

Time Domain Analysis (1A)

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2nd Order Systems

$$\frac{9}{s^2+9s+9}$$

$$s^2+9s+9 = 0$$

$$m_1, m_2 = \frac{-9 \pm 3\sqrt{5}}{2}$$

$$\frac{9}{s^2+2s+9}$$

$$s^2+2s+9 = 0$$

$$m_1, m_2 = -1 \pm i2\sqrt{2}$$

$$\frac{9}{s^2+9}$$

$$s^2+9 = 0$$

$$m_1, m_2 = \pm i3$$

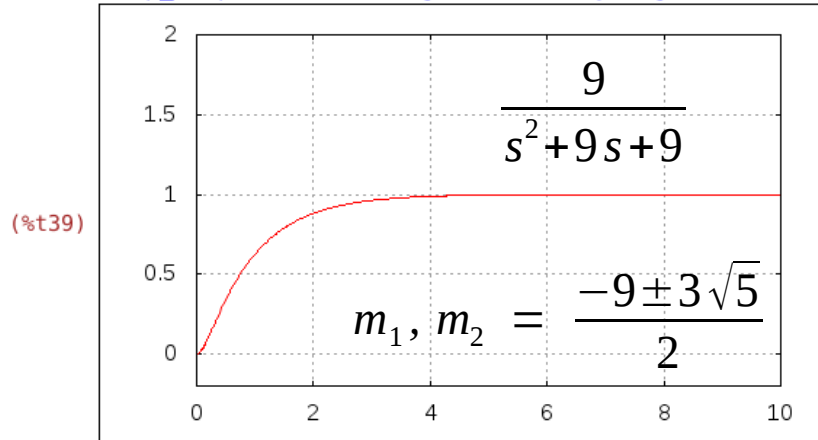
$$\frac{9}{s^2+6s+9}$$

$$s^2+6s+9 = 0$$

$$m_1, m_2 = -3$$

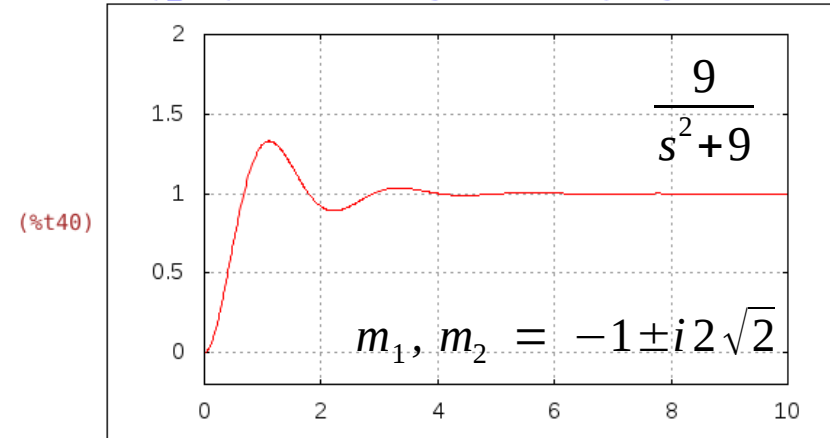
Step Responses

(%i39) step_response(G1, xrange=[0, 10], yrange=[-0.2, 2]);



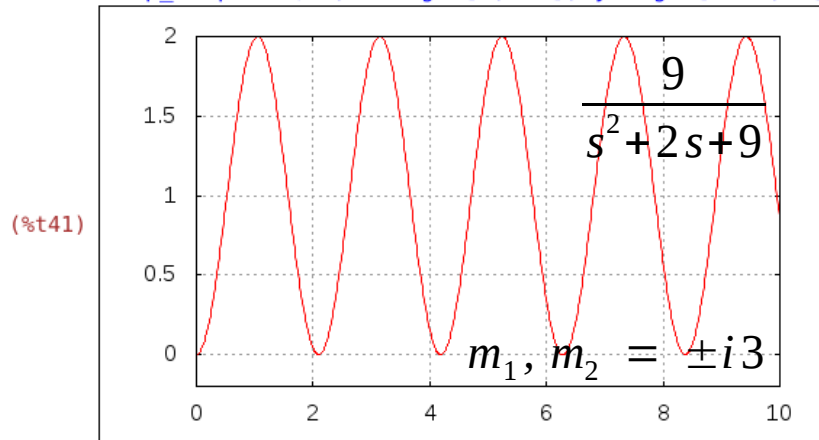
(%o39)

(%i40) step_response(G2, xrange=[0, 10], yrange=[-0.2, 2]);



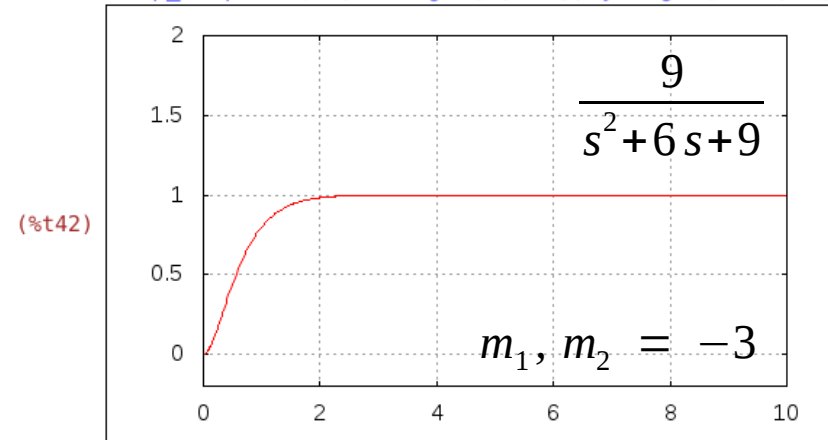
(%o40)

(%i41) step_response(G3, xrange=[0, 10], yrange=[-0.2, 2]);



(%o41)

(%i42) step_response(G4, xrange=[0, 10], yrange=[-0.2, 2]);



(%o42)

2nd Order Transfer Function: Standard Form

$$G(s) = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

$$s^2 + 2\zeta\omega_n s + \omega_n^2 = 0$$

$$s = -\zeta\omega_n \pm \sqrt{\zeta^2\omega_n^2 - \omega_n^2}$$

$$= -\zeta\omega_n \pm \sqrt{\zeta^2 - 1}\omega_n$$

$$= -\zeta\omega_n \pm j\sqrt{1 - \zeta^2}\omega_n$$

$$s = -\zeta\omega_n \pm \sqrt{\zeta^2 - 1}\omega_n \quad \zeta > 1$$

$$s = -\omega_n \quad \zeta = 1$$

$$s = -\zeta\omega_n \pm j\sqrt{1 - \zeta^2}\omega_n \quad 0 < \zeta < 1$$

$$s = \pm j\omega_n \quad \zeta = 0$$

2nd Order Transfer Function: Standard Form

$$G(s) = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

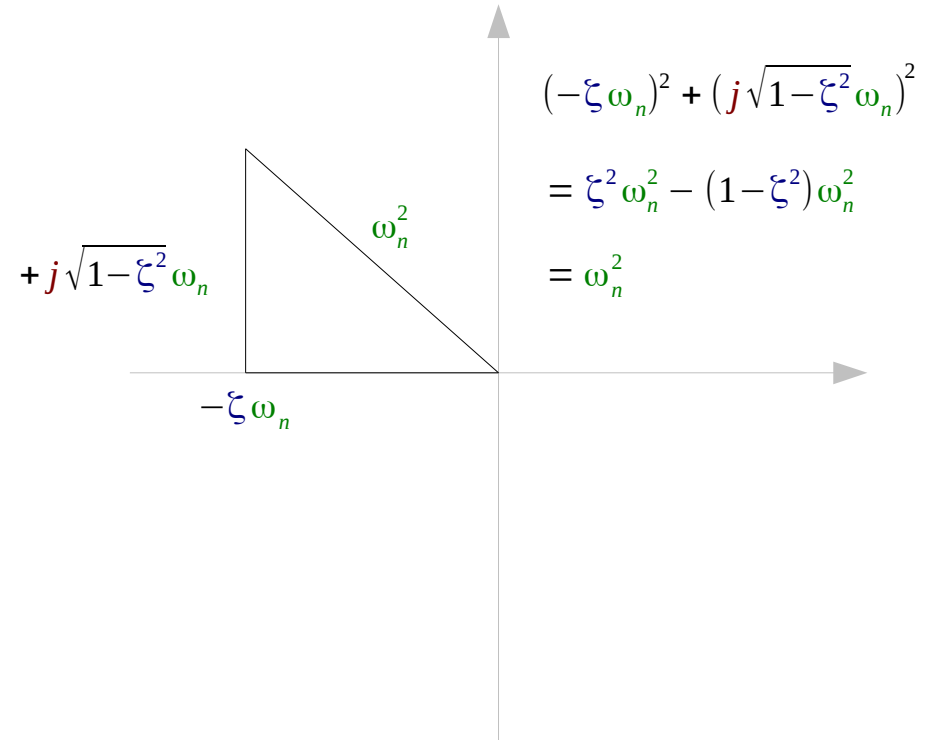
$$s^2 + 2\zeta\omega_n s + \omega_n^2 = 0$$

$$s = -\zeta\omega_n \pm \sqrt{\zeta^2 - 1}\omega_n \quad \zeta > 1$$

$$s = -\omega_n \quad \zeta = 1$$

$$s = -\zeta\omega_n \pm j\sqrt{1 - \zeta^2}\omega_n \quad 0 < \zeta < 1$$

$$s = \pm j\omega_n \quad \zeta = 0$$



2nd Order Transfer Function: Standard Form

$$s = -\zeta\omega_n \pm j\sqrt{1-\zeta^2}\omega_n \quad 0 < \zeta < 1$$

$$\zeta = 0.1, \quad \omega_n = 200 \quad s^2 + 4s + 20\sqrt{0.99}$$

$$\zeta = 0.2, \quad \omega_n = 100 \quad s^2 + 4s + 10\sqrt{0.96}$$

$$\zeta = 0.4, \quad \omega_n = 50 \quad s^2 + 4s + 5\sqrt{0.84}$$

2nd Order Systems

$$\frac{\omega_n^2}{(s^2 + 2\zeta\omega_n s + \omega_n^2)}$$

$$\frac{\omega_n^2}{s(s^2 + 2\zeta\omega_n s + \omega_n^2)}$$

$$\frac{\omega_n^2}{s^2(s^2 + 2\zeta\omega_n s + \omega_n^2)}$$

$$\zeta = \sqrt{0.75}$$

$$\omega_n = 1$$

$$2e^{-\frac{\sqrt{3}}{2}t} \sin\left(\frac{t}{2}\right)$$

$$e^{-\frac{\sqrt{3}}{2}t} \left(-\cos\left(\frac{t}{2}\right) - \sqrt{3} \sin\left(\frac{t}{2}\right) \right) + 1$$

$$e^{-\frac{\sqrt{3}}{2}t} \left(\sqrt{3} \cos\left(\frac{t}{2}\right) + \sin\left(\frac{t}{2}\right) \right) + t - \sqrt{3}$$

$$\zeta = 1$$

$$\omega_n = 1$$

$$e^{-t}t$$

$$-e^{-t}t - e^{-t} + 1$$

$$e^{-t}t + 2e^{-t} + t - 2$$

$$\zeta = 2$$

$$\omega_n = 1$$

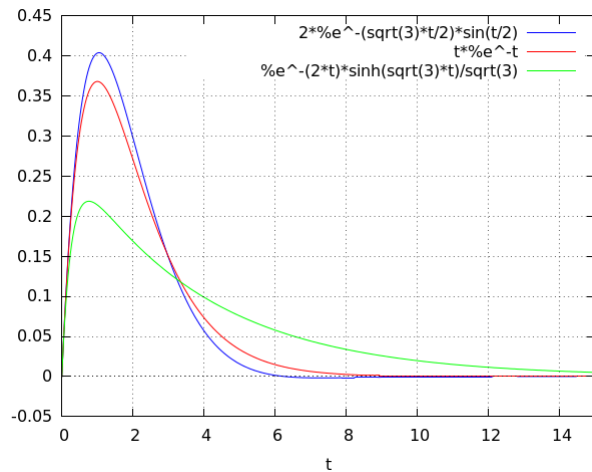
$$\frac{1}{\sqrt{3}}e^{-2t} \sinh(\sqrt{3}t)$$

$$e^{-2t} \left(-\cosh(\sqrt{3}t) - \frac{2}{\sqrt{3}} \sinh \sqrt{3}t \right) + 1$$

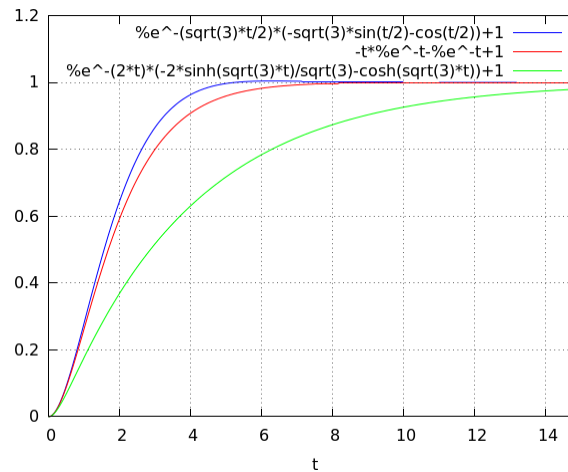
$$e^{-2t} \left(4 \cosh(\sqrt{3}t) + \frac{7}{\sqrt{3}} \sinh \sqrt{3}t \right) + t - 4$$

2nd Order Systems

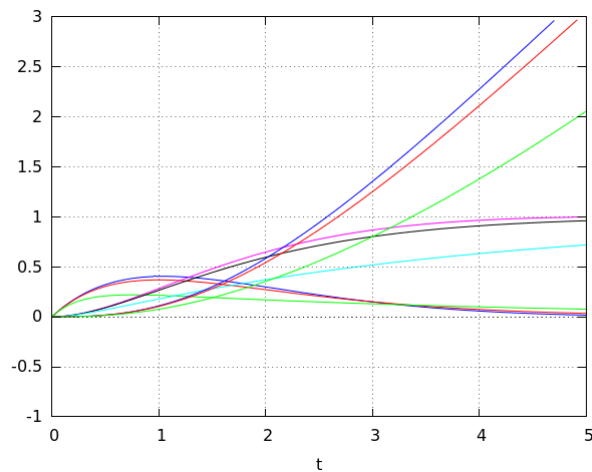
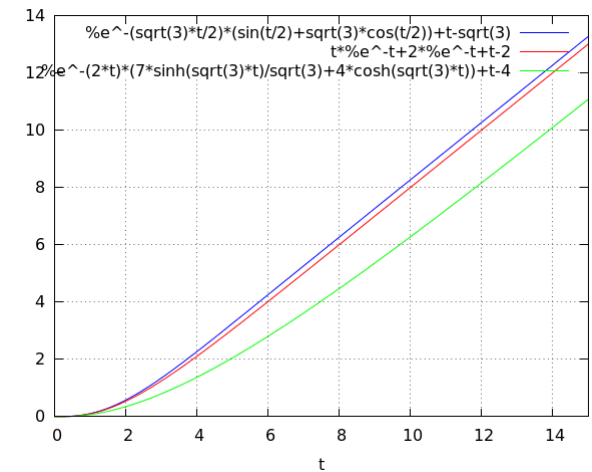
Impulse Response



Step Response



Ramp Response



$$\zeta = \sqrt{0.75}$$

$$\omega_n = 1$$

$$\zeta = 1$$

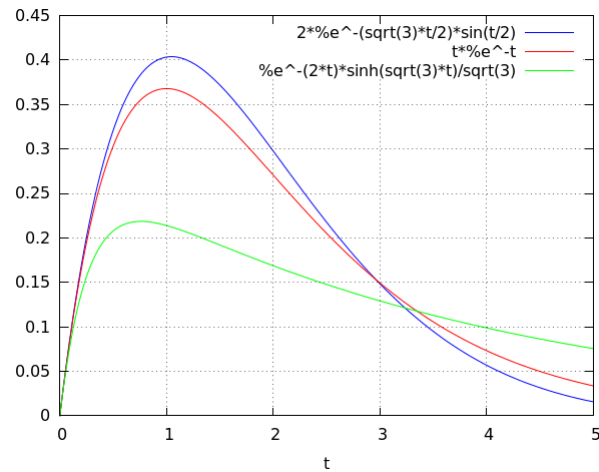
$$\omega_n = 1$$

$$\zeta = 2$$

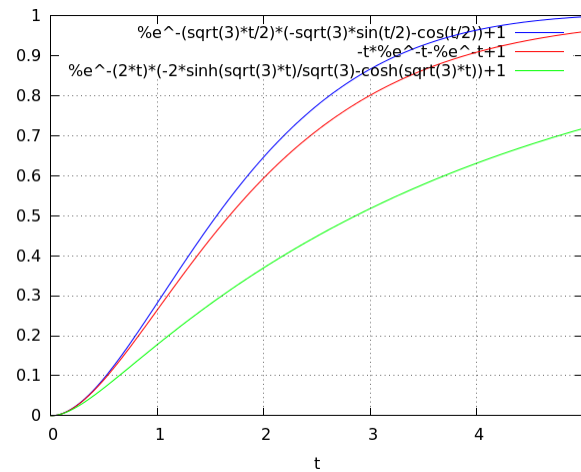
$$\omega_n = 1$$

2nd Order Systems

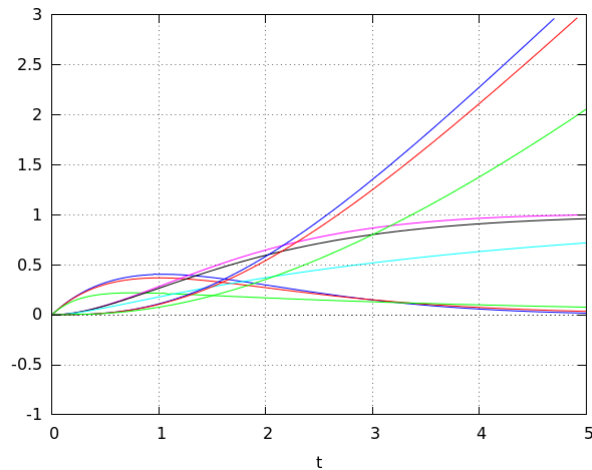
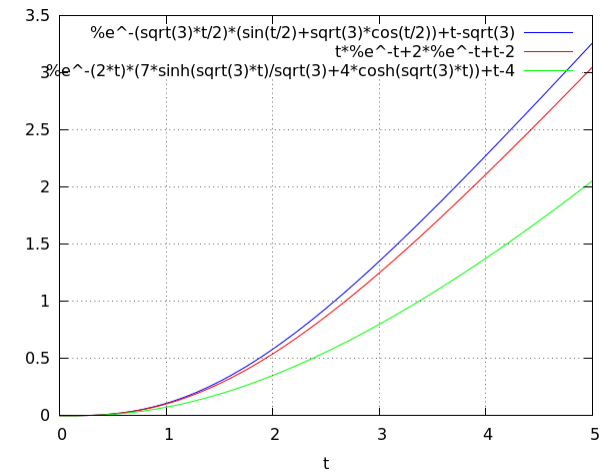
Impulse Response



Step Response



Ramp Response



2nd Order Systems – Underdamping

$$2e^{\frac{-\sqrt{3}}{2}t} \sin(2t)$$

$$e^{\frac{-\sqrt{3}}{2}t} (-\cos(2t) - \sqrt{3} \sin(2t)) + 1$$

$$e^{\frac{-\sqrt{3}}{2}t} (\sqrt{3} \cos(2t) + \sin(2t)) + t - \sqrt{3}$$

$$2e^{\frac{-\sqrt{3}}{2}t} \sin(t)$$

$$e^{\frac{-\sqrt{3}}{2}t} (-\cos(t) - \sqrt{3} \sin(t)) + 1$$

$$e^{\frac{-\sqrt{3}}{2}t} (\sqrt{3} \cos(t) + \sin(t)) + t - \sqrt{3}$$

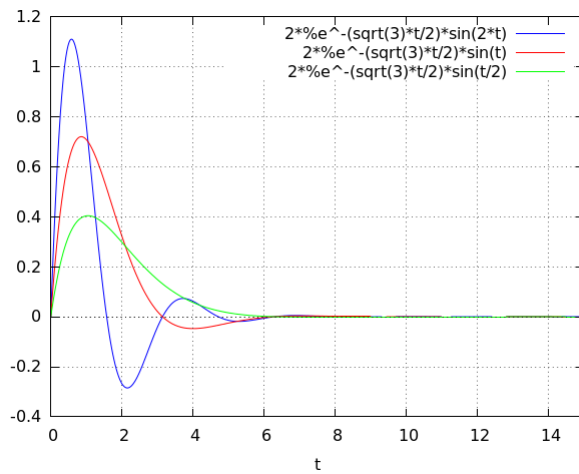
$$2e^{\frac{-\sqrt{3}}{2}t} \sin\left(\frac{t}{2}\right)$$

$$e^{\frac{-\sqrt{3}}{2}t} \left(-\cos\left(\frac{t}{2}\right) - \sqrt{3} \sin\left(\frac{t}{2}\right) \right) + 1$$

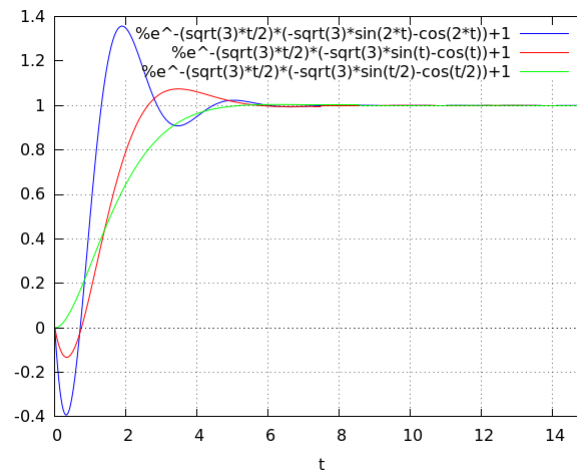
$$e^{\frac{-\sqrt{3}}{2}t} \left(\sqrt{3} \cos\left(\frac{t}{2}\right) + \sin\left(\frac{t}{2}\right) \right) + t - \sqrt{3}$$

2nd Order Systems

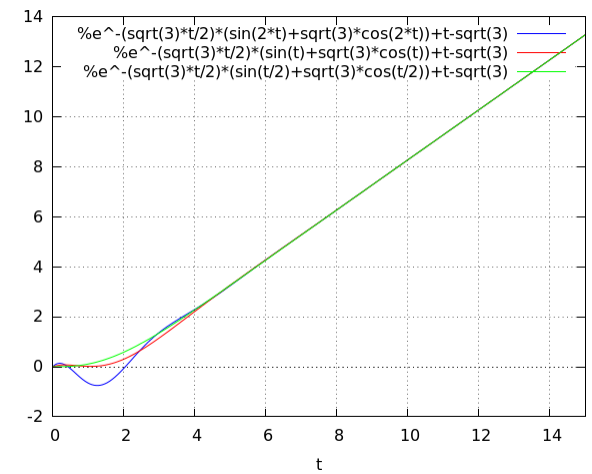
Impulse Response



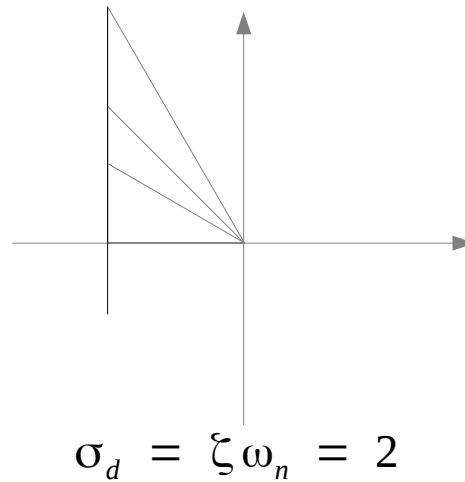
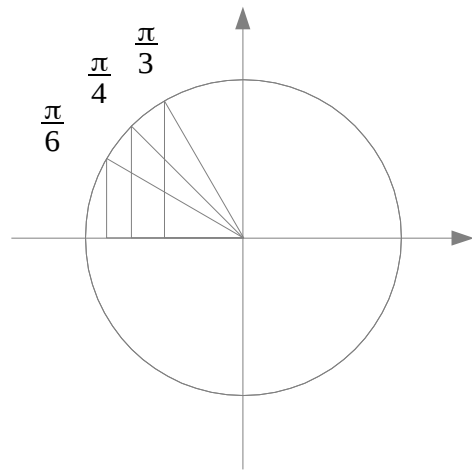
Step Response



Ramp Response



2nd Order Systems – Underdamping



$$\zeta = \frac{1}{2}$$

$$\omega_n = 2 \left(\frac{1}{2} \right)^{-1}$$

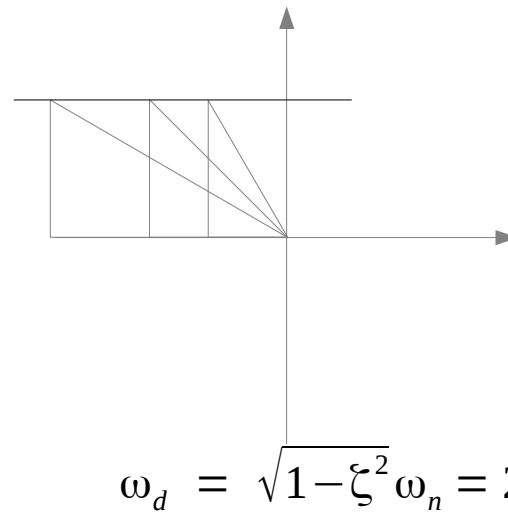
$$\zeta = \frac{\sqrt{2}}{2}$$

$$\omega_n = 2 \left(\frac{\sqrt{2}}{2} \right)^{-1}$$

$$\zeta = \frac{\sqrt{3}}{2}$$

$$\omega_n = 2 \left(\frac{\sqrt{3}}{2} \right)^{-1}$$

$$\sigma_d = \zeta \omega_n = 2$$



$$\zeta = \frac{1}{2}$$

$$\sqrt{1-\zeta^2} = \frac{\sqrt{3}}{2}$$

$$\omega_n = 2 \left(\frac{\sqrt{3}}{2} \right)^{-1}$$

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$$\sqrt{1-\zeta^2} = \frac{\sqrt{2}}{2}$$

$$\omega_n = 2 \left(\frac{\sqrt{2}}{2} \right)^{-1}$$

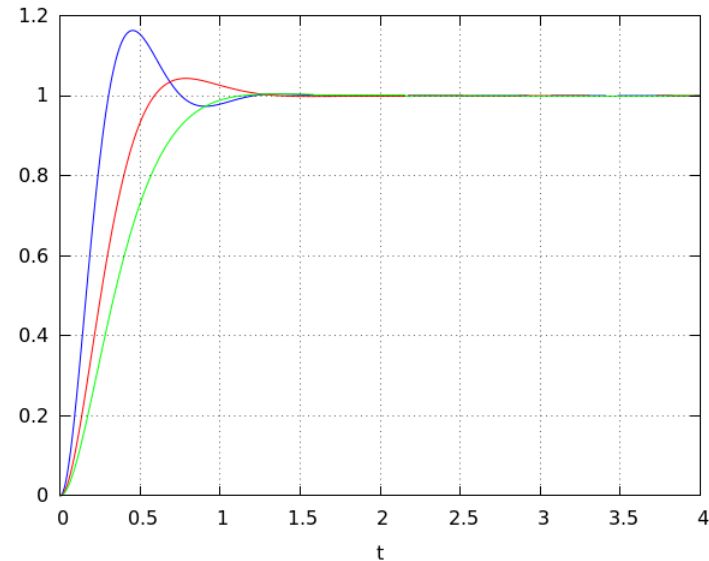
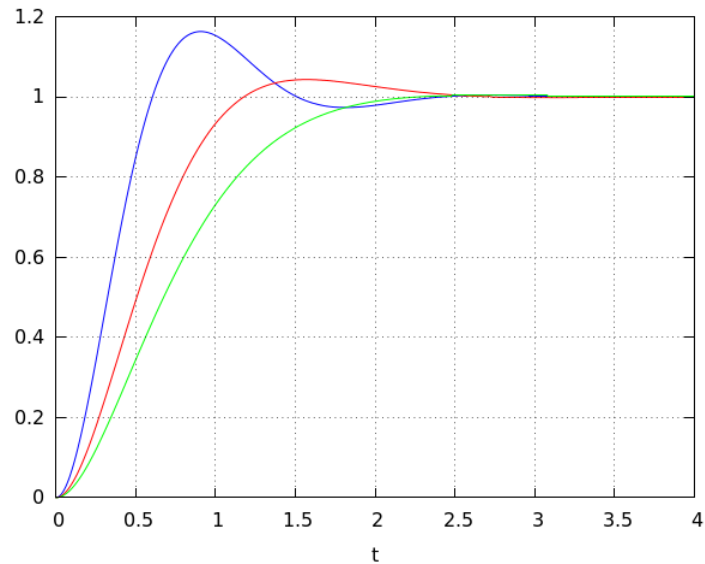
$$\zeta = \frac{\sqrt{3}}{2}$$

$$\sqrt{1-\zeta^2} = \frac{1}{2}$$

$$\omega_n = 2 \left(\frac{1}{2} \right)^{-1}$$

$$\omega_d = \sqrt{1-\zeta^2} \omega_n = 2$$

2nd Order Systems – Underdamping



$$\zeta = \frac{1}{2} \quad \zeta = \frac{\sqrt{2}}{2} \quad \zeta = \frac{\sqrt{3}}{2}$$

$$\omega_n = 2 \left(\frac{1}{2} \right)^{-1} \quad \omega_n = 2 \left(\frac{\sqrt{2}}{2} \right)^{-1} \quad \omega_n = 2 \left(\frac{\sqrt{3}}{2} \right)^{-1}$$

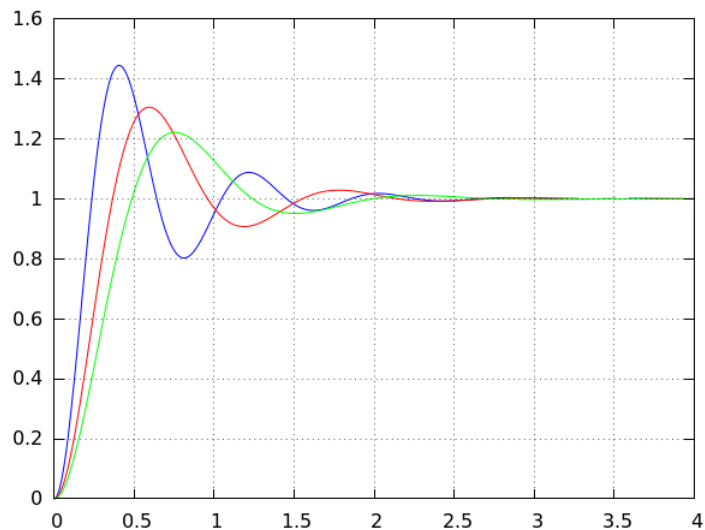
$$\zeta = \frac{1}{2} \quad \zeta = \frac{\sqrt{2}}{2} \quad \zeta = \frac{\sqrt{3}}{2}$$

$$\omega_n = 4 \left(\frac{1}{2} \right)^{-1} \quad \omega_n = 4 \left(\frac{\sqrt{2}}{2} \right)^{-1} \quad \omega_n = 4 \left(\frac{\sqrt{3}}{2} \right)^{-1}$$

$$\sigma_d = \zeta \omega_n = 2$$

$$\sigma_d = \zeta \omega_n = 4$$

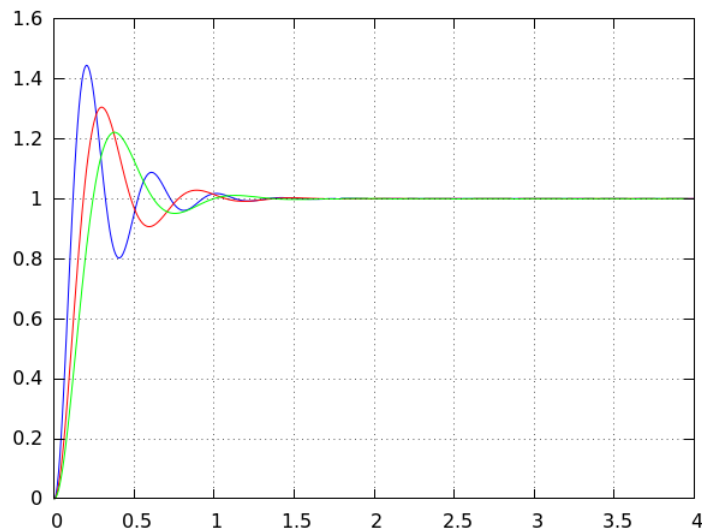
2nd Order Systems – Underdamping



$$\zeta = \frac{1}{4} \quad \zeta = \frac{\sqrt{2}}{4} \quad \zeta = \frac{\sqrt{3}}{4}$$

$$\omega_n = 2\left(\frac{1}{4}\right)^{-1} \quad \omega_n = 2\left(\frac{\sqrt{2}}{4}\right)^{-1} \quad \omega_n = 2\left(\frac{\sqrt{3}}{4}\right)^{-1}$$

$$\sigma_d = \zeta \omega_n = 2$$

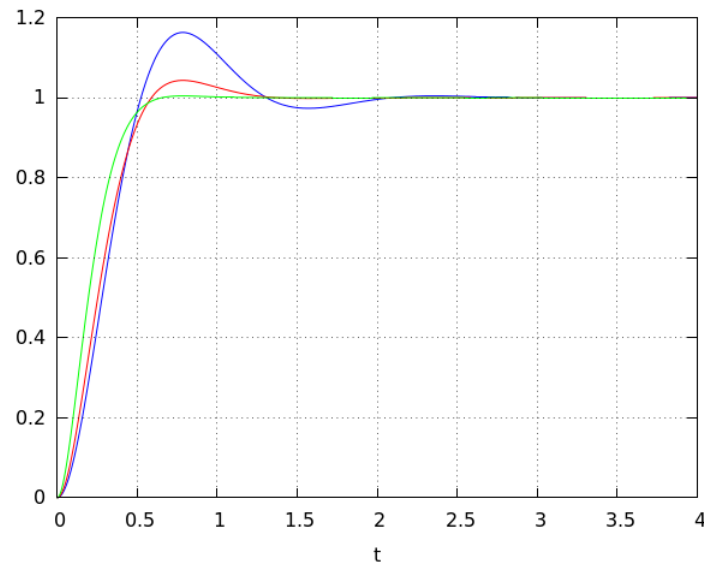
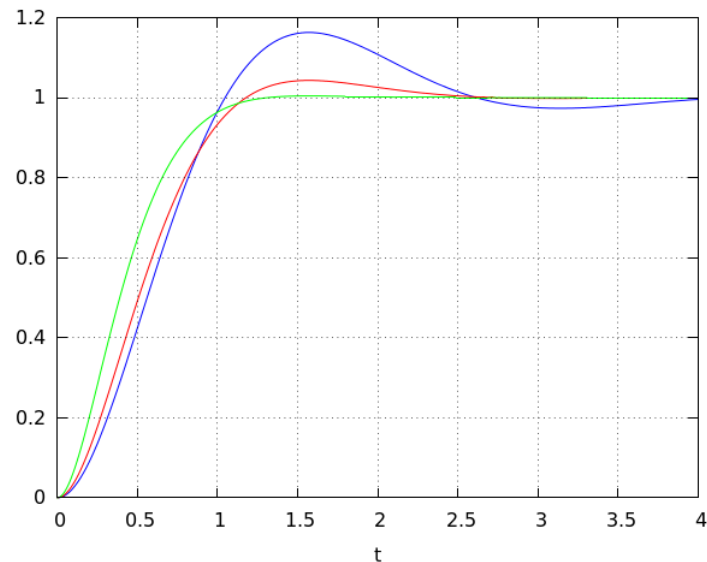


$$\zeta = \frac{1}{4} \quad \zeta = \frac{\sqrt{2}}{4} \quad \zeta = \frac{\sqrt{3}}{4}$$

$$\omega_n = 4\left(\frac{1}{4}\right)^{-1} \quad \omega_n = 4\left(\frac{\sqrt{2}}{4}\right)^{-1} \quad \omega_n = 4\left(\frac{\sqrt{3}}{4}\right)^{-1}$$

$$\sigma_d = \zeta \omega_n = 4$$

2nd Order Systems – Underdamping



$$\zeta = \frac{1}{2}$$

$$\sqrt{1-\zeta^2} = \frac{\sqrt{3}}{2}$$

$$\omega_n = 2 \left(\frac{\sqrt{3}}{2} \right)^{-1}$$

$$\zeta = \frac{\sqrt{2}}{2}$$

$$\sqrt{1-\zeta^2} = \frac{\sqrt{2}}{2}$$

$$\omega_n = 2 \left(\frac{\sqrt{2}}{2} \right)^{-1}$$

$$\zeta = \frac{\sqrt{3}}{2}$$

$$\sqrt{1-\zeta^2} = \frac{1}{2}$$

$$\omega_n = 2 \left(\frac{1}{2} \right)^{-1}$$

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$$\omega_n = 4 \left(\frac{\sqrt{3}}{2} \right)^{-1}$$

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$$\sqrt{1-\zeta^2} = \frac{\sqrt{2}}{2}$$

$$\omega_n = 4 \left(\frac{\sqrt{2}}{2} \right)^{-1}$$

$$\zeta = \frac{\sqrt{3}}{2}$$

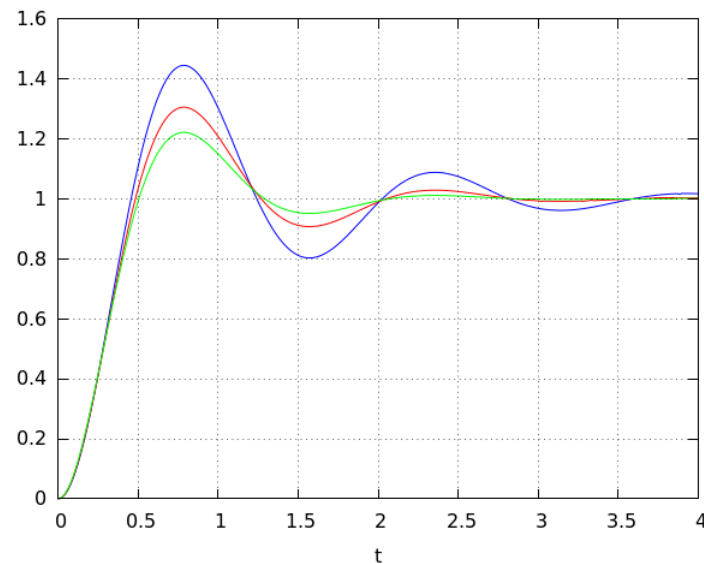
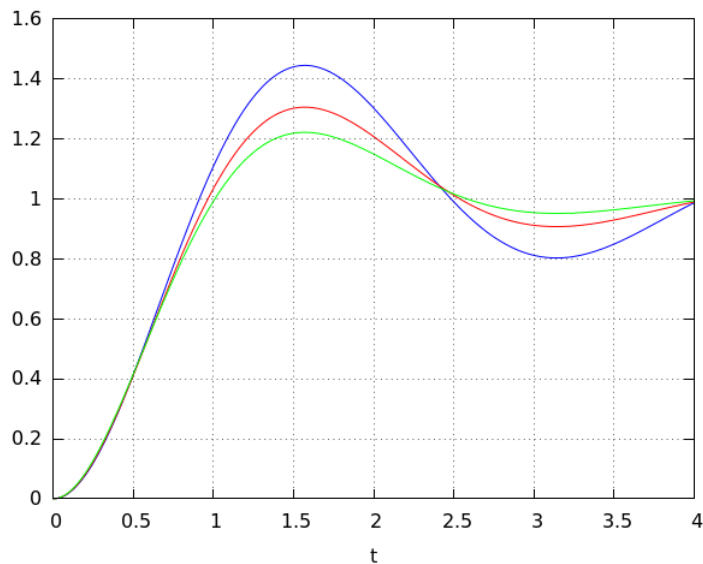
$$\sqrt{1-\zeta^2} = \frac{1}{2}$$

$$\omega_n = 4 \left(\frac{1}{2} \right)^{-1}$$

$$\omega_d = \sqrt{1-\zeta^2} \omega_n = 2$$

$$\omega_d = \sqrt{1-\zeta^2} \omega_n = 4$$

2nd Order Systems – Underdamping



$$\zeta = \frac{1}{4}$$

$$\sqrt{1-\zeta^2} = \frac{\sqrt{15}}{4}$$

$$\omega_n = 2 \left(\frac{\sqrt{15}}{4} \right)^{-1}$$

$$\zeta = \frac{\sqrt{2}}{4}$$

$$\sqrt{1-\zeta^2} = \frac{\sqrt{14}}{4}$$

$$\omega_n = 2 \left(\frac{\sqrt{14}}{4} \right)^{-1}$$

$$\zeta = \frac{\sqrt{3}}{4}$$

$$\sqrt{1-\zeta^2} = \frac{\sqrt{13}}{4}$$

$$\omega_n = 2 \left(\frac{\sqrt{13}}{4} \right)^{-1}$$

$$\omega_d = \sqrt{1-\zeta^2} \omega_n = 2$$

$$\zeta = \frac{1}{4}$$

$$\sqrt{1-\zeta^2} = \frac{\sqrt{15}}{4}$$

$$\omega_n = 4 \left(\frac{\sqrt{15}}{4} \right)^{-1}$$

$$\zeta = \frac{\sqrt{2}}{4}$$

$$\sqrt{1-\zeta^2} = \frac{\sqrt{14}}{4}$$

$$\omega_n = 4 \left(\frac{\sqrt{14}}{4} \right)^{-1}$$

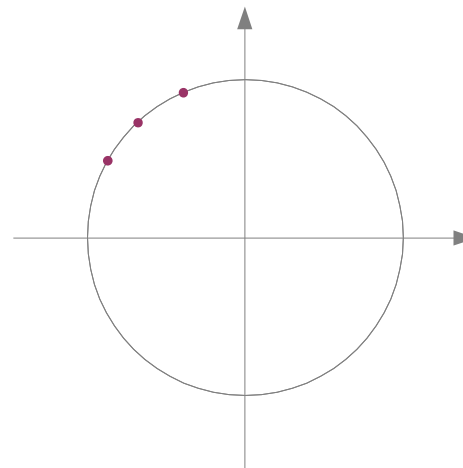
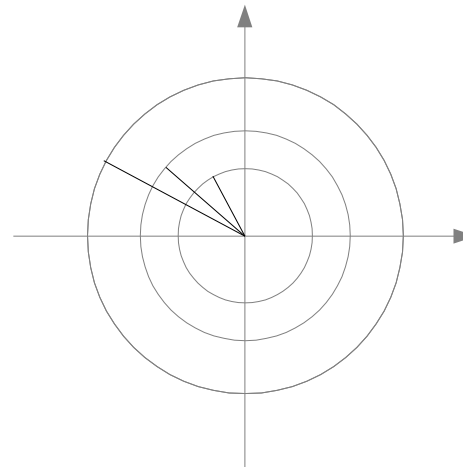
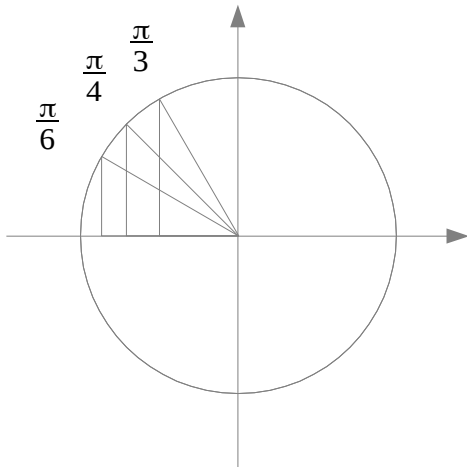
$$\zeta = \frac{\sqrt{3}}{4}$$

$$\sqrt{1-\zeta^2} = \frac{\sqrt{13}}{4}$$

$$\omega_n = 4 \left(\frac{\sqrt{13}}{4} \right)^{-1}$$

$$\omega_d = \sqrt{1-\zeta^2} \omega_n = 4$$

2nd Order Systems – Underdamping



References

- [1] <http://en.wikipedia.org/>
- [2] M.L. Boas, "Mathematical Methods in the Physical Sciences"
- [3] E. Kreyszig, "Advanced Engineering Mathematics"
- [4] D. G. Zill, W. S. Wright, "Advanced Engineering Mathematics"