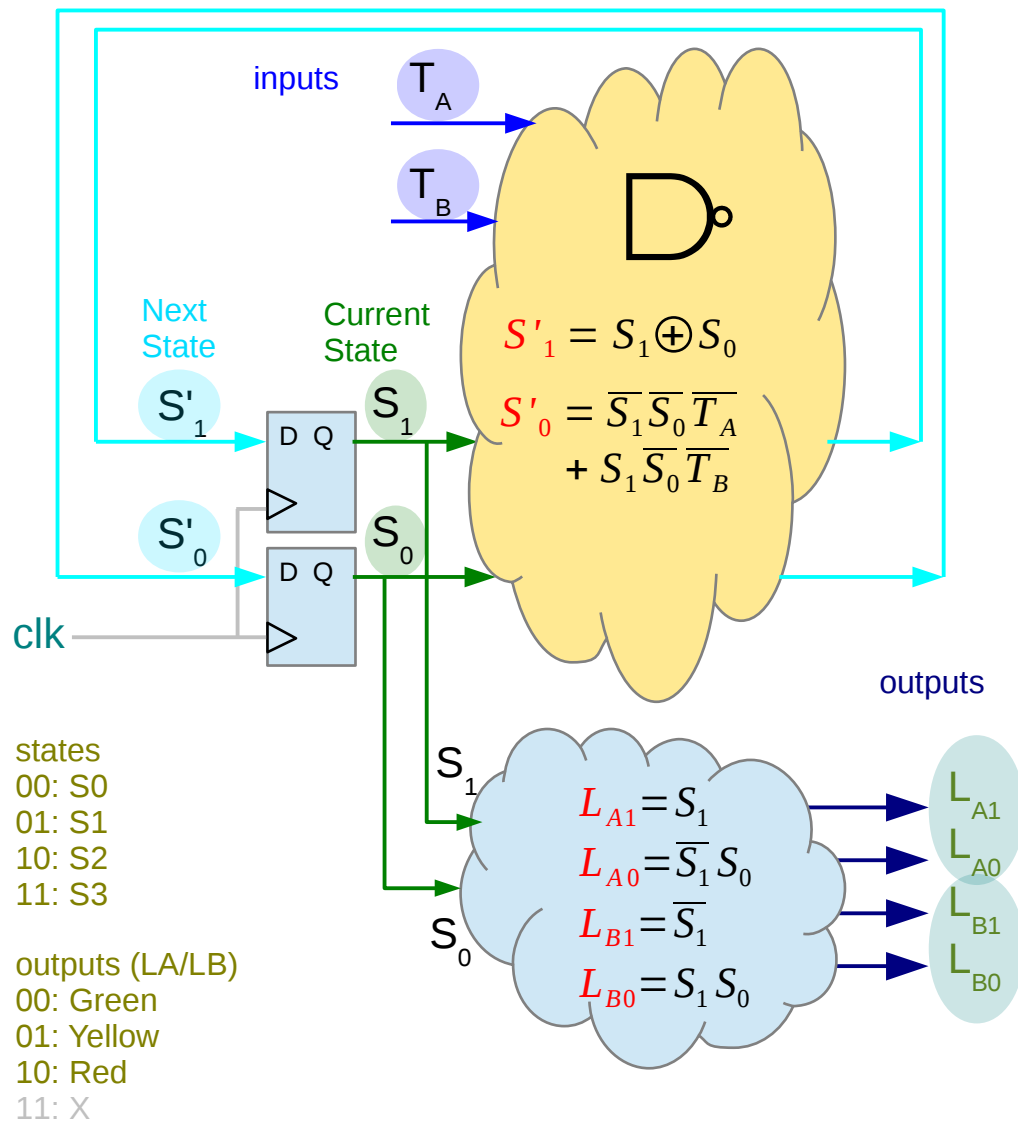
Moore FSM



outputs (LA/LB)
 00: Green
 01: Yellow
 10: Red
 11: X

https://en.wikiversity.org/wiki/The_necessities_in_Computer_Design

Moore FSM Implementation



Inputs	T_A	T_B
Current State	S_1	S_0



Next States

$$S'_1 = S_1 \oplus S_0$$

$$S'_0 = \overline{S_1 S_0 T_A} + S_1 S_0 T_B$$

Current State	S_1	S_0
---------------	-------	-------



Outputs

$$L_{A1} = S_1 \quad L_{B1} = \overline{S_1}$$

$$L_{A0} = \overline{S_1} S_0 \quad L_{B0} = S_1 S_0$$

https://en.wikiversity.org/wiki/The_necessities_in_Computer_Design

Next State Functions S_1' and S_2'

S_1	S_0	T_A	T_B	S_1'	S_0'
0	0	0	X	0	1
0	0	1	X	0	0
0	1	X	X	1	0
1	0	X	0	1	1
1	0	X	1	1	0
1	1	X	X	0	0

$$S_1' = S_1 + S_0$$

$$S_0' = \overline{S_1} \overline{S_0} \overline{T_A} + S_1 \overline{S_0} \overline{T_B}$$

Current State

$(S_1 S_0)$

$\{00, 01, 10, 11\}$

FSM Inputs

$(T_A T_B)$

$\{00, 01, 10, 11\}$

Next State

$(S_1 S_0)$

$\rightarrow \{00, 01, 10, 11\}$

https://en.wikiversity.org/wiki/The_necessities_in_Computer_Design

Cartesian Product

S_1	S_0	T_A	T_B	S'_1	S'_0
0	0	0	X	0	1
0	0	1	X	0	0
0	1	X	X	1	0
1	0	X	0	1	1
1	0	X	1	1	0
1	1	X	X	0	0

S_1	S_0	T_A	T_B	S'_1	S'_0
0	0	0	0	0	1
0	0	0	1	0	1
0	0	1	0	0	0
0	0	1	1	0	0
0	1	0	0	1	0
0	1	0	1	1	0
0	1	1	0	1	0
0	1	1	1	1	0
1	0	0	0	1	1
1	0	0	1	1	0
1	0	1	0	1	1
1	0	1	1	1	0
1	1	0	0	0	0
1	1	0	1	0	0
1	1	1	0	0	0
1	1	1	1	0	0

Current State **FSM Inputs** **Next State**
 $(S_1 S_0)$ $(T_A T_B)$ $(S_1 S_0)$
 $\{00, 01, 10, 11\} \times \{00, 01, 10, 11\} \rightarrow \{00, 01, 10, 11\}$

Output Functions : $L_{A1}, L_{A0}, L_{B1}, L_{B0}$

S_1	S_2	L_{A1}	L_{A0}	L_{B1}	L_{B0}		
0	0	0	0	1	0	●	●
0	1	0	1	1	0	●	●
1	0	1	0	0	0	●	●
1	1	1	0	0	1	●	●

● G : 00
 ● Y : 01
 ● R : 10

$L_{A1} = S_1$
 $L_{A0} = \overline{S_1} S_0$
 $L_{B1} = \overline{S_1}$
 $L_{B0} = S_1 S_0$

Current State

$(S_1 S_0)$

{00, 01, 10, 11}

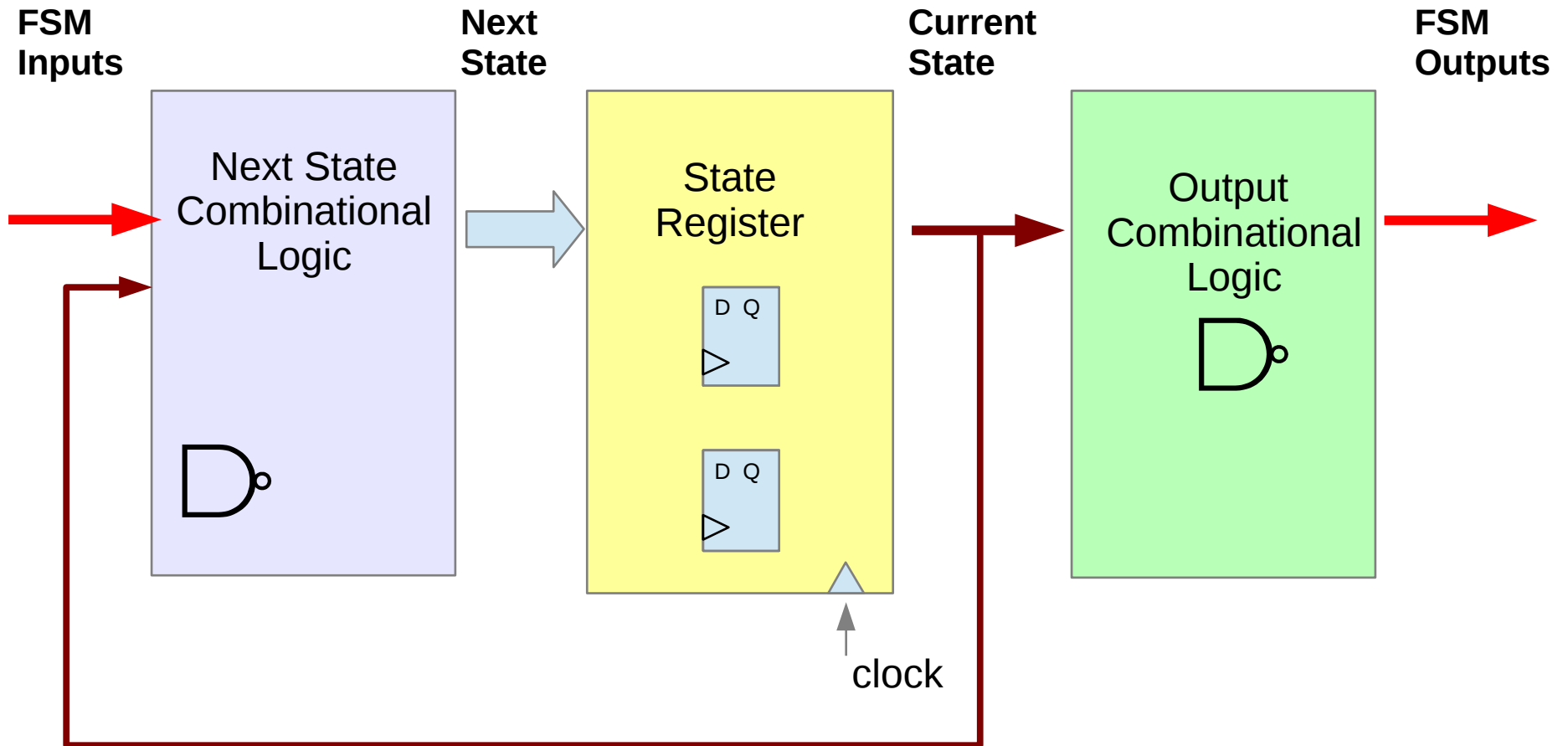
FSM Output

$(L_{A1}, L_{A0}, L_{B1}, L_{B0})$

→ {0010, 0110, 1000, 1001}

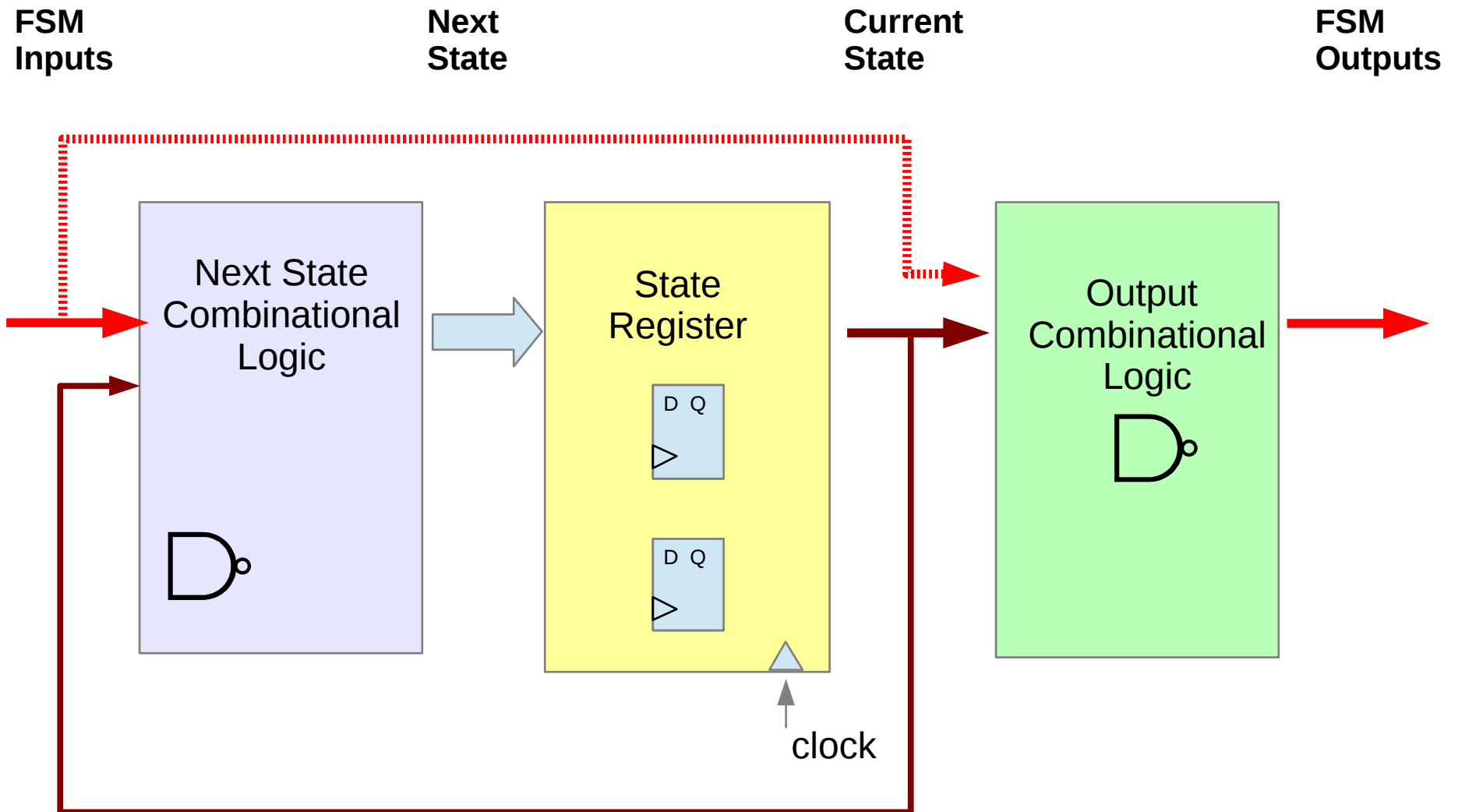
https://en.wikiversity.org/wiki/The_necessities_in_Computer_Design

Moore FSM



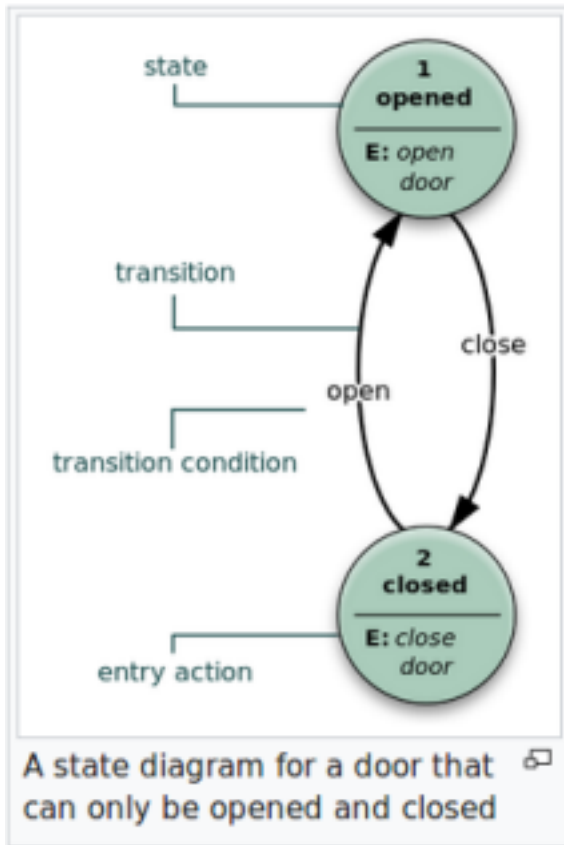
https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

Mealy FSM

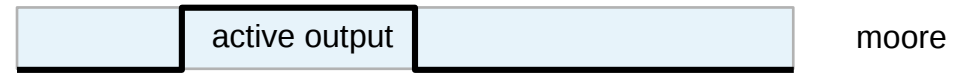


https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

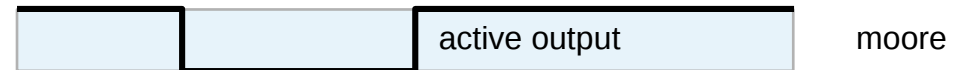
State Diagram



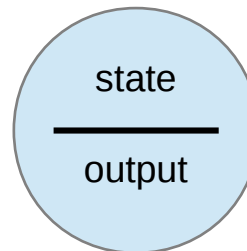
E: Entry Action



X: Exit Action

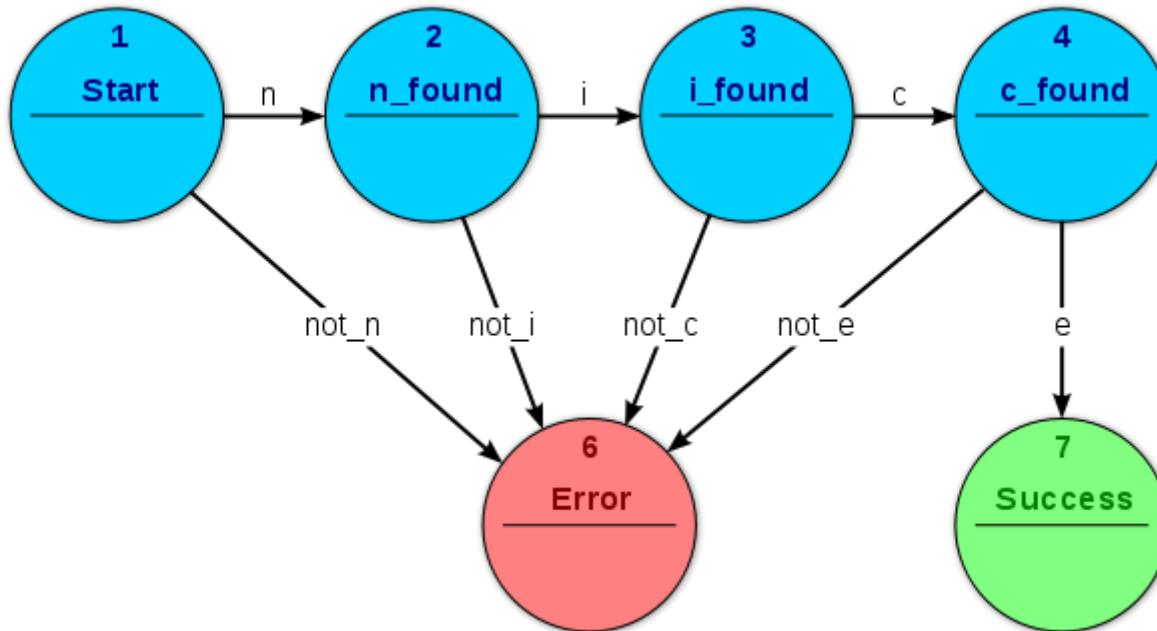


I: Input Action



https://en.wikipedia.org/wiki/Finite-state_machine

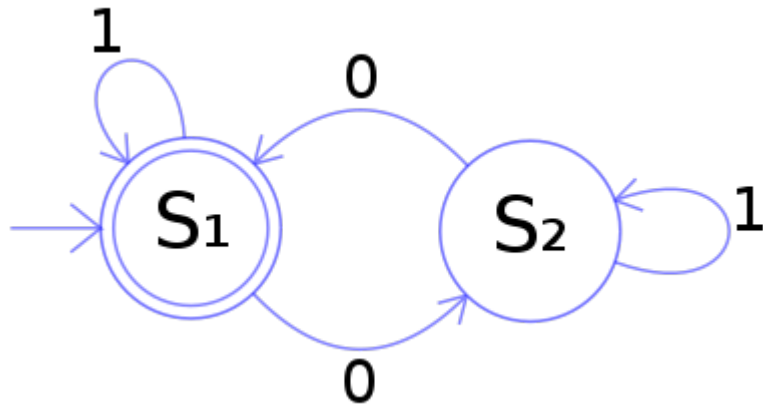
Acceptors



Acceptor FSM: parsing the string "nice"

https://en.wikipedia.org/wiki/Finite-state_machine

Recognizers



Representation of a finite-state machine;
determines whether a binary number has
an **even** number of **0s**,
where **S₁** is an **accepting state**.

https://en.wikipedia.org/wiki/Finite-state_machine

Classifiers

A **classifier** is a generalization of a finite state machine that, similar to an acceptor, produces a **single output** on termination but has more than two **terminal states**

https://en.wikipedia.org/wiki/Finite-state_machine

Transducers

Transducers generate **output** based on a given **input** and/or a **state** using actions. They are used for control applications and in the field of computational linguistics.

https://en.wikipedia.org/wiki/Finite-state_machine

Acceptors, Recognizers, Transducers

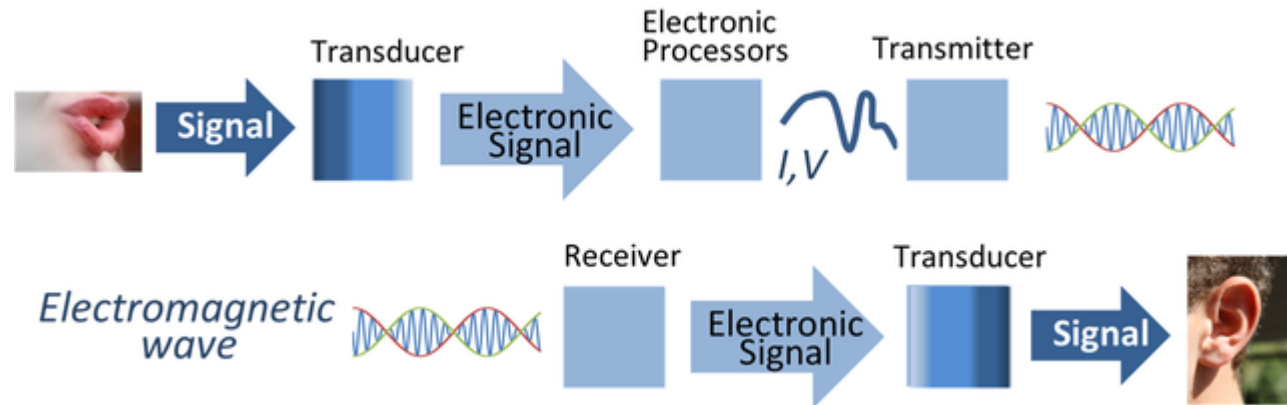
acceptors: either accept the input or not

recognizers: either recognize the input

transducers: generate output from given input

<https://cs.stanford.edu/people/eroberts/courses/soco/projects/2004-05/automata-theory/basics.html>

General Transducers



Transducers are used in electronic communications systems to convert signals of various physical forms to electronic signals, and vice versa. In this example, the first transducer could be a **microphone**, and the second transducer could be a **speaker**.

Transducers : Moore and Mealy Machines

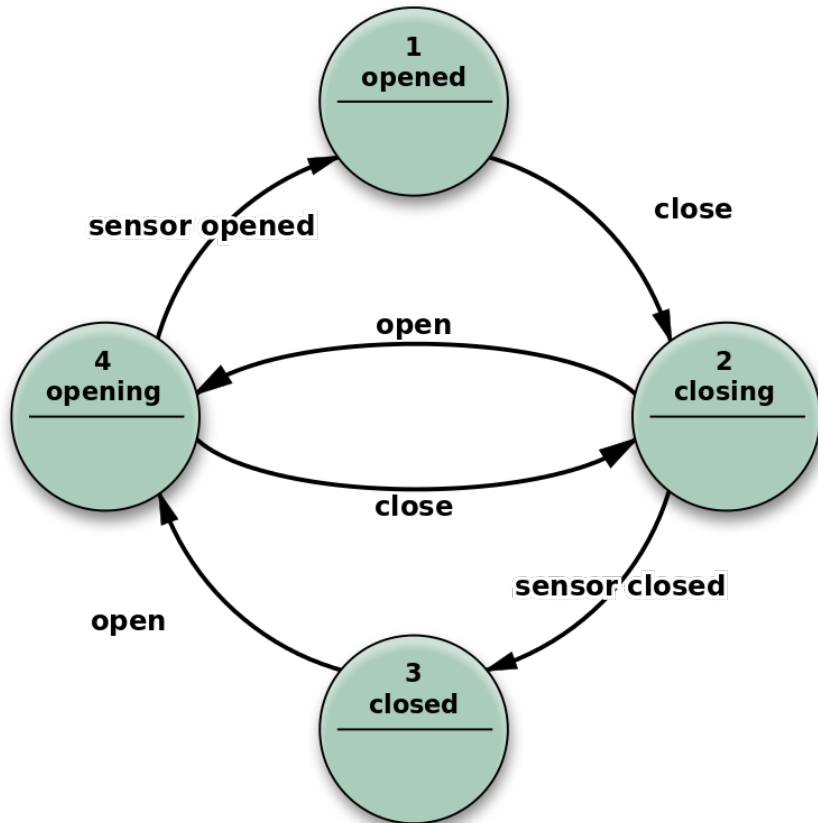


Fig. 6 Transducer FSM: Moore model example

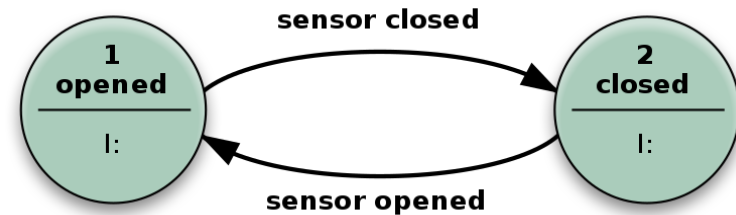


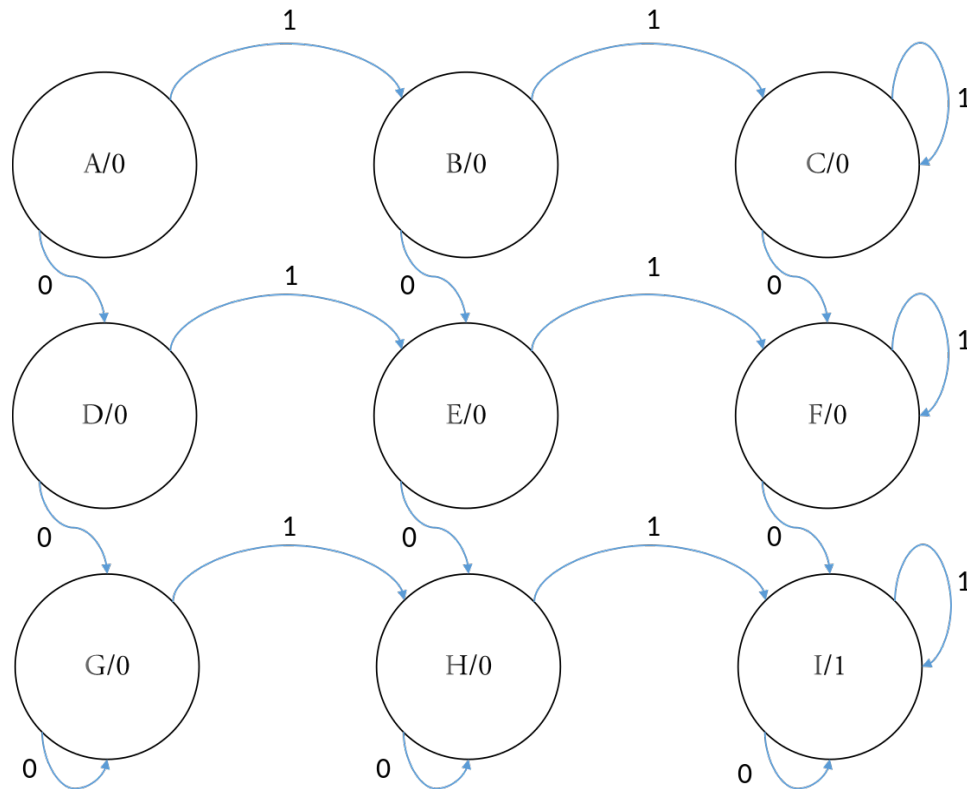
Fig. 7 Transducer FSM: Mealy model example

There are two **input actions** (I:):

"start motor to close the door if command_close arrives"

"start motor in the other direction to open the door if command_open arrives".

Moore machine example

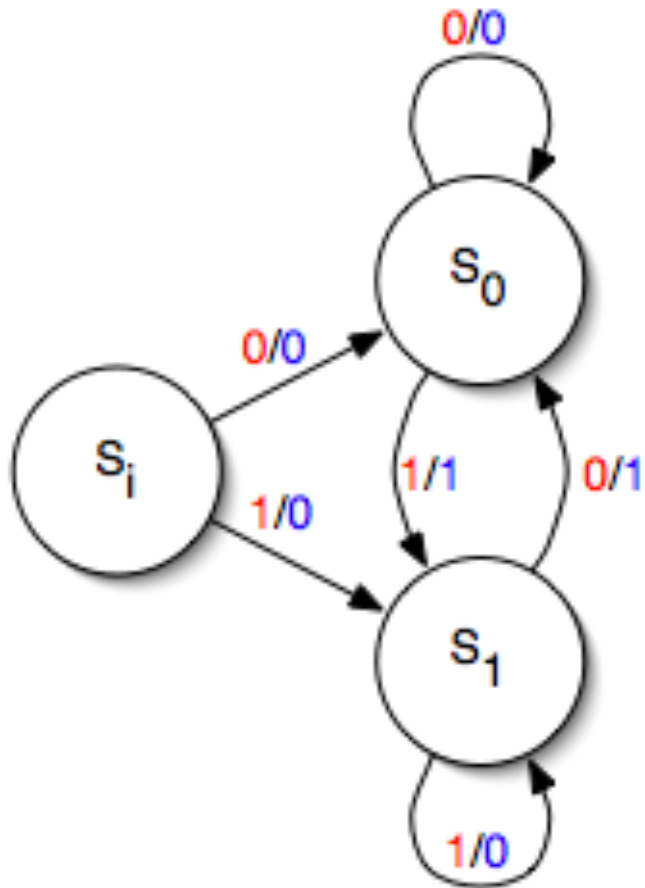


output does not depend on inputs

Current state	Input	Next state	Output
A	0	D	0
	1	B	
B	0	E	0
	1	C	
C	0	F	0
	1	C	
D	0	G	0
	1	E	
E	0	H	0
	1	F	
F	0	I	0
	1	F	
G	0	G	0
	1	H	
H	0	H	0
	1	I	
I	0	I	1
	1	I	

https://en.wikipedia.org/wiki/Moore_machine

Mealy machine



input / output

output does depend on inputs

https://en.wikipedia.org/wiki/Mealy_machine

Mathematical Model – transducers (1)

A **finite-state transducer** is a sextuple $(\Sigma, \Gamma, \mathbf{S}, s_0, \delta, \omega)$, where:

- Σ is the **input** alphabet (a finite non-empty set of symbols).
- Γ is the **output** alphabet (a finite, non-empty set of symbols).
- \mathbf{S} is a finite, non-empty set of **states**.
- s_0 is the **initial** state, an element of S .
- δ is the **state-transition function**: $\delta : \mathbf{S} \times \Sigma \rightarrow \mathbf{S}$
- ω is the **output function**.

Moore machine : $\omega : \mathbf{S} \rightarrow \Gamma$

Mealy machine : $\omega : \mathbf{S} \times \Sigma \rightarrow \Gamma$

$(\Sigma, \Gamma, \mathbf{S}, s_0, \delta, \omega)$
| | | |
 (I, O, S, f, g, σ)

https://en.wikiversity.org/wiki/The_necessities_in_Digital_Design

Mathematical Model – transducers (2)

If the **output** function is a function of a **state** and **input** alphabet ($\omega : \mathbf{S} \times \Sigma \rightarrow \Gamma$) that definition corresponds to the **Mealy model**, and can be modelled as a **Mealy machine**.

If the **output** function depends only on a **state** ($\omega : \mathbf{S} \rightarrow \Gamma$) that definition corresponds to the **Moore model**, and can be modelled as a **Moore machine**.

A finite-state machine with no output function at all is known as a **semiautomaton** or **transition system**.

Mathematical Models – acceptors

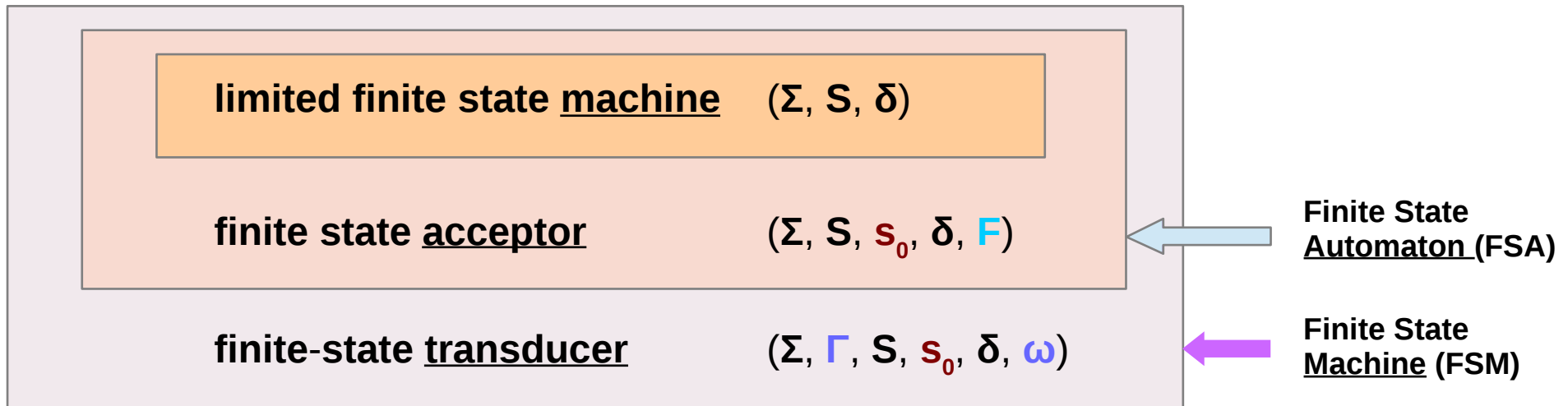
A **deterministic finite state machine** or **acceptor** deterministic finite state machine is a quintuple $(\Sigma, \mathbf{S}, \mathbf{s}_0, \delta, \mathbf{F})$, where:

output set $\{0, 1\}$

- Σ is the **input** alphabet (a finite, non-empty set of symbols).
- \mathbf{S} is a finite, non-empty set of **states**.
- \mathbf{s}_0 is an **initial** state, an element of \mathbf{S} .
- δ is the **state-transition function**: $\delta : \mathbf{S} \times \Sigma \rightarrow \mathbf{S}$
- \mathbf{F} is the set of **final states**, a (possibly empty) subset of \mathbf{S} .

output function ω
A set of accepted states

Finite State Transducers and Acceptors



Σ is the input alphabet (a finite non-empty set of symbols).

S is a finite, non-empty set of states.

δ is the state-transition function: $\delta : S \times \Sigma \rightarrow S$

s_0 is the initial state, an element of S .

F is the set of final states, a (possibly empty) subset of S .

Γ is the output alphabet (a finite, non-empty set of symbols).

ω is the output function.

References

[1] <http://en.wikipedia.org/>

[2]

Automata Theory (2A)

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Automata

The word **automata** (the plural of **automaton**) comes from the Greek word **αὐτόματα**, which means "**self-acting**".

https://en.wikipedia.org/wiki/Automata_theory

Automata Theory

Automata theory is the study of **abstract machines** and **automata**, as well as the computational problems that can be solved using them.

It is a theory in theoretical computer science and discrete mathematics.

https://en.wikipedia.org/wiki/Automata_theory

Automata Informal description (1) – Inputs

An **automaton** runs when it is given some sequence of **inputs** in discrete (individual) time steps or steps.

word 1000100

An automaton processes one input picked from a set of **symbols** or **letters**, which is called an **alphabet**.

alphabet {0,1}

The symbols received by the automaton as input at any step are a finite sequence of **symbols** called **words**.

https://en.wikipedia.org/wiki/Automata_theory

Automata informal description (2) – States

An automaton has a finite set of **states**.

At each moment during a run of the automaton, the automaton is in one of its **states**.

When the automaton receives new input it moves to another state (or **transitions**) based on a **function** that takes the **current state** and **input symbol** as parameters.

This function is called the **transition function**.

https://en.wikipedia.org/wiki/Automata_theory

Automata informal description (3) – Stop

The **automaton**

reads the symbols of the **input word**
one after another and
transitions from **state** to **state**
according to the **transition function**
until the **word** is read completely.

word

1000100

Once the input **word** has been read,
the automaton is said to have stopped.

The state at which the automaton **stops**
is called the **final state**.

https://en.wikipedia.org/wiki/Automata_theory

Automata informal description (4) – Accept / Reject

Depending on the **final state**,
it's said that the automaton
either **accepts** or **rejects** an **input word**.

word

1000100

There is a **subset** of **states** of the automaton,
which is defined as the set of **accepting states**.

If the **final state** is an **accepting state**,
then the automaton **accepts** the **word**.

Otherwise, the **word** is **rejected**.

https://en.wikipedia.org/wiki/Automata_theory

Automata informal description (5) – Language

The set of **all the words accepted** by an automaton is called the "**language** of that automaton".

Any **subset** of the **language** of an automaton is a language **recognized** by that automaton.

https://en.wikipedia.org/wiki/Automata_theory

Automata informal description (6) – Decision on inputs

an **automaton** is a mathematical object that takes a word as **input** and **decides** whether to **accept** it or **reject** it.

Since all computational problems are reducible into the **accept/reject question** on **inputs**, (all problem instances can be represented in a finite length of symbols), automata theory plays a crucial role in computational theory.

https://en.wikipedia.org/wiki/Automata_theory

Automata Applications

Automata theory is closely related to **formal language** theory.

An automaton is a **finite representation** of a **formal language** that may be an **infinite set**.

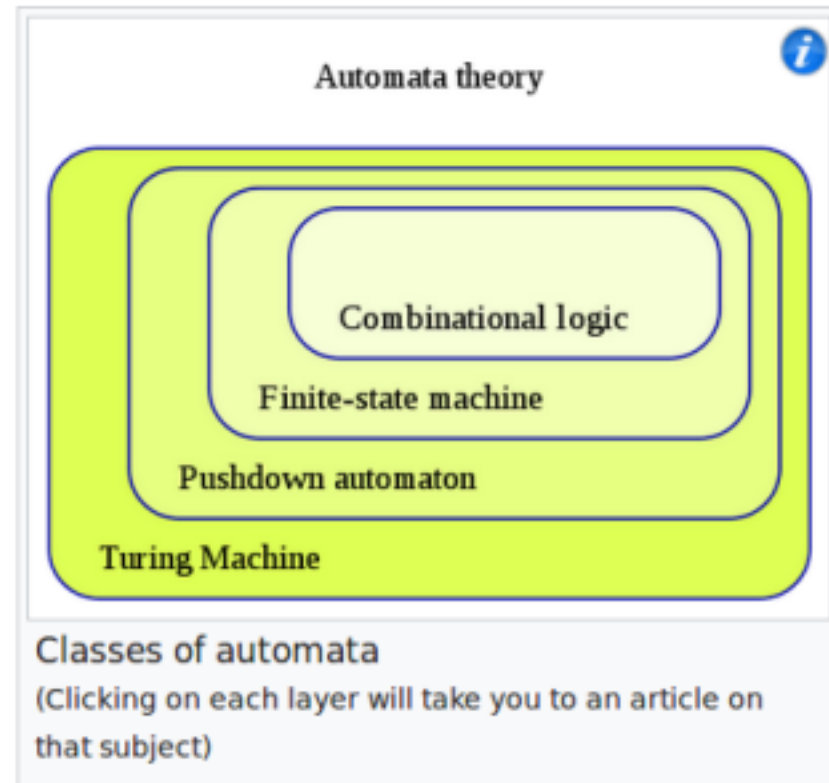
Automata are often classified by the **class of formal languages** they can **recognize**, typically illustrated by the **Chomsky hierarchy**, which describes the relations between various **languages** and kinds of formalized **logic**.

Automata play a major role in
theory of computation,
compiler construction,
artificial intelligence,
parsing and
formal verification.

https://en.wikipedia.org/wiki/Automata_theory

Class of Automata

- Combinational Logic
- Finite State Automaton (FSA)
- Pushdown Automaton (PDA)
- Turing Machine



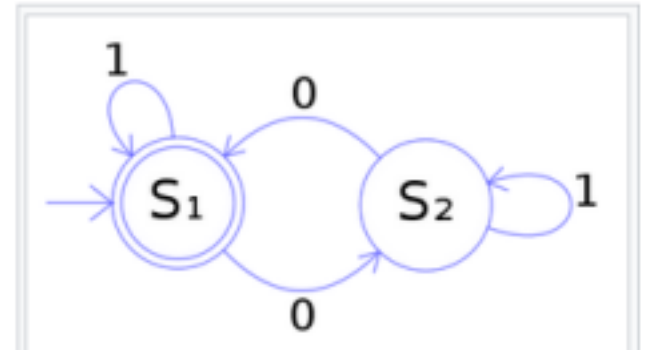
https://en.wikipedia.org/wiki/Automata_theory

Finite State Automaton

The figure at right illustrates a **finite-state machine**, which belongs to a well-known type of **automaton**.

This automaton consists of **states** (represented in the figure by circles) and **transitions** (represented by arrows).

As the automaton sees a **symbol of input**, it makes a **transition** (or jump) to another **state**, according to its **transition function**, which takes the **current state** and the recent **symbol** as its **inputs**.



The study of the mathematical properties of such automata is automata theory. The picture is a visualization of an automaton that recognizes strings containing an even number of 0s. The automaton starts in state S_1 , and transitions to the non-accepting state S_2 upon reading the symbol 0. Reading another 0 causes the automaton to transition back to the accepting state S_1 . In both states the symbol 1 is ignored by making a transition to the current state.

https://en.wikipedia.org/wiki/Automata_theory

Pushdown Automaton (1)

a type of automaton that employs a **stack**.

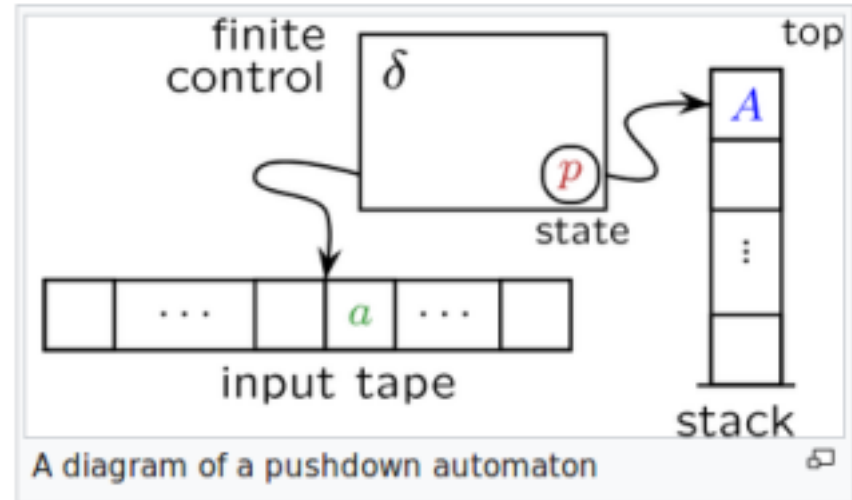
The term "pushdown" refers to the fact that the stack can be regarded as being "pushed down" like a tray dispenser at a cafeteria, since the operations never work on elements other than the **top element**.

A **stack automaton**, by contrast, does allow access to and operations on deeper elements.

https://en.wikipedia.org/wiki/Automata_theory

Pushdown Automaton (2)

a pushdown automaton (PDA) is
a type of automaton that employs a stack



https://en.wikipedia.org/wiki/Pushdown_automaton

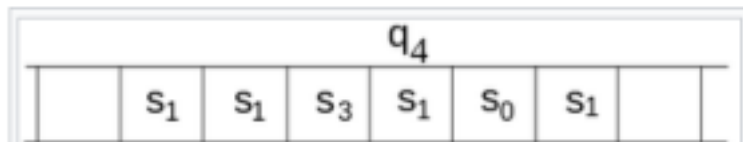
Turing Machine (1)

A **Turing machine** is a mathematical **model** of computation that defines an **abstract machine**, which manipulates **symbols** on a strip of **tape** according to a **table** of **rules**.

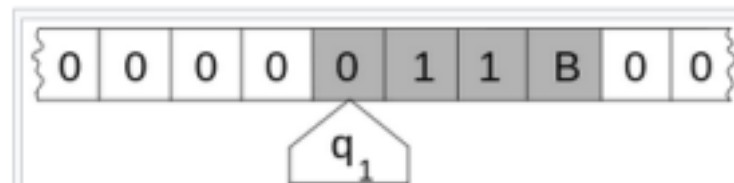
Despite the model's simplicity, given any computer **algorithm**, a **Turing machine** capable of **simulating** that algorithm's logic can be constructed.

https://en.wikipedia.org/wiki/Automata_theory

Turing Machine (2)



The head is always over a particular square of the tape; only a finite stretch of squares is shown. The instruction to be performed (q_4) is shown over the scanned square. (Drawing after Kleene (1952) p. 375.)



Here, the internal state (q_1) is shown inside the head, and the illustration describes the tape as being infinite and pre-filled with "0", the symbol serving as blank. The system's full state (its *complete configuration*) consists of the internal state, any non-blank symbols on the tape (in this illustration "11B"), and the position of the head relative to those symbols including blanks, i.e. "011B". (Drawing after Minsky (1967) p. 121.)

https://en.wikipedia.org/wiki/Turing_machine

1. Definition of Finite State Automata

A deterministic finite automaton is represented formally by a 5-tuple $\langle Q, \Sigma, \delta, q_0, F \rangle$, where:

- Q is a finite set of **states**.
- Σ is a finite set of **symbols**, called the **alphabet** of the automaton.
- δ is the **transition function**, that is, $\delta: Q \times \Sigma \rightarrow Q$.
- q_0 is the **start state**, that is, the state of the automaton before any input has been processed, where $q_0 \in Q$.
- F is a set of **states** of Q (i.e. $F \subseteq Q$) called **accept states**.

https://en.wikipedia.org/wiki/Automata_theory

2. Deterministic Pushdown Automaton

A **PDA** is formally defined as a 7-tuple:

$M = (Q, \Sigma, \Gamma, \delta, q_0, Z, F)$ where

- Q is a finite set of **states**
- Σ is a finite set which is called the **input alphabet**
- Γ is a finite set which is called the **stack alphabet**
- δ is a finite subset of $Q \times (\Sigma \cup \{\varepsilon\}) \times \Gamma \times Q \times \Gamma^*$, the **transition relation**.
- $q_0 \in Q$ is the **start state**
- $Z \in \Gamma$ is the **initial stack symbol**
- $F \subseteq Q$ is the set of **accepting states**

https://en.wikipedia.org/wiki/Pushdown_automaton

3. Turing Machine

Turing machine as a 7-tuple $M = (Q, \Gamma, b, \Sigma, \delta, q_0, F)$ where \setminus set minus

- Q is a finite, non-empty set of **states**;
- Γ is a finite, non-empty set of **tape alphabet symbols**;
- $b \in \Gamma$ is the **blank symbol**
- $\Sigma \subseteq \Gamma \setminus \{b\}$ is the set of **input symbols** in the initial tape contents;
- $q_0 \in Q$ is the **initial state**;
- $F \subseteq Q$ is the set of **final states** or **accepting states**.
- $\delta : (Q \setminus F) \times \Gamma \rightarrow Q \times \Gamma \times \{L, R\}$ is **transition function**, where **L** is **left shift**, **R** is **right shift**.

The initial tape contents is said to be accepted by M if it eventually halts in a state from F .

https://en.wikipedia.org/wiki/Turing_machine

FSA, PDA, Turing Machine

Deterministic Finite State Automaton	$(Q, \Sigma, \delta, q_0, F)$
Deterministic Pushdown Automaton	$(Q, \Sigma, \Gamma, \delta, q_0, Z, F)$
Turing machine	$(Q, \Gamma, b, \Sigma, \delta, q_0, F)$

Σ is the input alphabet (a finite non-empty set of symbols).

Q is a finite, non-empty set of states.

δ is the state-transition function: $\delta : S \times \Sigma \rightarrow S$

s_0 is the initial state, an element of S .

F is the set of final states, a (possibly empty) subset of S .

Γ is a finite set which is called the **stack alphabet**

$Z \in \Gamma$ is the **initial stack symbol**

Γ is a finite, non-empty set of **tape alphabet symbols**;

$b \in \Gamma$ is the **blank symbol**

Deterministic Finite State Automaton (FSA)

Deterministic Finite Automaton Example (1)

The following example is of a DFA M , with a binary alphabet, which requires that the input contains an even number of 0s.

$M = (Q, \Sigma, \delta, q_0, F)$ where

$Q = \{S_1, S_2\}$,

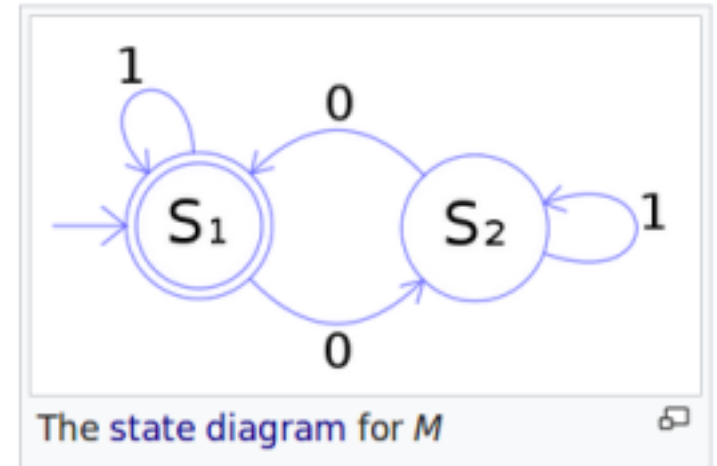
$\Sigma = \{0, 1\}$,

$q_0 = S_1$,

$F = \{S_1\}$, and

δ is defined by the following state transition table:

	0	1
S_1	S_2	S_1
S_2	S_1	S_2



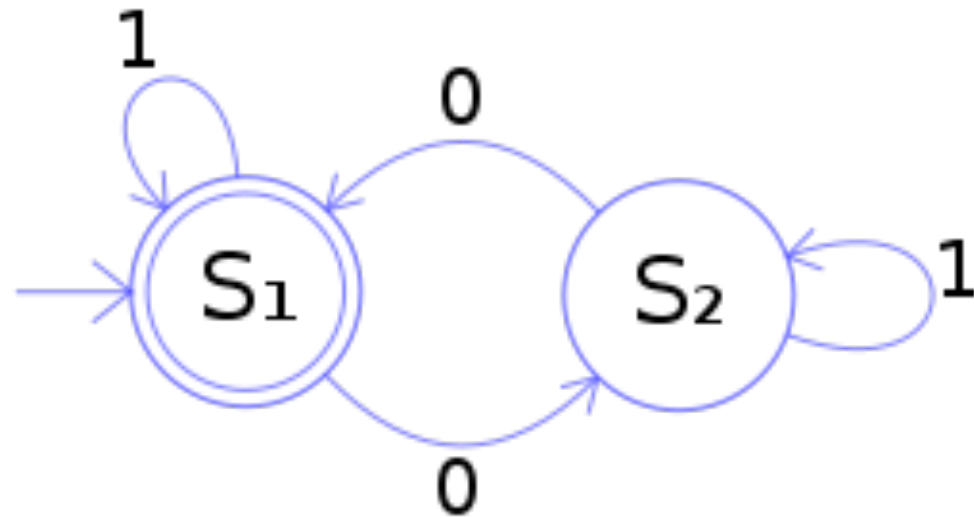
$(\Sigma, S, s_0, \delta, F)$

$(Q, \Sigma, \delta, q_0, F)$

Deterministic Finite Automaton Example (2)

State Transition Table

Input \ State	1	0
S ₁	S ₁	S ₂
S ₂	S ₂	S ₁



$$\{S_1, S_2\} \times 0,1 \rightarrow \{S_1, S_2\}$$

https://en.wikipedia.org/wiki/State_transition_table

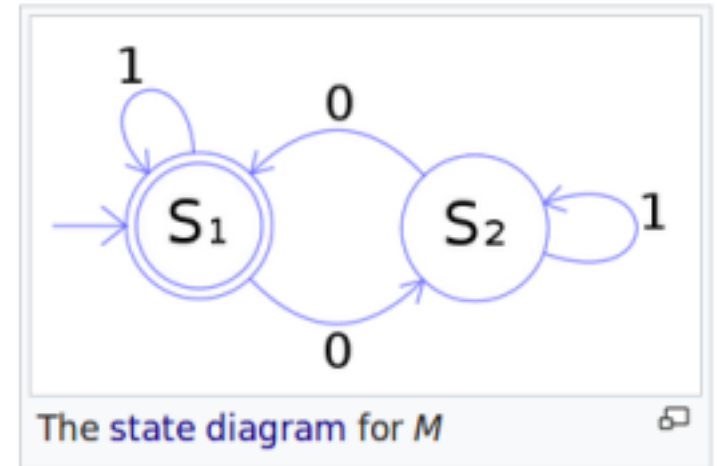
Deterministic Finite Automaton Example (3)

The **state S1** represents that there has been an even number of 0s in the input so far, while **S2** signifies an odd number.

A **1** in the input does not change the state of the automaton.

When the input ends, the state will show whether the input contained an even number of **0s** or not.

If the input did contain an even number of **0s**, M will finish in **state S1**, an accepting state, so the input string will be accepted.

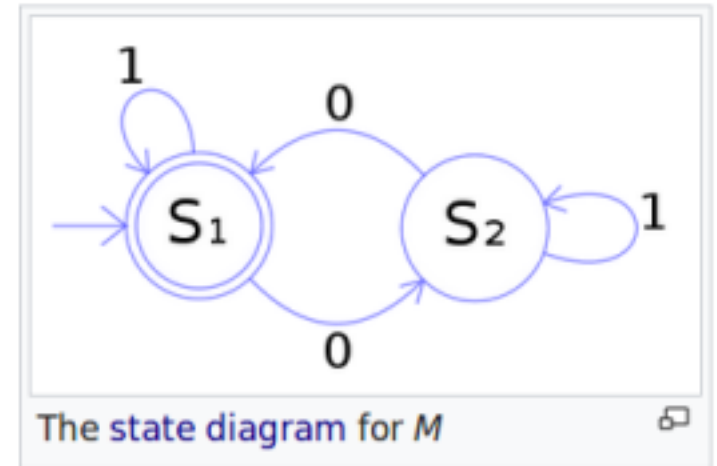


Deterministic Finite Automaton Example (4)

The language recognized by M is
the regular language given
by the regular expression
 $((1^* 0 (1^* 0 (1^*))^*$,

where "*" is the Kleene star,
e.g., 1^* denotes any number
(possibly zero) of consecutive **ones**.

zero or more



References

[1] <http://en.wikipedia.org/>

[2]

Formal Language (3A)

- Regular Language

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Formal Language

a **formal language** is
a set of **strings** of **symbols**
together with a set of **rules**
that are specific to it.

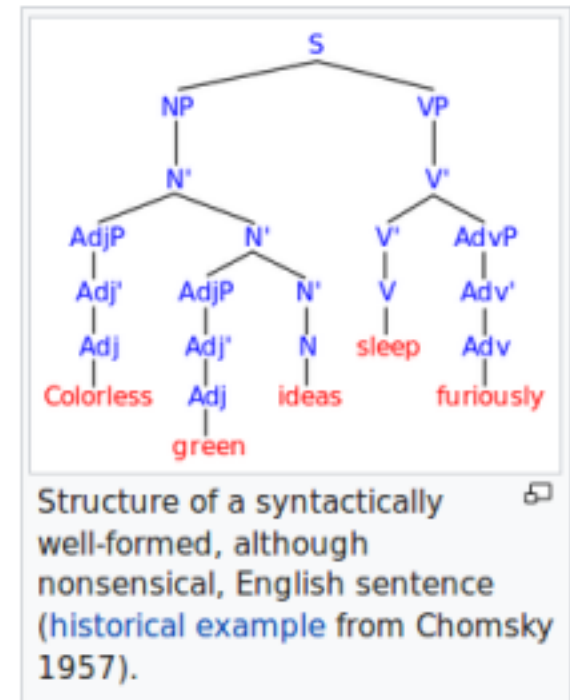
https://en.wikipedia.org/wiki/Formal_language

Alphabet and Words

The **alphabet** of a formal language is the **set** of **symbols**, **letters**, or **tokens** from which the **strings** of the language may be formed.

The **strings** formed from this alphabet are called **words**

the **words** that belong to a particular formal language are sometimes called **well-formed words** or **well-formed formulas**.



https://en.wikipedia.org/wiki/Formal_language

Formal Language

A **formal language (formation rule)**
is often defined by means of
a **formal grammar**
such as a **regular grammar** or
context-free grammar,

https://en.wikipedia.org/wiki/Formal_language

Formal Language and Natural Language

The field of **formal language** theory studies primarily the purely **syntactical aspects** of such languages—that is, their internal **structural patterns**.

Formal language theory sprang out of linguistics, as a way of understanding the **syntactic regularities** of **natural languages**.

formalized versions of subsets of **natural languages** in which the words of the language represent **concepts** that are associated with particular **meanings** or **semantics**.

https://en.wikipedia.org/wiki/Formal_language

Formal Language and Programming Languages

In computer science, formal languages are used among others as the basis for defining the **grammar** of **programming languages**

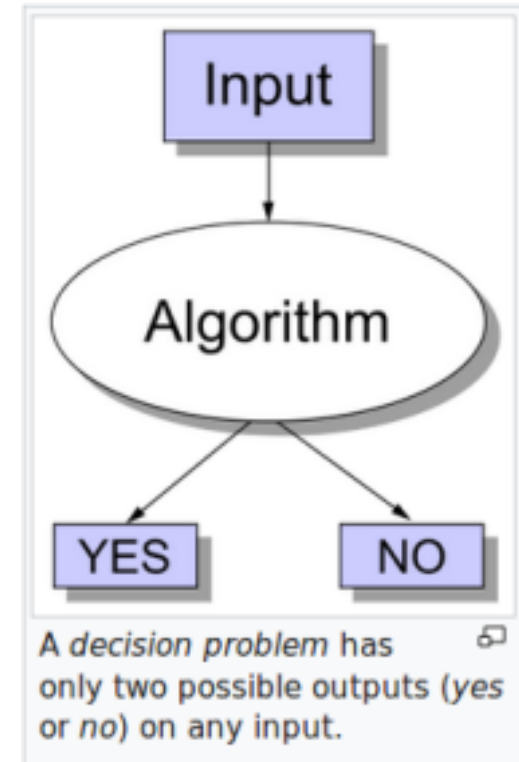
https://en.wikipedia.org/wiki/Formal_language

Formal Language and Complexity Theory

In computational **complexity theory**, **decision problems** are typically defined as formal languages, and

complexity classes are defined as the sets of the formal languages that can be parsed by machines with limited computational power.

These inputs can be natural numbers, but may also be values of some other kind, such as strings over the binary alphabet $\{0,1\}$ or over some other finite set of symbols. The subset of strings for which the problem returns "yes" is a formal language, and often decision problems are defined in this way as formal languages.



https://en.wikipedia.org/wiki/Formal_language
https://en.wikipedia.org/wiki/Decision_problem

Formal Language and Logic / Mathematics

In **logic** and the foundations of **mathematics**, formal languages are used to represent the **syntax** of **axiomatic systems**, and **mathematical formalism** is the philosophy that all of mathematics can be reduced to the **syntactic manipulation** of formal languages in this way.

https://en.wikipedia.org/wiki/Formal_language

Alphabet

An **alphabet** can be any set
think a **character set** such as ASCII.
the elements of an alphabet are called its **letters**.
 an **infinite** number of elements
 a **finite** number of elements

https://en.wikipedia.org/wiki/Formal_language

Words over an alphabet

A **word** over an **alphabet** can be any finite sequence (i.e., string) of **letters**.

The set of all words over an **alphabet** Σ is usually denoted by Σ^* (using the **Kleene star**).

The **length** of a word is the number of letters
only one word of **length 0**, the **empty word** (ϵ / ε / λ or even Λ)
By **concatenation** one can combine two words to form a new word

in logic, the **alphabet** is also known as the **vocabulary**
and **words** are known as **formulas** or **sentences**;

the letter/word metaphor	: formal language
a word/sentence metaphor	: logic

https://en.wikipedia.org/wiki/Formal_language

Kleene star

Given a set V define

$V_0 = \{\varepsilon\}$ (the language consisting only of the empty string),

$V_1 = V$

and define recursively the set

$V_{i+1} = \{wv : w \in V_i \text{ and } v \in V\}$ for each $i > 0$.

$V^* = \bigcup_{i \in \mathbb{N}} V_i = \{\varepsilon\} \cup V \cup V_2 \cup V_3 \cup V_4 \cup \dots$ *: zero or more

$V^+ = \bigcup_{i \in \mathbb{N} \setminus \{0\}} V_i = V_1 \cup V_2 \cup V_3 \cup \dots$ +: one or more

$$\mathbb{N}^0 = \mathbb{N}_0 = \{0, 1, 2, \dots\}$$

$$\mathbb{N}^* = \mathbb{N}^+ = \mathbb{N}_1 = \mathbb{N}_{>0} = \{1, 2, \dots\}.$$

https://en.wikipedia.org/wiki/Kleene_star

$$\mathbb{N} = \{0, 1, 2, \dots\}.$$

$$\mathbb{Z}^+ = \{1, 2, \dots\}.$$

Kleene star examples (1)

$\{\text{"ab"}, \text{"c"}\}^* = \{ \varepsilon, \text{"ab"}, \text{"c"}, \text{"abab"}, \text{"abc"}, \text{"cab"}, \text{"cc"}, \text{"ababab"}, \text{"ababc"}, \text{"abcab"}, \text{"abcc"}, \text{"cabab"}, \text{"cabac"}, \text{"ccab"}, \text{"ccc"}, \dots \}.$

$\{\text{"a"}, \text{"b"}, \text{"c"}\}^+ = \{ \text{"a"}, \text{"b"}, \text{"c"}, \text{"aa"}, \text{"ab"}, \text{"ac"}, \text{"ba"}, \text{"bb"}, \text{"bc"}, \text{"ca"}, \text{"cb"}, \text{"cc"}, \text{"aaa"}, \text{"aab"}, \dots \}.$

$\{\text{"a"}, \text{"b"}, \text{"c"}\}^* = \{ \varepsilon, \text{"a"}, \text{"b"}, \text{"c"}, \text{"aa"}, \text{"ab"}, \text{"ac"}, \text{"ba"}, \text{"bb"}, \text{"bc"}, \text{"ca"}, \text{"cb"}, \text{"cc"}, \text{"aaa"}, \text{"aab"}, \dots \}.$

$\emptyset^* = \{\varepsilon\}.$

$\emptyset^+ = \emptyset$

$\emptyset^* = \{ \} = \emptyset,$

https://en.wikipedia.org/wiki/Kleene_star

Kleene star examples (2)

$\{ab, c\}^* =$
{ ϵ ,
ab, c,
abab, abc, cab, cc,
ababab, ababc, abcab, abcc, cabab, cabc, ccab, ccc, ... }

$\{a, b, c\}^+ =$
{ a, b, c,
aa, ab, ac, ba, bb, bc, ca, cb, cc,
aaa, aab, aac, aba, abb, abc, aca, acb, acc, baa, bab, bac, bba, bbb, bbc, bca, bcb, bcc, ... }

$\{a, b, c\}^*$
{ ϵ
a, b, c,
aa, ab, ac, ba, bb, bc, ca, cb, cc,
aaa, aab, aac, aba, abb, abc, aca, acb, acc, baa, bab, bac, bba, bbb, bbc, bca, bcb, bcc, ... }

https://en.wikipedia.org/wiki/Kleene_star

Kleene star examples (3)

regular expression

$((1^*) 0 (1^*) 0 (1^*))^*$,

$(1^*) = \{\epsilon, 1, 11, 111, \dots\}$

$$\begin{pmatrix} e \\ 1 \\ 11 \\ 111 \\ \vdots \end{pmatrix} 0 \begin{pmatrix} e \\ 1 \\ 11 \\ 111 \\ \vdots \end{pmatrix} 0 \begin{pmatrix} e \\ 1 \\ 11 \\ 111 \\ \vdots \end{pmatrix}$$

$00\{e, 1, 11, 111, \dots\}$	$100\{e, 1, 11, 111, \dots\}$	$1100\{e, 1, 11, 111, \dots\}$	$11100\{e, 1, 11, 111, \dots\}$
$010\{e, 1, 11, 111, \dots\}$	$1010\{e, 1, 11, 111, \dots\}$	$11010\{e, 1, 11, 111, \dots\}$	$111010\{e, 1, 11, 111, \dots\}$
$0110\{e, 1, 11, 111, \dots\}$	$10110\{e, 1, 11, 111, \dots\}$	$110110\{e, 1, 11, 111, \dots\}$	$1110110\{e, 1, 11, 111, \dots\}$
$01110\{e, 1, 11, 111, \dots\}$	$101110\{e, 1, 11, 111, \dots\}$	$1101110\{e, 1, 11, 111, \dots\}$	$11101110\{e, 1, 11, 111, \dots\}$
\vdots	\vdots	\vdots	\vdots

https://en.wikipedia.org/wiki/Kleene_star

Formal Language Definition

A **formal language L** over an **alphabet Σ** is a **subset of Σ^*** , that is, a set of **words** over that alphabet.

Sometimes the sets of **words** are grouped into **expressions**, whereas **rules** and **constraints** may be formulated for the creation of '**well-formed expressions**'.

https://en.wikipedia.org/wiki/Formal_language

Formal Language Examples (1)

The following **rules** describe
a **formal language L**

over the **alphabet** $\Sigma = \{ 0, 1, 2, 3, 4, 5, 6, 7, 8, 9, +, = \}$:

- every nonempty string is in **L**
 - that does not contain "+" or "="
 - does not start with "0"
- the string "0" is in **L**.
- a string containing "=" is in **L**
 - if and only if there is exactly one "=",
 - and it separates two valid strings of **L**.
- a string containing "+" but not "=" is in **L**
 - if and only if every "+" in the string separates two valid strings of **L**.
- no string is in **L** other than those implied by the previous rules.

https://en.wikipedia.org/wiki/Formal_language

Formal Language Examples (2)

Under these rules,
the string "**23+4=555**" is in L,
but the string "**=234=+**" is not.

This formal language expresses

- **natural numbers**,
- well-formed **additions**,
- and well-formed **addition equalities**,

but it expresses only what they look like (their **syntax**),
not what they mean (**semantics**).

for instance, nowhere in these rules is
there any indication that "0" means the number zero,
or that "+" means addition.

https://en.wikipedia.org/wiki/Formal_language

Formal Language Examples (3)

- $L = \Sigma^*$, the set of all **words** over Σ ;
- $L = \{ "a" \}^* = \{ "a"^n \}$, where n ranges over the natural numbers and " a " ^{n} means " a " repeated n times
(this is the set of words consisting only of the symbol " a ");
- the set of **syntactically correct** programs in a given programming language (the syntax of which is usually defined by a **context-free grammar**);
- the set of inputs upon which a certain **Turing machine** halts; or
- the set of **maximal strings** of alphanumeric ASCII characters on this line, i.e., the set $\{ "the", "set", "of", "maximal", "strings", "alphanumeric", "ASCII", "characters", "on", "this", "line", "i", "e" \}$.

https://en.wikipedia.org/wiki/Formal_language

Formal Language Examples (4)

For instance, a **language** can be given as

- those strings generated by some **formal grammar**;
- those strings described or matched by a particular **regular expression**;
- those strings accepted by some automaton,
such as a **Turing machine** or **finite state automaton**;
- those **strings** for which some **decision procedure**
produces the answer YES.

(an algorithm that asks a sequence of related YES/NO questions)

https://en.wikipedia.org/wiki/Formal_language

Formal Grammar Example

the alphabet consists of **a** and **b**,
the start symbol is **S**,
the **production rules**:

1. **S** → **aSb**
2. **S** → **ba**

then we start with **S**, and can choose a rule to apply to it.

Application of rule 1, the string **aSb**.

Another application of rule 1, the string **aaSbb**.

Application of rule 2, the string **aababb**

$$S \Rightarrow aSb \Rightarrow aaSbb \Rightarrow aababb$$

The **language** of the grammar is then the infinite set

$$\{a^n bab^n \mid n \geq 0\} = \{ba, abab, aababb, aaababbb, \dots\}$$

https://en.wikipedia.org/wiki/Formal_language

Syntax of Formal Grammars

a **grammar** G consists of the following components:

- A finite set N of **nonterminal symbols**, that is disjoint with the strings formed from G .
- A finite set Σ of **terminal symbols** that is disjoint from N .
- A finite set P of **production rules**,
 $(\Sigma \cup N)^* N (\Sigma \cup N)^* \rightarrow (\Sigma \cup N)^*$
- A distinguished symbol $S \in N$ that is the **start symbol**, also called the **sentence symbol**.

A grammar is formally defined as the tuple (N, Σ, P, S)

often called a rewriting system
or a phrase structure grammar

https://en.wikipedia.org/wiki/Formal_language

Terminal and Non-terminal Symbols

Terminal symbols are the elementary symbols of the language defined by a formal grammar.

Nonterminal symbols (or syntactic variables) are replaced by groups of **terminal symbols** according to the **production rules**.

A formal grammar includes a **start symbol**, a designated member of the set of **nonterminals** from which all the strings in the language may be derived by successive applications of the **production rules**.

In fact, the language defined by a grammar is precisely the set of **terminal strings** that can be so derived.

https://en.wikipedia.org/wiki/Terminal_and_nonterminal_symbols

Production Rules

$$(\Sigma \cup N)^* N (\Sigma \cup N)^* \rightarrow (\Sigma \cup N)^*$$

Head \rightarrow Body

- each **production rule** maps from one string of symbols to another
- the first string (the "head") contains
 - an arbitrary number of symbols
 - provided at least one of them is a **nonterminal**. ***N***
- If the second string (the "body") consists solely of the **empty string**
 - i.e., that it contains no symbols at all
 - it may be denoted with a special notation (Λ , e or ϵ)

https://en.wikipedia.org/wiki/Formal_language

Grammar Examples (1)

Consider the grammar **G**

where $\mathbf{N} = \{ \mathbf{S}, \mathbf{B} \}$, $\Sigma = \{ \mathbf{a}, \mathbf{b}, \mathbf{c} \}$, **S** is the start symbol, and **P** consists of the following production rules:

1. **S** \rightarrow **aBSc**
2. **S** \rightarrow **abc**
3. **Ba** \rightarrow **aB**
4. **Bb** \rightarrow **bb**

This grammar defines the language $\mathbf{L(G)} = \{ \mathbf{a}^n \mathbf{b}^n \mathbf{c}^n \mid n \geq 1 \}$ where \mathbf{a}^n denotes a string of **n** consecutive **a**'s.

Thus, the language is the set of strings that consist of **1 or more a's**, followed by the same number of **b's**, followed by the same number of **c's**.

https://en.wikipedia.org/wiki/Formal_language

Grammar Examples (2)

$$S \xRightarrow{2} abc$$

$$\begin{aligned} S &\xRightarrow{1} aBSc \\ &\xRightarrow{2} aBabcc \\ &\xRightarrow{3} aaBbcc \\ &\xRightarrow{4} aabbcc \end{aligned}$$

$$\begin{aligned} S &\xRightarrow{1} aBSc \xRightarrow{1} aBaBSc \\ &\xRightarrow{2} aBaBabccc \\ &\xRightarrow{3} aaBBabccc \xRightarrow{3} aaBaBbccc \xRightarrow{3} aaaBBbccc \\ &\xRightarrow{4} aaaBbbccc \xRightarrow{4} aaabbbccc \end{aligned}$$

1. $S \rightarrow aBSc$
2. $S \rightarrow abc$
3. $Ba \rightarrow aB$
4. $Bb \rightarrow bb$

https://en.wikipedia.org/wiki/Formal_language

Context Free Grammars

Context-free grammars are those grammars in which the left-hand side of each **production rule** consists of only a single nonterminal symbol.

This restriction is non-trivial; not all languages can be generated by context-free grammars.

$$\begin{aligned} S &\rightarrow aSb \\ S &\rightarrow ba \end{aligned}$$

Those that can are called **context-free languages**.

https://en.wikipedia.org/wiki/Terminal_and_nonterminal_symbols

Context Free Grammar Examples

The language $L(G) = \{a^n b^n c^n \mid n \geq 1\}$ is not a **context-free language**
the grammar **G**

where $N = \{S, B\}$, $\Sigma = \{a, b, c\}$, **S** is the start symbol,
and **P** consists of the following production rules:

1. **S** \rightarrow **aBSc**
2. **S** \rightarrow **abc**
3. **Ba** \rightarrow **aB**
4. **Bb** \rightarrow **bb**

The language $\{a^n b^n \mid n \geq 1\}$ is **context-free**

(at least 1 **a** followed by the same number of **b**)

the grammar **G2** with $N = \{S\}$, $\Sigma = \{a, b\}$, **S** the start symbol,
and **P** the following production rules:

1. **S** \rightarrow **a S b**
2. **S** \rightarrow **a b**

https://en.wikipedia.org/wiki/Formal_language

Regular Expression Examples

- .at** matches any three-character string ending with "at", including "hat", "cat", and "bat".
- [hc]at** matches "hat" and "cat".
- [^b]at** matches all strings matched by .at except "bat".
- [^hc]at** matches all strings matched by .at other than "hat" and "cat".
- ^[hc]at** matches "hat" and "cat", but only at the beginning of the string or line.
- [hc]at\$** matches "hat" and "cat", but only at the end of the string or line.
- \[.\\]** matches any single character surrounded by "[" and "]" since the brackets are escaped, for example: "[a]" and "[b]".
- s.*** matches s followed by zero or more characters, for example: "s" and "saw" and "seed".

- [hc]?at** matches "at", "hat", and "cat".
- [hc]*at** matches "at", "hat", "cat", "hhat", "chat", "hcat", "cchchat", ...
- [hc]+at** matches "hat", "cat", "hhat", "chat", "hcat", "cchchat",..., but not "at".
- cat|dog** matches "cat" or "dog".

https://en.wikipedia.org/wiki/Regular_expression

Chomsky's four types of grammars

Grammar	Languages	Automaton	Production rules (constraints)*
Type-0	Recursively enumerable	Turing machine	$\alpha \rightarrow \beta$ (no restrictions)
Type-1	Context-sensitive	Linear-bounded non-deterministic Turing machine	$\alpha A \beta \rightarrow \alpha \gamma \beta$
Type-2	Context-free	Non-deterministic pushdown automaton	$A \rightarrow \gamma$
Type-3	Regular	Finite state automaton	$A \rightarrow a$ and $A \rightarrow aB$

* Meaning of symbols:
a = terminal
 α = string of terminals, non-terminals, or empty
 β = string of terminals, non-terminals, or empty
 γ = string of terminals, non-terminals, never empty
A = non-terminal
B = non-terminal

https://en.wikipedia.org/wiki/Chomsky_hierarchy

Type-0 grammars

Unrestricted grammar

Type-0 grammars include all **formal grammars**.

They generate exactly all languages that can be recognized by a **Turing machine**.

These languages are also known as the **recursively enumerable** or **Turing-recognizable languages**.

Note that this is different from the **recursive languages**, which can be decided by an **always-halting Turing machine**.

https://en.wikipedia.org/wiki/Regular_expression

Type-0 grammars

Context-sensitive grammar

Type-1 grammars generate the **context-sensitive languages**.

These grammars have rules of the form $\alpha A \beta \rightarrow \alpha \gamma \beta$ with A a **nonterminal** and α , β , and γ strings of **terminals** and/or **nonterminals**.

The strings α and β may be empty, but γ must be nonempty.

The rule $S \rightarrow \epsilon$ is allowed if S does not appear on the right side of any rule.

The languages described by these grammars are exactly all languages that can be recognized by a **linear bounded automaton** (a **nondeterministic** Turing machine whose tape is bounded by a constant times the length of the input.)

https://en.wikipedia.org/wiki/Regular_expression

Type-2 grammars

Context-free grammar

Type-2 grammars generate the context-free languages.

These are defined by rules of the form $A \rightarrow \gamma$ with A being a nonterminal and γ being a string of terminals and/or nonterminals.

These languages are exactly all languages that can be recognized by a **non-deterministic pushdown automaton**.

Context-free languages—or rather its subset of deterministic context-free language—are the theoretical basis for the phrase structure of most **programming languages**, though their syntax also includes context-sensitive name resolution due to declarations and scope.

Often a subset of grammars is used to make parsing easier, such as by an LL parser.

https://en.wikipedia.org/wiki/Regular_expression

Type-3 grammars (1)

Regular grammar

Type-3 grammars generate the regular languages.

restricts its rules to a single nonterminal on the **left**-hand side

a **right**-hand side consisting of a single terminal,
possibly followed by a **single nonterminal (right regular)**.

the **right**-hand side consisting of a single terminal,
possibly preceded by a **single nonterminal (left regular)**.

https://en.wikipedia.org/wiki/Regular_expression

Type-3 grammars (1)

Right regular and left regular generate the same languages.

However, if left-regular rules and right-regular rules are combined, the language need no longer be regular.

The rule $S \rightarrow \epsilon$ is also allowed here if S does not appear on the right side of any rule.

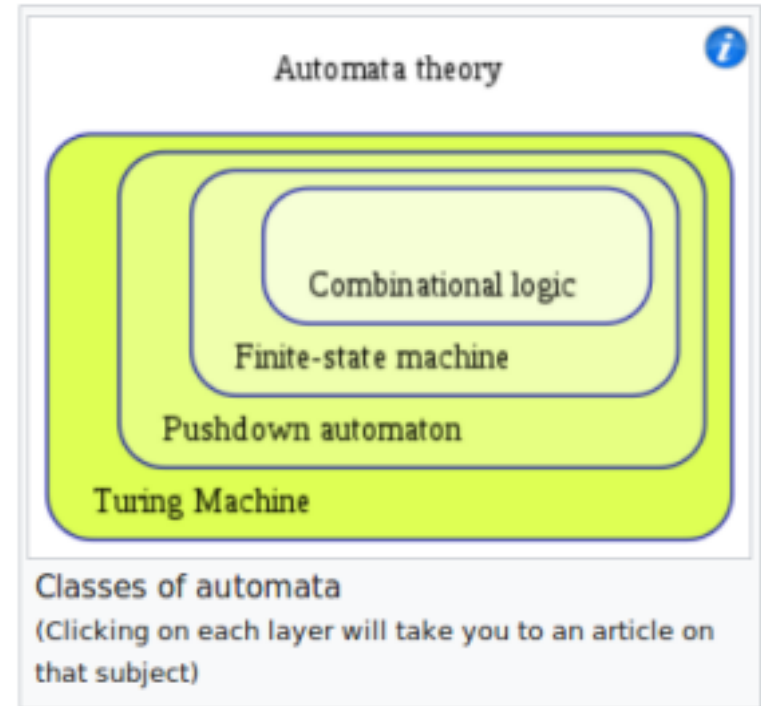
These languages are exactly all languages that can be decided by a **finite state automaton**.

Additionally, this family of formal languages can be obtained by **regular expressions**.

Regular languages are commonly used to define search patterns and the lexical structure of programming languages.

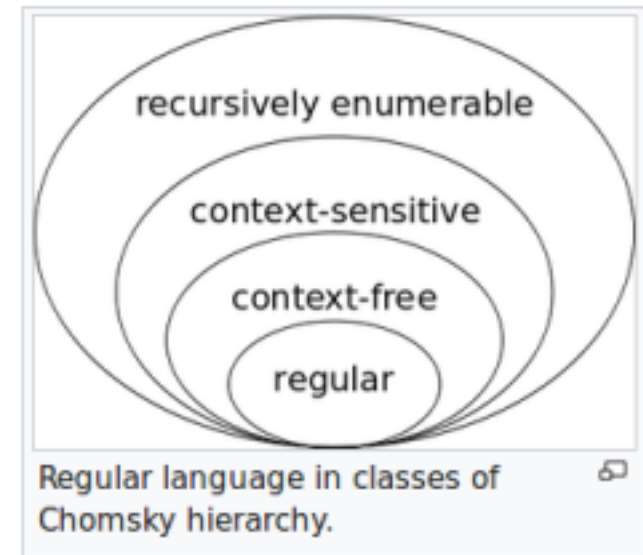
https://en.wikipedia.org/wiki/Regular_expression

Class of Automata



https://en.wikipedia.org/wiki/Automata_theory

Chomsky Hierarchy



https://en.wikipedia.org/wiki/Regular_language

Class of Automata

Finite State Machine (FSM)	Regular Language
Pushdown Automaton (PDA)	Context-Free Language
Turing Machine	Recursively Enumerable Language

https://en.wikipedia.org/wiki/Automata_theory

Regular Language

a **regular language** (a **rational language**) is a formal language that can be expressed using a **regular expression**, in the strict sense

Alternatively, a regular language can be defined as a language recognized by a **finite automaton**.

The equivalence of **regular expressions** and **finite automata** is known as **Kleene's theorem**.

Regular languages are very useful in input parsing and programming language design.

https://en.wikipedia.org/wiki/Regular_language

Regular Language – Formal Definition

The collection of **regular languages** over an **alphabet** Σ is defined recursively as follows:

The **empty language** \emptyset , and the **empty string language** $\{\epsilon\}$ are **regular languages**.

For each $a \in \Sigma$ (a belongs to Σ), the **singleton language** $\{a\}$ is a **regular language**.

If A and B are **regular languages**, then $A \cup B$ (**union**), $A \cdot B$ (**concatenation**), and A^* (**Kleene star**) are **regular languages**.

No other languages over Σ are **regular**.

See regular expression for its syntax and semantics. Note that the above cases are in effect the defining rules of regular expression.

https://en.wikipedia.org/wiki/Regular_language

Equivalent Formalism

1. it is the language of a **regular expression** (by the above definition)
2. it is the language accepted by a **nondeterministic finite automaton (NFA)**
3. it is the language accepted by a **deterministic finite automaton (DFA)**
4. it can be generated by a **regular grammar**
5. it is the language accepted by an **alternating finite automaton**
6. it can be generated by a **prefix grammar**
7. it can be accepted by a read-only Turing machine

https://en.wikipedia.org/wiki/Regular_language

Regular Language Example

All **finite** languages are **regular**;

in particular the **empty** string language $\{\epsilon\} = \emptyset^*$ is **regular**.

Other typical examples include the language consisting of **all strings** over the **alphabet** $\{a, b\}$ which contain an even number of a's, or the language consisting of all strings of the form: several a's followed by several b's.

A simple example of a language that is **not regular** is the set of strings $\{ a^n b^n \mid n \geq 0 \}$.

Intuitively, it cannot be recognized with a **finite automaton**, since a **finite automaton** has **finite memory** and it cannot remember the exact number of a's.

https://en.wikipedia.org/wiki/Regular_language

References

- [1] <http://en.wikipedia.org/>
- [2]